

UNIVERSITI TEKNIKAL MALAYSIA MELAKA

# DEVELOPMENT OF CIM CONTROL SYSTEM USING PLC

Thesis submitted in accordance with the requirement of the National Technical University College of Malaysia for Degree of Bachelor of Engineering (Honours) Manufacturing (Robotic and Automation)

By

## Hassanul Sazali bin Ahmaddin (B050310088)

Faculty of Manufacturing Engineering September 2007

THE WALAYSIA REPART	UNIVERSI	TI TEKNIK	AL MALAYSIA MELAKA
		BORANG PEN	GESAHAN STATUS TESIS*
JUDUL: _	DEVELO	PMENT OF CIM	I CONTROL SYSTEM USING PLC
- SESI PENC	GAJIAN :2	2002-2007	
Saya	ŀ		ZALI B. AHMADDIN F Besar)
Perpustak		Teknikal Malays	ana/Doktor Falsafah) ini disimpan di sia Melaka (UTeM) dengan syarat-syarat
2. Perpus untuk 3. Perpus antara	stakaan Univers tujuan pengajia	siti Teknikal Ma an sahaja. rkan membuat s	knikal Malaysia Melaka . Iaysia Melaka dibenarkan membuat salinan salinan tesis ini sebagai bahan pertukaran
	SULIT	atau kepen	ngi maklumat yang berdarjah keselamatan tingan Malaysia yang termaktub di dalam IA RASMI 1972)
	TERHAD		ngi maklumat TERHAD yang telah ditentukan sasi/badan di mana penyelidikan dijalankan)
$\overline{\checkmark}$	TIDAK TERHA	D	Disahkan oleh:
(	TANDATANGAN	PENULIS)	(TANDATANGAN PENYELIA)
Alamat POS 1, 1	Tetap: Kampung Baru, S	Seri Gading,	Cop Rasmi:
83300, E	Batu Pahat,		
Johor			
Tarikh:	3 DISEMBE	ER 2007	Tarikh:
lisertasi bagi   * Jika tesis ini	pengajian secara i SULIT atau TERH itakan sekali seba	kerja kursus dan j IAD, sila lampirka b dan tempoh tes	ktor Falsafah dan Sarjana secara penyelidikan, atau penyelidikan, atau Laporan Projek Sarjana Muda (PSM). n surat daripada pihak berkuasa/organisasi berkenaan sis ini perlu dikelaskan sebagai SULIT atau TERHAD. <b>al Malaysia Melaka</b>

# DECLARATION

I hereby, declared this thesis entitled "Development of CIM Control System Using PLC" is the results of my own research except as cited in references.

Signature	:	
Author's Name	:	HASSANUL SAZALI B. AHMADDIN
Date	:	3 DISEMBER 2007



# APPROVAL

This thesis submitted to the senate of UTeM and has been accepted as fulfilment of the requirement for the degree of Bachelor of Manufacturing Engineering (Honours) (Robotic and Automation). The members of the supervisory committee are as follows:

.....

(MR AZRUL AZWAN BIN ABD. RAHMAN) Main supervisor Faculty of Manufacturing Engineering

C Universiti Teknikal Malaysia Melaka

### ABSTRACT

This project is to make an analysis and development of the programmable logic controller (PLC) for the computer integrated manufacturing (CIM) which mean that by making a conveyor line and adding the CIM behaviour. This project also will be combining with other final projects (workstation) and this project (conveyor) will be the main features of the project. Other projects that will involve in this project are the feeder station, automatic colour sorting station, quality inspection station and the assembly station. The method used to make this thesis is by making of the ideology and research of the PLC, conveyor system, and CIM. All the data and input from the literature review chapter are use in the methodology chapter as the source of information and planning. The method to accomplish this project is by implement 5 phase of project methodology which is the planning phase, identification of requirement phase, designing phase, construction phase and lastly the implementation phase. All these phases play an important role in completing this project where if there are some mistake or delays from one of the phase, it can cause the entire project can not be completed or there will be trouble in continuing the next phase. All the data that acquired will be used for the studying the system and the outcome will be a conveyor system that will carried and moved the LCD screen to each workstation.

