

# FLAME IMAGING USING OPTICAL SENSOR AND LASER

NUR FAIQAH BINTI FAUZI

Laporan ini dikemukakan untuk sebahagian daripada syarat penganugerahan Ijazah Sarjana Muda Kejuruteraan Elektronik (Kejuruteraan Komputer) Dengan Kepujian

Fakulti Kejuruteraan Elektronik dan Kejuruteraan Komputer  
Universiti Teknikal Malaysia Melaka

April 2008



UNIVERSITI TEKNIKAL MALAYSIA MELAKA  
FAKULTI KEJURUTERAAN ELEKTRONIK DAN KEJURUTERAAN KOMPUTER

BORANG PENGESAHAN STATUS LAPORAN  
PROJEK SARJANA MUDA II

Tajuk Projek : FLAME IMAGING USING OPTICAL SENSOR AND LASER

Sesi Pengajian : 2007/2008

Saya NUR FAIQAH BINTI FAUZI  
mengaku membenarkan Laporan Projek Sarjana Muda ini disimpan di Perpustakaan dengan syarat-syarat kegunaan seperti berikut:

1. Laporan adalah hakmilik Universiti Teknikal Malaysia Melaka.
2. Perpustakaan dibenarkan membuat salinan untuk tujuan pengajian sahaja.
3. Perpustakaan dibenarkan membuat salinan laporan ini sebagai bahan pertukaran antara institusi pengajian tinggi.
4. Sila tandakan (  ) :

SULIT\*

(Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia seperti yang termaktub di dalam AKTA RAHSIA RASMI 1972)

TERHAD\*

(Mengandungi maklumat terhad yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan)

√TIDAK TERHAD

Disahkan oleh

  
(TANDATANGAN PENULIS)

  
(COP DAN TANDATANGAN PENYELIA)

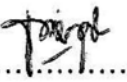
Alamat Tetap: PT 2055,  
JALAN KAMPUNG TELOK  
16300 BACHOK,  
KELANTAN.

**ADIE BIN MOHD KHAFF**  
Pensyarah  
Fakulti Kejuruteraan Elektronik dan Kejuruteraan Komputer (FKEKK),  
Universiti Teknikal Malaysia Melaka (UTeM),  
Karung Berkunci 1200, Hang Tuah Jaya  
Ayer Keroh, 75450 Melaka.

Tarikh: 9<sup>th</sup> May 2008

Tarikh: 9<sup>th</sup> May 2008


“Saya akui laporan ini adalah hasil kerja saya sendiri kecuali ringkasan dan petikan yang tiap-tiap satunya telah saya jelaskan sumbernya.”

Tandatangan :..........

Nama Penulis : Nur Faiqah Binti Fauzi

Tarikh : 9 Mei 2008

“Saya akui bahawa saya telah membaca laporan ini dan pada pandangan saya laporan ini adalah memadai dari segi skop dan kualiti untuk tujuan penganugerahan Ijazah Sarjana Muda Kejuruteraan Elektronik (Kejuruteraan Komputer) Dengan Kepujian.”

Tandatangan :  .....

Nama Penyelia : En. Adie Bin Mohd Khafe

Tarikh : 9 Mei 2008

## ACKNOWLEDGEMENT

First of all, I would like to express my highest gratitude to my supervisor En. Adie Bin Mohd Khafe as mentor and guidance throughout this final year project.

Unforgotten, I am also wanted to say thank you to my friends that directly or hidden involve in the effort to finishing this project.

Lastly, I would like to thank my family for giving me fully support physically and mentally for throughout these four years to assure my study here run smoothly and successfully.

## ABSTRACT

This project describes an investigation of the combination between optical sensor and laser in flame imaging. The aim of this project is to obtain the concentration profile of the flame to be incorporated in laser-based transmission tomography measurement system for the burning process online monitoring. Tomography method being chosen because it can obtain the concentration profile of the flame with the measurement section in the form of a visual image. This project actually can be applied in industrial heat process such as furnace, oven, and brazing. Tomography method is cheaper and safer than the most of the current methods which mostly made use of radioactive methods. Image of the flame are capture using optical sensors that will be digitalized into a form suitable for computer processing of the flow pictures. This project used two orthogonal projections with one laser source. Laser diode was used as the transmitter and photodiode are used as the receiver. The laser source will supply 16 light beams, so the cross-section of the pipe being interrogated by a total of 16 beams. The flame is placed in specific places in the measurement cross-section and voltage output will calculated by the individual sensor. Besides the hardware, this project includes the use of software which is Visual Basic 6.0 program to visualize the concentration profile of the flame.

