

AUTOMATIC HANDWASH SYSTEM USING MICROCONTROLLER

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**This report is Submitted in Partial Fulfillment Of Requirement for The Bachelor of
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UNIVERSITI TEKNIKAL MALAYSIA MELAKA
FAKULTI KEJURUTERAAN ELEKTRONIK DAN KEJURUTERAAN KOMPUTER

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Tajuk Projek : AUTOMATIC HANDWASH SYSTEM USING
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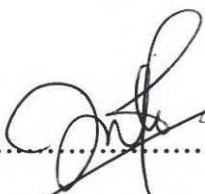
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To my beloved mom and dad

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ABSTRACT

This project is to build and to test an automatic hand wash system. The automatic hand wash system is more advanced than the conventional hand wash and it is designed to improve life by having a more convenient hand wash system. For instance, the water, soap and dryer are integrated all into the system. The machine controls the water, soap and dryer automatically in sequence using the PIC16F877A microcontroller. Water, soap and dryer are controlled based on the programming code that programmed in the PIC16F877A microcontroller. The project is using the infrared sensor to detect the user hand. The level of soap can be detected by sensor. First, the soap sensor detects the level of soap, if the level of soap low, the red lamp will ON and the operation cannot operate. When the green lamp was ON, that means the level of soap is full and the operation can operate. Then if the infrared sensor (hand sensor) detects the user hand, the water flows to wash the hand for 10 seconds. After that, the soap will flow for two seconds and delay for eight seconds. After delay, the water flow out again for 10 seconds and dryer will activate depends on the user hand. If hand sensor cannot detect the user hand, the operation will end.

ABSTRAK

Projek ini bertujuan untuk menghasilkan satu sistem pembasuh tangan automatik. System ini lebih canggih dan maju daripada system basuh tangan biasa dan ia dicipta untuk memudahkan kehidupan manusia dengan menghasilkan satu sistem pembasuh tangan yang mesra pengguna dan mudah digunakan. Air, sabun dan pengering akan dipasang pada sistem ini. Mesin ini mengawal air, sabun dan pengering tangan secara automatik mengikut turutan yang ditetapkan dengan menggunakan mikro pengawalan PIC16F877A. Kawalan air, sabun dan pengering menggunakan mikro pengawalan PIC16F877A adalah berdasarkan kod aturcara program yang diprogramkan ke dalam mikro pengawalan PIC16F877A. Projek ini menggunakan pengesan infra merah untuk mengesan tangan pengguna. Paras sabun pula dikesan oleh pengesan. Pertama sekali, pengesan sabun mengesan paras sabun, jika paras sabun rendah, LED merah akan menyala dan operasi sistem tidak boleh diteruskan. Apabila LED hijau menyala, menunjukkan paras sabun adalah penuh, maka sistem ini boleh berfungsi. Selepas itu, pengesan infra merah mengesan tangan pengguna, air akan keluar selama sepuluh minit dan pengguna boleh basuh tangan. Selepas itu, sabun akan keluar selama 2 saat dan sistem akan berhenti selama 8 saat untuk member peluang pengguna untuk meratakan sabun ke seluruh tangan. Kemudian, air akan keluar semula selama 10 saat dan pengering tangan akan aktif untuk mengeringkan tangan pengguna. Jika pengesan infra merah tidak mengesan tangan pengguna lagi, maka operasi akan tamat.

TABLE OF CONTENT

CHAPTER	TITLE	PAGE
	PROJECT TITLE	i
	DECLARATION	ii
	ACKNOWLEDGEMENT	iv
	ABSTRACT	v
	ABSTRAK	vii
	TABLE OF CONTENTS	viii
	LIST OF TABLES	xi
	LIST OF FIGURES	xii
	LIST OF ABBREVIATIONS	xiii
	LIST OF APPENDIX	xiv
I	INTRODUCTION	1
	1.1 Introduction	1
	1.2 Project Objectives	2
	1.3 Problem Statement	2
	1.4 Scope of Work	2
	1.5 Methodology	3
	1.6 Thesis Outline	4
II	LITERATURE REVIEW	4
	2.1 Introduction of Microcontroller	5
	2.2 Microcontroller	6
	2.1.1 Microchip PIC 16F877A Microcontroller	7
	Features	

2.2	Infrared Sensor	10
2.3	Transformer	11
2.3.1	Basic Principle	11
2.4	Relay	13
2.4.1	Basic Design and Operation	13
2.4.2	Application	15
2.5	Dryer	17
2.6	CAD Tools	18
2.6.1	Proteus VSM 7.0	18
2.6.1.1	Overview	19
2.7...	C-Language	19
III	METHODOLOGY	21
3.1	Project Flow Chart	22
3.2	Selecting Microcontroller	23
3.2.1	Microcontroller PIC16F877A	24
3.2.2	Datasheet of PIC16877A	25
3.2.2	Circuit Simulation Program	21
3.3	Proteus Professional VSM 7.0	26
3.4	Software Development	27
3.5	Etching Process	27
3.6	Soldering Process	28
3.7	Testing Process	29
3.8	Troubleshooting	29
IV	RESULT AND DISCUSSION	31
4.1	Prototype Design	31