#### ABSTRAK

Projek ini adalah bertujuan untuk membuat analisis dan pembangunan Kawalan Program Logic (PLC) yang digunakan untuk Pembuatan Terpadu Komputer (CIM) di mana ia akan dilakukan dengan menggunakan pembawa dan kemudian akan ditambah dengan cirri-ciri CIM. Projek ini juga akan digabungkan bersama-sama projek tahun akhir yang lain (stesen kerja). Projek ini akan menjadi sebahagian yang terpenting di dalam menjayakan projek gabungan ini. Projek yang lain dan akan terlibat di dalam projek ini adalah stesen pemberi, stesen pengasingan warna automatic, pengkelasan kualiti dan stesen pemasangan. Kaedah yang digunakan untuk menjayakan tesis ini ialah dengan membuat kajian dan mengambil ideologi-ideologi yang boleh di guna pakai berkenaan dengan PLC, Pembawa, dan juga CIM. Kesemua data yang diperolehi dari ulasan pembacaan di gunakan di dalam bab metodologi sebagai sumber maklumat dan perancangan yang akan dibuat. Kaedah yang digunakan untuk melaksanakan projek ini dengan jayanya ialah dengan mengaplikasikan kesemua 5 fasa metodologi projek iaitu fasa perancangan, fasa mengenalpasti kehendak projek, fasa membentuk, fasa pembinaan dan yang terakhir sekali ialah fasa aplikasi. Kesemua fasa-fasa ini memainkan peranan yang penting didalam melaksanakan projek ini di mana jika terdapat sedikit kesalahan atau kelewatan dari fasa sebelumnya sudah tentu ia akan memberikan tekanan kepada pembikinan projek ini. Ini kerana sudah tentu projek tidak akan dapat dilaksanakan dan diteruskan untuk fasa seterusnya. Kesemua data yang diperoleh akan digunakan di dalam kajian dan pembelajaran system ini. Hasil dari projek ini nanti ialah untuk menghasilkan sebuah mesin pembawa yang akan membawa skrin LCD ke setiap stesen kerja.

# DEDICATION

Special dedication to:

My father, Ahmaddin bin Sarpin; mother, Selasiah Binti Arsal; sister, Norul Wahiddah; brothers, Hassanul Hakimi and Hassanul Amirul Amin who are very concern, understanding, patient and supporting. This project and success will never achieve without all of you.



#### ACKNOWLEDGEMENT

I would like to thanks everyone that have involve in the making of this thesis and to those who have given generous contributions within the period of this thesis development to fulfill the requirement of the Degree of Bachelor of Engineering (Honours) Manufacturing (Robotic and Automation) program.

Here I would like to express my deepest appreciation to my supervisor, Mr. Azrul Azwan Bin Abd. Rahman, whose have given such effort in helping and support to complete this thesis. His constant guidance and support during my thesis writing is invaluable to me. His continuous direction and opinion regarding the flow of the project has a mass contribution to achieve the objective of the project. Furthermore, the guide and help of him on how to make this thesis a more effective reference are followed with my sincere gratitude. And not to forget the college that had provide me with all the studies equipment of this thesis project.

I also would like to thanks my parent, all my friends and lecturers who have done a lot of things and helped me to fulfil and finished this thesis. I also like to send my best of luck to everyone whom have and will take the final year project and hopefully they can complete and finished their project accordingly.

Finally I hope that with this project it can be used to help and improve for human life standard. Not just in the industrial but for everyday life.