## ABSTRAK

Projek ini dijalankan adalah untuk mengkaji gabungan penggunaan antara alat pengesanan optikal dan laser pada pengimejan nyalaan api. Tujuan utama projek adalah untuk mendapatkan sisi muka pada penumpuan nyalaan api yang akan digabungkan menggunakan sistem tomografi berdasarkan penghantaran laser bagi mengukur tahap proses nyalaan api secara on-line. Kaedah tomografi dipilih adalah kerana ia boleh mendapatkan penumpuan sisi muka pada nyalaan api dengan seksyen pengukuran dalam bentuk imej visual. Projek ini sebenarnya boleh diaplikasikan dalam industri proses pemanasan seperti dapur leburan, oven dan brazing. Kaedah tomografi lebih murah dan selamat digunakan berbanding dengan kaedah yang digunakan sekarang iaitu melalui kaedah radioactive. Imej pada nyalaan api diambil menggunakan optikal laser dan akan di digitalized dalam bentuk yang sesuai untuk diproses oleh computer dalam bentuk aliran gambar. Projek ini akan menggunakan pandangan unjuran dua orthogonal dengan satu sumber laser. Laser diod akan digunakan sebagai pemancar manakala photodiode digunakan sebagai penerima pancaran signal. Sumber laser tersebut akan melancarkan 16 sumber laser dan akan mengenai photodiode yang diletakkan merentasi paip tersebut. Nyalaan api diletakkan pada tengah paip tersebut untuk pengukuran imej keratan rentas dan pengeluaran voltan akan dikira oleh setiap pengesan. Selain dari litar yang digunakan, projek ini juga menggunakan program visual basic 6.0 untuk memaparkan keputusan pada penumpuan nyalaan api tersebut.

## TABLE OF CONTENTS

CHAPTER	TITLE	PAGE
	<b>DECLARATION</b>	ii
	<b>ACKNOWLEDGEMENT</b>	iv
	<b>ABSTRACT</b>	v
	<b>ABSTRAK</b>	vi
	<b>TABLE OF CONTENTS</b>	vii
	<b>LIST OF TABLES</b>	ix
	<b>LIST OF FIGURES</b>	x
	<b>LIST OF SYMBOLS</b>	xii
	<b>LIST OF APPENDICES</b>	xiii
<b>I</b>	<b>INTRODUCTION</b>	
	1.1 Objectives of the Project	3
	1.2 Problem Statement	3
	1.3 Project Scope	4
	1.4 Project Methodology	5
<b>II</b>	<b>LITERATURE REVIEW</b>	
	2.1 Basic Tomographic System	8
	2.2 Sensor Type	13
	2.2.1 Electrical Capacitance Tomography	14
	2.2.2 Ultrasonic Tomography	15
	2.2.3 Gamma Ray Tomography	17
	2.2.4 Optical Tomography	18



2.3	Basic Principles of Laser	19
	2.3.1 Difficulties of Laser Beam Deliveries	21
2.4	Laser Diode: Brief History	21
	2.4.1 Semiconductor Laser Diode	22
2.5	The Photodiode	25
	2.5.1 Photodiode Responsivity	26
	2.5.2 PIN Photodiode	27
2.6	The Proposed Optical Tomography System	27
<b>III</b>	<b>PROJECT METHODOLOGY</b>	
3.1	Literature Survey	29
	3.1.1 Process tomography	29
	3.1.2 Sensing Techniques	30
	3.1.3 Image Reconstruction Algorithms	32
3.2	Design of Instrumentation System	36
	3.2.1 Sensor's Fixture	36
	3.2.2 Projection Modeling	37
	3.2.3 Sensor Modeling	39
	3.2.4 Transmitter and Receiver Selection	40
	3.2.5 Signal Conditioning Circuit	41
	3.2.6 Emitter and Receiver Circuit	42
3.3	Data Acquisition System	43
3.4	Data Selection	47
3.5	Software Development	48
<b>IV</b>	<b>RESULT ANALYSIS AND DISCUSSION</b>	
4.1	Result	50
	4.1.1 Concentration Profile and Color Scale	50
	4.1.2 Result of Image Reconstruction	53
4.2	Discussion	54