	4.2 Circuit Design	33
	4.3 Project Operation	35
	4.4 Discussion	35
V	CONCLUSION AND RECOMMENDATION	37
	5.1 CONCLUSION	37
	5.2 RECOMMENDATION FOR FUTURE WORK	38
	REFERENCES	39
	APPENDICES	40

LIST OF TABLES

NO	TITLE	PAGE
3.1	Key features of PIC16877A	25
3.2	Microcontroller Functional Comparisons	26
3.3	Microcontroller Coverage Comparisons	27

LIST OF FIGURES

NO	TITLE	PAGE
2.1	PIC 16F877A	7
2.2	IR Transmitter and Receiver	10
2.3	Transformer 12V 1A	11
2.4	An Ideal Transformer	12
2.5	SPDT Relay	13
2.6	Dryer	17
2.7	ISIS Professional User Interface	19
3.1	Flowchart of the project process	22
3.2	PIC16F877A	24
3.3	PCB Etching Process	28
3.4	Soldering the PCB	29
4.1	Detail Prototype Design	31
4.2	Plan View	32
4.3	Actual Model of Project	32
4.4	Circuit design for the project	33
4.5	PCB Circuir Layout	34
4.6	Circuit of The Project	34
4.7	The System Flow	35

LIST OF ABBREVIATIONS

PIC	-	Peripheral Interface Controller
RAM	-	Random Access Memory
LED	-	Light Emitting Diode

LIST OF APPENDIX

NO	TITLE	PAGE
A	Data Sheet of PIC16F877A	40
B	Program Source Code	66

CHAPTER I

INTRODUCTION

This chapter is focusing on the introduction of the project, project objectives, problem statements, scope of work, system operation (methodology) and organisation of thesis.

1.1 Introduction

This project is to build and to test an automatic hand wash system. The automatic hand wash system is more advanced than the conventional hand wash and it is designed to improve life by having a more convenient hand wash system. For instance, the water, soap and dryer are integrated all into the system. The machine controls the water, soap and dryer automatically in sequence using the PIC16F877A microcontroller.

1.2 Project Objectives

These are the main purposes of this project:

- (a) Prevent the risk of having contact with micro-bacteria after washing hand as this system helps to wash hand individually. Hence, it is more efficient and more hygienic.
- (b) To improve life by providing more convenient and easier way as the user just need to place his/her hand to wash hands and does not need to turn on the water tap.

1.3 Problem Statement

The automatic handwash system will help to wash a person's hand and in addition would save time. The automatic handwash system is actually a smart system as the people who wish to wash his/her hand don't need to turn on the water pipe.

1.4 Scope of Work

This project is automatic handwash system by using microcontroller (8051). The function of the project is to improve people's life by having a more convenient hand wash system. This machine have three outputs, the outputs are water, soap and dryer to dry the hand. The machine also have two sensors, the sensor is Infrared sensor (Transmitter and Receiver) and the level soap sensor. Infrared sensor is to detect the user hand, if the sensors detect the hand, the operation of machine will operate. The outputs for this machine are put at the same place, where the hand sensor Infrared Transmitter is located. This machine have the sink to flow the water when wash the hand to the ditch.

To complete this project, the soap display is included when the level of soap low, the red lamp is ON, whereas when the level of soap full, the green lamp will ON.

1.5 Methodology

Proteus ISIS 6 Professional is used to design the circuit and simulate it. After completing the circuit assembly and configuration, its time to verify whether the source code compiled is virtually accurate or not. The source code is designed by using PICC Lite Compiler with MPLAB IDE which is widely used by most of the programmers where their project is related to PIC-based system or microcontroller. When the simulation successfully runs, this means that the circuit will be tested and troubleshooting may necessary taken to overcome those circuitry problems. After done without error, the circuit will be packaged and the users may ready to use.

1.6 Thesis Outline

This thesis is a document that delivers the ideas generated and the concept applied. It consists of 5 chapters which are Introduction, Literature Review and Methodology.

Chapter 1 is all about the introduction which contains background, project objectives, problems statements, scope of work and a simple methodology.

Chapter 2 explains about literature review regarding the project. It discusses the researches done upon the related project and data obtain through journals, books, magazines and internet.

Chapter 3 describes the methodology of the project which includes the project flow and its functional block diagram. It also discusses the methods used for the project such as software applied and reasons behind it.

Chapter 4 discusses about the result for this project.

Chapter 5 concluded about the whole project findings for this semester and the recommendation for future work.

CHAPTER II

LITERATURE REVIEW

This chapter is about literature review regarding the project. It discusses about the theory and software that are use in the project.