Hassanul Sazali Bin Ahmaddin September 2007

## **TABLE OF CONTENTS**

DECLARATION	II
APPROVAL	III
ABSTRACT	IV
ABSTRAK	V
DEDICATION	VI
ACKNOWLEDGEMENT	VII
TABLE OF CONTENTS	VIII
LIST OF FIGURES	XI
LIST OF TABLES	XIV
LIST OF ABBREVIATIONS, SYMBOLS SPECIALIZED NOM	IENCLATURE XV

#### **CHAPTER 1**

INTRODUCTION		1
1.1	Problem Statement	3
1.2	Objectives of the Project	3
1.3	Scope of Project	3
1.4	Project Planning	4

### **CHAPTER 2**

LITERATURE REVIEW	
2.1 Introduction to Computer Integrated Manufacturing (CIM)	6
2.1.1 CIM activities	7
2.1.2 Design of the CIM system	9
2.2 Introduction to Conveyor System	13
2.2.1 Powered Conveyor concept	14

C Universiti Teknikal Malaysia Melaka

2.1.1.1 Po	owered skate wheel, roller and strand conveyor group	14
2.1.1.2 Be	elt conveyor concept	15
2.2.2 Open	ational Philosophy of standard manufacturing conveyor	
syste	em	16
2.2.3 Basi	c Components of conveyor system	16
2.3 Introdu	ction to PLC	26
2.3.1 PLC	compared with other control systems	47
2.3.2 Adva	antages of PLCs	48
2.3.3 Auto	mation and PLC programming	50
2.3.4 PLC	communication	52
2.3.4.1 Si	emens PLC's	52
2.3.5 Siem	nens PLC-SIMATIC S7-200	54
2.4 Program	nming software (STEP 7)	54
2.4.1 Crea	ting Program with Binary Logic	55
2.4.1.1 In	tegrate the hardware and software	56
2.4.1.2 Ba	asic Procedure Using STEP 7	58
2.4.1.3 C	hoosing Ladder Logic, Statement List, or Function Block	
D	iagram	59
2.4.1.4 SI	MATIC STEP-7 Micro/WIN	62

METHODOLOG	GY	64
3.1	Description of the stages.	64
3.1.1	Phase one: Planning	64
3.1.2	Phase two: Identification of requirement	65
3.1.3	Phase three: Designing	65
3.1.4	Phase four: Construction	65
3.1.5	Phase five: Implementation	66
3.2	Experimental Setup	68
3.3	Equipment	68

RESULT		69	
	4.1	DEVELOPMENT	69
	4.2	IMPLEMENTATION	71
	4.3	RESULT	72
	4.3	3.1 Programming	73
		4.3.1.1 Ladder diagram programming	73

### **CHAPTER 5**

DISCUSSION	
5.1 Analysis	78
5.1.1 Hardware Analysis	79
5.1.1.1 Early stage	79
5.1.1.2 Conveyor analysis	81
5.1.2 Program Analysis	90
5.1.2.1 Program task and network analysis.	92
5.2 Program and network discussion	94

### **CHAPTER 6**

CONCLUSION	& RECOMMENDATION	106
6.1	Recommendation and suggestion	106
6.2	Observation of the project	107
6.3	Conclusion	108
REFERENCE		109

#### APPENDICES

112

Х

# LIST OF FIGURES

Figure 2.1: Relations of CIM activities (Rembold 1993)	8
Figure 2.2: CIM processes	9
Figure 2.3: A framework of the design and implementation of CIM (Tariq Masood	ł
and Iqbal Khan, 2004)	11
Figure 2.4: History of CIM (Tariq Masood and Iqbal Khan, 2004)	12
Figure 2.5: Simple conveyor line with control panel (Siemens Energy & Automati	on,
2004).	14
Figure 2.6: A sample picture of a motor (stepper)	19
Figure 2.7: Picture (a) show the 3 phase motor and (b) show the inside of the motor	or
	19
Figure 2.8: Safety device that used in the conveyor and industries	21
Figure 2.9: Showed a flow chart of key decisions in the selection of a safety switch	h22
Figure 2.10: Types of sensor used in conveyor system	23
Figure 2.11: Shows that the comparison between hardwiring circuit with the ladde	r
circuit. Picture (a) is the hardwiring circuit and picture (b) is the lade	ler
circuit.	24
Figure 2.12: Shows the connection of control circuit from the power circuit	25
Figure 2.13: Relationship between PLC and it components	26
Figure 2.14: Show that the Basic PLC operation module block.	27
Figure 2.15: Input/output (I/O) component connected to PLC	28
Figure 2.16: Basic PLC terminal	29
Figure 2.17: Input X1 is energized	29
Figure 2.18: Output Y1 energized and what happen inside the PLC	30
Figure 2.19: Communication between hardware and software	31
Figure 2.20: How the software simulate and energized the hardware	32
Figure 2.21: Pushbutton is unactuated (not being pressed)	34
Figure 2.22: Switch is shown actuated (pressed)	35
Figure 2.23: Input signals can be re-used as many times in the program	36
Figure 2.24: Assign contacts in a PLC program "actuated" by an output (Y) status	. 37