<b>V</b>	<b>CONCLUSION</b>	
	5.1 Conclusion	56
	5.2 Suggestions for Future Works	57

**LIST OF TABLES**

<b>NO</b>	<b>TITLE</b>	<b>PAGE</b>
2.1	Sensor Grouping	12

## LIST OF FIGURES

<b>NO</b>	<b>TITLE</b>	<b>PAGE</b>
1.1	Flow Chart for Project Methodology	5
2.1	Two Orthogonal Projection	8
2.2	Two Rectilinear Projections	8
2.3	Three Rectilinear Projection	9
2.4	Combination of Orthogonal and Rectilinear Projection	9
2.5	Three Fan Beam Projection	10
2.6	Four Fan Beam Projection	10
2.7	Basic Structure of Semiconductor Laser	22
2.8	Spectral Wave Sensitivity for BPX 65 PIN Photodiode	25
3.1	Image Reconstruction	29
3.2	Position of Transmitter and Receiver	30
3.3	Diagram of Jig for Laser Based Tomography	34
3.4	Photo of Jig for Laser Based Tomography	35
3.5	The Two Dimensional Function $F(x,y)$ Is Arranged Into Two Orthogonal Projection	36
3.6	Corresponding Functional Block for Optical Tomography	39
3.7	Receiver Circuit for Optical Tomography System	40
3.8	Photo of Receiver Circuit for Laser Based Tomography	40
3.9	Block Diagram of Data Acquisition System	44
3.10	Calibration of DAS Card	45
3.11	Calibration of DAS Card	45
3.12	Calibration of DAS Card	46

3.13	Calibration of DAS Card	46
3.14	Analog Input Data of the Heat Distribution	47
3.15	Plotted Graph of the Value of Heat Distribution	48
3.16	Flowchart for Concentration Profile Image Reconstruction	49
4.1	Front Form Used To Start Concentration Profile	51
4.2	GUI to Display Concentration Profile	51
4.3	The Color Scale Used To Convert the Concentration Matrix to Image	52
4.4	Concentration Profile during Half Open Valve	53
4.5	Concentration Profile during Full Open Valve	54

## LIST OF SYMBOLS

$I$	=	Transmitted Intensity ( $Wm^{-2}$ )
$I_0$	=	Initial Incident Intensity ( $Wm^{-2}$ )
$N$	=	Thickness Of The Absorbing Material (m)
$\mu$	=	Linear Absorption Coefficient ( $m^{-2}$ )
$V_{LBP}(x, y)$	=	Voltage distribution obtained using LBP algorithm (concentration profile in unit volt) an $n \times m$ matrix where n equals to dimension of sensitivity matrix.
$S_{Rx, Tx}$	=	Signal loss amplitude of receiver Rx-th for projection Tx-th in unit of volt.
$\overline{M}_{Rx, Tx}(x, y)$	=	The normalized sensitivity matrices for the view of Tx–Rx
$P\theta$	=	Projection Angle
$x'$	=	Detector Position In X-Plane
$f(x, y)$	=	Coordinate Of Real Object
$N$	=	Total Number Of Receiver
$M$	=	Total Number Of Projection
$D_{Rx, Tx}$	=	Width Of The Light Beam Of Tx-Th Emitter To Rx-Th Receiver
$\alpha_{Rx, Tx}$	=	Angle Between The Tx-Th Emitter To Rx-Th Receiver
$m_{Rx, Tx}$	=	Slope Of The Line Node Tx-Th Emitter To Rx-Th Receiver
$d$	=	Gap Between The Emitter And Receiver

$V(x, y)$  = The Concentration Profile Obtains With Resolution Of  $n \times n$  Pixels For Modeled Image Or Reconstruction Image

$pixels_{sum}$  = The Total Of Pixels Occupied By Any Light Beam. Determined By Counting The Number Of Elements In Total Sensitivity Matrix That Possessed Non-Zero Value.

**LIST OF APPENDICES**

<b>APPENDIX</b>	<b>TITLE</b>	<b>PAGE</b>
<b>A</b>	<b>BPX 65 Photodiode Datasheet</b>	<b>58-62</b>
<b>B</b>	<b>TL084 IC Datasheet</b>	<b>63-91</b>
<b>C</b>	<b>Layout of PCB Circuit</b>	<b>92</b>
<b>D</b>	<b>Source Code Program</b>	<b>93-97</b>
<b>E</b>	<b>Data Collection</b>	<b>98-104</b>



## CHAPTER I

### INTRODUCTION

As defined in one encyclopedia (Helicon 1991), the word “tomography” is derived from the Greek language which *tomo* means “slice” and graph means “picture”. In another word, tomography is a method of viewing the plane section image of an object.