2.1 Microcontroller [1]

Microcontrollers can be found in any products these days. For example modern washing machine in our house that consists of timer, button and LED contains a microcontroller. All modern cars contain microcontroller. Digital electronics knowledge is essential in order to understand the way microcontroller works. However, with the existing of latest microcontroller like peripheral interface controller (PIC) PIC16F877A from microchip, microcontroller works by writing programming code using C language. Everything becomes so simple by learning C programming and uses it to program the microcontroller. Here are the examples of microcontrollers:

- (a) PIC 16F870
- (b) PIC 16F871
- (c) PIC 16F872

- (d) PIC 16F873A
- (e) PIC 16F874A
- (f) PIC 16F876A
- (g) PIC 16877A

2.2 Microcontroller

A microcontroller is a small computer and it can only perform simple task. Microcontroller consists of:

- (a) Processor that executes programs. Processor execute program digitally. All instruction given to the processor should be in digital form.
- (b) Program Memory to store the program that has been compiled successfully by the programmer.
- (c) RAM (random-access memory to store “variables”).
- (d) IO Port to connect sensor, keypad, LED, Relay and so on.
- (e) Timer to count the time executes some process.

2.2.1 Microchip PIC 16F877A Microcontroller Features

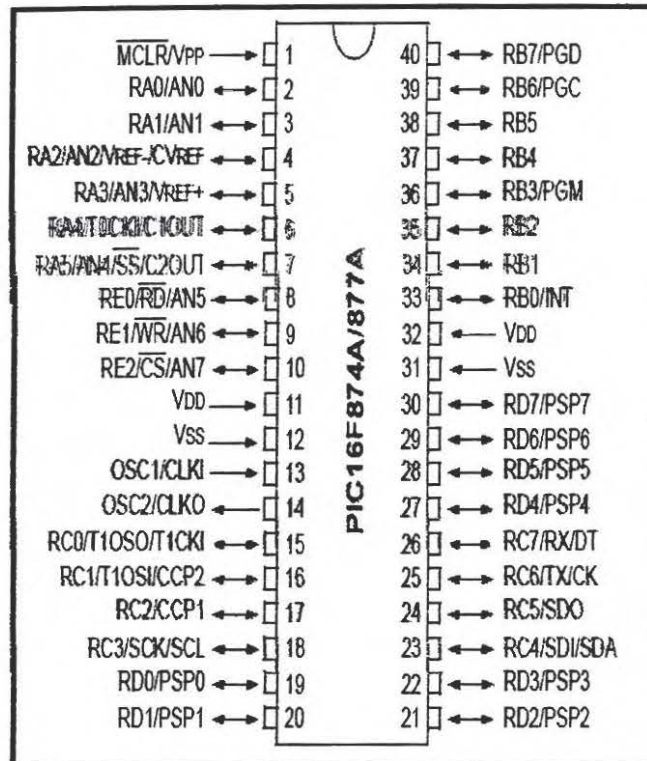


Figure 2.1: PIC 16F877A

High-Performance RISC CPU:

- Lead-free; RoHS-compliant
- Operating speed: 20 Mhz, 200 ns instruction cycle
- Operating voltage: 4.0 – 5.5 V
- Industrial temperature range (-40° to +85°C)
- 15 Interrupt Sources
- 35 single-word instructions
- All single-cycle instructions except for program branches (two-cycle)

Special Microcontroller Features:

- (a) Flash Memory: 14.3 Kbytes (8192 words)
- (b) Data SRAM: 368 bytes
- (c) Data EEPROM: 256 bytes
- (d) Self-reprogrammable under software control
- (e) In-Circuit Serial Programming via two pins (5V)
- (f) Watchdog Timer with on-chip RC oscillator
- (g) Programmable code protection
- (h) Power-saving Sleep mode
- (i) Selectable oscillator options
- (j) In-Circuit Debug via two pins

Peripheral Features:

- (a) 33 I/O pins; 5 I/O ports
- (b) Timer0: 8-bit timer/counter with prescaler
- (c) Timer1: 16-bit timer/counter with prescaler
 - i. Can be incremented during Sleep via external crystal/clock
- (d) Timer2: 16-bit timer/counter with 8-bit period register, prescaler and postscaler
- (e) Two Capture, Compare, PWM modules
 - i. 16-bit Capture input; max resolution 12.5 ns
 - ii. 16-bit Compare; max resolution 200 ns
 - iii. 10-bit PWM
- (f) Synchronous Serial Port with two modes:
 - i. SPI Master
 - ii. I2C Master and Slave
- (g) USART/SCI with 9-bit address detection
- (h) Parallel Slave Port (PSP)

- i. 8 bits wide with external RD, WR and CS controls
- (i) Brown-out detection circuitry for Brown-Out Reset

Analog Features:

- (a) 10-bit, 8-channel A/D Converter
- (b) Brown-Out Reset
- (c) Analog Comparator module
 - i. 2 analog comparators
 - ii. Programmable on-chip voltage reference module
 - iii. Programmable input multiplexing from device inputs and internal VREF
 - iv. Comparator outputs are externally accessible