Figure 2.25: Start button is pressed and actuated the output	39
Figure 2.26: When the start button is released	40
Figure 2.27: To stop the motor, must momentarily press the "Stop" pushbutton	41
Figure 2.28: The motor, however, will not start again until the "Start" pushbutto	on is
actuated	42
Figure 2.29: Reversal of logic between the X2 "contact" inside the PLC program	and
the actual "Stop" pushbutton switch	43
Figure 2.30: Emulate the function of a three-input NAND gate	45
Figure 2.31: The lamp remain lit so long as any of the pushbuttons remain	
unactuated (unpressed)	46
Figure 2.32: Connection between the CPU with the input/output and PC	51
Figure 2.33: Programming cable for OPxx display series	52
Figure 2.34: User Communication and Modem Communication System	53
Figure 2.35: Illustration of AND logic function.	55
Figure 2.36: Illustration of OR logic function.	55
Figure 2.37: Illustration of SR function.	56
Figure 2.38: Connection between the STEP 7 software with other output.	57
Figure 2.39: How to create the STEP 7 programming	58
Figure 2.40: Shows the input output terminal module	59
Figure 2.41: Example of ladder logic diagram, statement list and function block	
diagram	61
Figure 2.42: CPU operating cycle.	61
Figure 2.43: The sequence of PLC programming using SIMATIC Step-7 MicroW	'in.
	62
Figure 3.1: Flow chart of method and working procedure	67
Figure 5.1: Specification and type of motor are also attached at the motor cage	84
Figure 5.2: Pneumatic stoppers and proximity sensors	84
Figure 5.3: "U" shape conveyor design	85
Figure 5.4: A pneumatic cylinder as a pusher for the pallet	86
Figure 5.5: Control panel is clear and easy to understand	87
Figure 5.6: Back panel of the control panel door also must properly done	87
Figure 5.7: All pressure is control by pressure regulator	88

Figure 5.8: Pneumatic valve is using electrical solenoid					
Figure 5.9: All wiring must do properly and labelled using cable mark. This is for					
easy reference and checking	89				
Figure 5.10: Only with the supervision of authorised personnel can modified the					
wiring	89				
Figure 5.11: Additional input use for foot switch.	90				



# LIST OF TABLES

Table 1.1: Gantt Chart	4
Table 2.1: Motor Matched sizes rating (Siemens Energy & Automation, 2004)	18
Table 2.2: Utilization Category with IEC description (Siemens Energy &	
Automation, 2004)	19
Table 2.3: Types of sensors, advantages and disadvantages and applications	23
Table 2.4: Programming language and suitable user group with it application	60
Table 4.1: List of Input Output (I./O) address	72
Table 5.1: Basic structure program	94

# LIST OF ABBREVIATIONS, SYMBOLS SPECIALIZED NOMENCLATURE

CAD	-	Computer-aided Design												
CAM	-	Computer-aided Manufacturing												
CAQ	-	Computer-aided Quality Control												
CASA	-	Computer and Automation Systems Association												
CIM	-	Computer Integrated Manufacturing												
CNC	-	Computer Numerical Control												
CPU	-	Central Processing Unit												
CRT	-	Cathode Rays-tube												
DIN	-	Deutsches Institut für Normung (German Institute for												
		Standardization)												
DNC	-	Direct Numerical Control												
EEPROM	-	Electrically Erasable Programmable Read-Only Memory												
FBD	-	Function Block Diagram												
FMS	-	Flexible Manufacturing System												
ft	-	Feet												
I/O	-	Input/output												
IEC	-	International Electrotechnical Commission												
in	-	Inch												
LAD	-	Ladder Logic												
LCD	-	Liquid Crystal Display												
MPI	-	Multi Point Interface												
NC	-	Numerical Control												
NEMA	-	National Electrical Manufacturers Association												
PLC	-	Programmable Logic Controller												
PP&C	-	Production, Planning and Control												