Process tomography provides several real time methods of viewing the cross-section of a process to provide information relating to the material distribution. This involves by taking numerous measurement from sensors which placed around the section of the process being investigated and processing the data to reconstruct an image. The process involves the use of non-invasive sensors to acquire vital information in order to produce two or three-dimensional images of the dynamic internal characteristic of process system. Information on the flow regime, vector velocity, and concentration distribution may be determined from the images. Such information can assist in the design of process equipment, verification of existing computational modeling and simulation techniques, or to assist in process control and monitoring.

Process tomography refers to any tomographic method used to measure the internal state of a chemical process (e.g. material distribution in a reactor, multiphase flow fields in piping or concentration uniformity in mixers). By tomographic techniques can measure quantities such as the flow rate or solid concentration of material flowing through a pipeline and the distribution of material inside a chemical reactors or a mixer. This type of information is not usually obtainable with the sensor traditionally used by engineer, therefore these techniques gives a better understanding of the flow of material through the plant and the data can be used to design better process equipment and to control certain processes to maximize yield and quality.

From an engineering perspective, tomographic technology involves the acquisition of measurement signals from sensors located on the periphery of an object. This reveals information on the nature and distribution of components within the sensing zone. Most tomographic techniques are concerned with abstracting information to form a cross sectional image.

Basically, in tomography system several sensors are installed around the pipe or vessel to be imaged. The sensor output signal depends on the position of the component boundaries with their sensing zones. A computer is used to reconstruct a tomographic image of the cross-section being interrogated by the sensor. Real times image can be obtain which measure the dynamic evolution of the parameter being detect at the sensor.

## 1.1 Objectives of the Project

This project aims to investigate the use of tomographic measurement for online monitoring of two-component especially providing cross sectional image of flame concentration. The specific objectives of this project are:

1. To investigate the use of laser based tomography in measurement of concentration profile of flame.
2. To implement the using of laser diode as the transmitter or source.
3. To utilize photodiode as a detector.
4. To develop cross sectional image using suitable software.
5. To measure the concentration profile and visualize an image reconstruction of flame using Visual Basic 6.0

## 1.2. Problem Statement

This project actually can be applied in industrial heat process such as furnace, oven, and brazing. This method is cheaper and safer than the most of the current methods which mostly made use of radioactive methods. In industrial section, we usually using transducer to detect and sense heat process. A transducer is a device, usually electrical, electronic, electro-mechanical, electromagnetic, photonic, or photovoltaic that converts one type of energy to another for various purposes including measurement or information transfer. Transducers that we usually used in heat industry are from thermoelectric type which is RTD (Resistance Temperature Detector), thermocouple, thermistor and peltier cooler. We usually used thermistor and thermocouple to detect and sense heat in industrial section.

In electronics, thermocouples are a widely used type of temperature sensor and can also be used as a means to convert thermal potential difference into electric potential difference. They are cheap and interchangeable, have standard connectors, and can measure a wide range of temperatures. While a thermistor is a type of

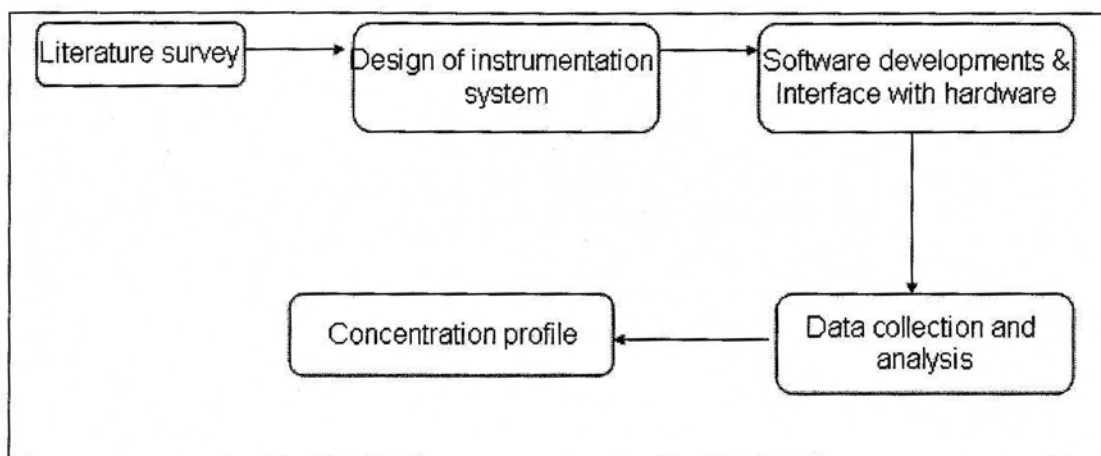
resistor used to measure temperature changes, relying on the change in its resistance with changing temperature. But, usually conventional transducer which is thermocouple and thermistor cannot detect and sense heat at specific point where the sensor is located. The case of uniformity of heat distribution makes the conventional transducer cannot detect. This type of information not usually obtained with the traditionally sensor that always been used before.