SKU	-	Stock Keeping Unit
SME	-	Society of manufacturing Engineers
SR	-	Set / Reset
STL	-	Statement List
TTY	-	Text Terminal



#### INTRODUCTION

In this chapter it will be discussed about the introduction of this project where it will be focusing on the background of the project. As the title of the chapter, this also includes the basic and overall description of the project. To knows and making a research what the important things to do is by finding it problem and does it have been research before or similar to it. In this chapter also will telling the objectives and the purpose of this project.

This project is actually to make an analysis and development of the programmable logic controller (PLC) for the computer integrated manufacturing (CIM) which mean that by making a conveyor line and adding the (CIM) behaviour. The used of PLC in this project is to control the system and develop an automated system. This project also will be combining with other final projects (workstation) and this project (conveyor) will be the main features of the project. Other projects that will involve in this project are the feeder station, automatic colour sorting station, quality inspection station and the assembly station.

Firstly to make sure this project is running on the right track is by determined and discussing the right product to be made and designing a better way to control or operate the system. When the product has been decided then it can be continued with the processes involved. This is because there are a lot of ways to programming the PLC controller and there is a lot of time needed to familiarise with the interface. The product that will be used to be assembly is the liquid crystal display (LCD) monitor and there are a lot of things to be considered when trying to assembly the LCD. Before starting with the programming with the PLC controller, the main thing needed here is the structural of the conveyor system and it workflows.

Conveyor system is the medium to make the product transferred or moved from one destination to other. This project can only be success if the conveyor workflows are running smoothly and nothing problems is happens. Beside as the transferring device, conveyor also gives the highest impact to the industry. This because the chosen of conveyor like it length, types and application are playing a big role in choosing the conveyor system. The environmental of the working area that the conveyor will be operated is also depend and must be consider as important part in making a conveyor system. For an example, if the conveyor are used in the ice cream factory it need to be made from high quality stainless steel or by using a coated steel to prevent the conveyor from rusting. Component of the conveyor also must be made from non-rusting steel and high quality because it needs to stand the temperature under 0 <sup>o</sup>C. Conveyor system can make the whole system failure to operate accordingly if the conveyor is malfunction or the programming of the conveyor system itself is wrong. This can cause the company to lose a lot of time and production.

When all the problem is defined with the mechanical part are connected and join with the wiring, next is to do the correct programming and studying the sequential or processes that involve. The task in this project is to make the programming of the conveyor system by using PLC as the main programming. The PLC model that will be used in the conveyor is the Siemens PLC. The programming software used is the SIMATIC STEP-7. This software is compatible with the hardware that will be used. And by using this software, all the program that have been created can be download to the PLC by using the suitable cable and communication port from the computer. All the information about the title of this project can be read at the literature review section.

#### **1.1 Problem Statement**

Computer integrated manufacturing is a large area in manufacturing and it combine the use of activities. Even all the machine is controlled individually or synchronously but the main operation to move the product from station to station and from machine to other machine is controlled by the PLC. The main problem now is how to develop a new PLC programming and analyse it movement and operation. This have been the problem because there are a lot of things got to be consider and not just look at the conveyor operation but also all the equipment, tools, controller, it state, cycle time and working procedure. The PLC programming is depends on the conveyor system that will be made as the main system to move the product. So here what the most important is by making the design of the conveyor and know the station is taking places. After all the design is complete and have been analyse then the conveyor working procedure can be made to set the PLC programming as to made it autonomous.

#### **1.2 Objectives of the Project**

The objective of this project is to integrate the conveyor system in CIM by using PLC controller to control the working procedures. Also to develop an integrated conveyor system that will be attached with assembly stations and a system that can be improved for further research.

#### **1.3 Scope of Project**

The scope of this project is to analyse and designing the suitable design of the conveyor to be used in the system and also to develop a PLC as the programming of the conveyor operation.

3

# 1.4 Project Planning

Table 1-1:	Gantt	Chart fo	r PSM 1
1 auto 1-1.	Oanti	Chart 10	

Sco	ope	Weeks													
		1	2	3	4	5	6	7	8	9	10	11	12	13	14
1 2	Understand the title and discuss with the supervisor Finding article and journal of the project														
	title.														
3	Gather all data and article of SIMATEC PLC														
4	Learning the design and all the calculation involve														
5	Learning on electrical circuit and diagram									SEMESTER BREAK					
6	Gathering information on I/O device that will be used									SEMESTH					
7	Learning how to use ladder diagram														
8	Test the software and circuit in simulation														
9	Make draft report of the project														
10	Complete and submit the full report														

Sco	pe	Weeks													
		1	2	3	4	5	6	7	8	9	10	11	12	13	14
1	Assemble the conveyor system														
2	Start to programming the PLC														
3	Test run the system and find out any problem occur														
4	Early detection stage (hardware and software)														
5	Re-check the project planning									SEMESTER BREAK					
6	Troubleshoot the system by making false and error									SEMESTI					
7	Make the program and system more easy														
8	Make the final test run of the project														
9	Make draft report of the project														
10	Complete and submit the full report														

Table 1-2: Gantt Chart for PSM 2

#### LITERATURE REVIEW

#### 2.1 Introduction to Computer Integrated Manufacturing (CIM)

The definition of CIM by the Computer and Automation Systems Association of the Society of manufacturing Engineers (CASA/SME) are CIM is the integration of the total manufacturing enterprise through the use of integrated systems and data communications coupled with new managerial philosophies that improve organizational and personnel efficiency. Analysis and Design Of PLC in CIM is a project that analyse and designing a CIM by using PLC as the programming and it controller. The meaning of CIM if we look at it narrower we could get is the on-line computer control and linking together of all function in a manufacturing plant. CIM and automation have an exclusive bond where automation is to working or operate with the use of machine, electrical drive, machine tools and other by controlled itself without the need of many human resource. The relationship between CIM and automation are like the physical production activities that take place in the factory can be distinguished from the information-processing activities. The heart of CIM is CAD/CAM. Computer-aided design (CAD) and computer-aided manufacturing (CAM) systems are essential to reducing cycle times in the organization. CAD/CAM is a high technology integrating tool between design and manufacturing. CAD techniques make use of group technology to create similar geometries for quick retrieval. Electronic files replace drawing rooms. CAD/CAM integrated systems provide design/drafting, planning and scheduling, and fabrication capabilities. CAD

provides the electronic part images, and CAM provides the facility for toolpath cutters to take on the raw piece.

#### 2.1.1 CIM activities

In the CIM there are some activities that lead to the making of the CIM system itself. The definition of the computer terminology in manufacturing are include the,

- CAD (Computer-aided Design) this activity comprises computer supported design, drafting, and engineering calculation. Since engineering is also involved in product testing, NC program generation, and other computer supported functions, the term CAE (Computer-aided engineering) is often used.
- CAP (Computer-aided planning) this activity is concerned with the computer-aided generation of a technological plan to make the product. The process plan describes the manufacturing processes and sequence to make the part.
- CAM (Computer-aided manufacturing) this activity defines the functions of a computer to control the activities on the manufacturing floor, including direct control of production equipment and management of material, cutting tools, fixtures and maintenance.
- CAQ (Computer-aided quality control) this activity combines all ongoing quality control work of a manufacturing system. In some cases it is termed CAT (Computer-aided testing), which is somewhat restrictive in its meaning.
- CAD/CAM designates the sum of the activities CAD, CAP, CAM, and CAQ.
- PP&C (production, planning and control) this function is the organisational activity of CIM. It is concerned with manufacturing resources planning, materials requirement planning, gross requirement planning, time phasing, order release, and manufacturing control.

All the activities above are an important part in CIM system technologies (figure 2.1) and if there any of the activities fail to perform or take part, it will make the system not working efficiently.