### **1.3. Project Scope**

1. The Sensor Fixture And Selection Of Sensors
  - i. To investigate the suitable mounting method of transmitter and sensor
  - ii. To investigate the suitable type of optical sensor.
2. Signal Conditioning Circuit
  - i. To design the receiver circuit with an appropriate gain and applying suitable signal processing technique.
3. Designing Printed Circuit Board (PCB)
4. Data Acquisition System Design
  - i. To use a data acquisition system for signal or data that been obtained from sensor.
5. Software Development
  - i. Design graphic user interface (GUI) using suitable software for performing online image reconstruction.
6. Thesis writing

#### 1.4. Project Methodology

This part is the explanation for the procedures and methods that will be used to complete the project. It will explain step by step the process build the project until it finished. The first step until the last step is literature survey, design of instrumentation system, software development and interface with hardware, data collection and analysis, concentration profile and lastly completing thesis writing. The figure below shows procedure and steps that will be used to achieve the objectives of this project.



**Figure 1.1: Flow Chart for Project Methodology**

1. Literature Survey
  - i. Process tomography
  - ii. Sensing techniques
  - iii. Image reconstruction algorithm
2. Design Of Instrumentation System
  - i. Sensor fixture
  - ii. Transmitter and receiver
  - iii. Signal condition
3. Software development and interfacing with hardware
  - i. Software development
  - ii. Interfacing DAS card with measurement system

4. Data collection and analysis
  - i. Process measurement
  - ii. Data collection and analysis
5. Concentration profile
  - i. Tomographic image reconstruction

## **CHAPTER II**

### **LITERATURE REVIEW**

Process tomography involves the use of non-invasive sensors to acquire vital information in order to produce two or three dimensional images of the dynamic internal characteristic of process systems. Information can assist in the design of process systems. Information can assist in the design process equipment, verification of existing computational modeling and simulation techniques, or to control and monitoring.

At present, the usual objectives of using tomographic system is to obtain concentration profile of moving components of interest within the measurement section in the form of a visual image, which is updated at a refreshment rate dependent upon the process being investigated.

Basically, in tomography system, several sensors are installed around the pipe to be imaged. The sensor output signals depend on the position of the component boundaries within their sensing zone. A computer is used to reconstruct a tomographic image of the cross section being interrogated by the sensors. Real time images can be obtained which measure the dynamic evolution of the parameters being detect at the sensor. And all the required for a practical system is an imaged

updated frequently enough for the smallest relevant feature of the flow to be observe.

## 2.1 Basic Tomographic System

Tomographic techniques vary widely in their instrumentation and applications, all of them can be characterized by a common two step approach to the imaging process; firstly gather projection data based on some physical sensing mechanism, then reconstruct a cross sectional image from the projections. The term projection has a meaning tomography which a projection can be visualize as type of radiography of the process vessel.

In tomography, many projections are needed to reconstruct the interior volume or cross section of an object. Projection actually can be referred as sensor arrangement. There are several types of projection that can be applied in to measure flame concentration, which are;

1. orthogonal projection
  - i. two orthogonal projection (figure 2.1)
  - ii. two rectilinear projection (figure 2.2)
  - iii. three rectilinear projection (figure 2.3)
  - iv. a combination of two orthogonal and two rectilinear projections (figure 2.4)
2. Fan beam projection.
  - i. Three fan beam projection (figure 2.5)
  - ii. Four fan beam projection (figure 2.6)