



UNIVERSITI TEKNIKAL MALAYSIA MELAKA

**AUTOMATED FACTORY SAFETY CONTROL SYSTEM USING
PLC**

This report submitted in accordance with requirement of the Universiti Teknikal Malaysia Melaka (UTeM) for the Bachelor Degree of Manufacturing Engineering (Robotic and Automation) with Honours.

by

MOHD SYUKRI BIN MOHAMED

FACULTY OF MANUFACTURING ENGINEERING

2009

DECLARATION

I hereby, declared this report entitled “Automated Factory Safety Control System Using PLC” is the results of own my research except as cited in references.

Signature:

Author's Name: Mohd Syukri Bin Mohamed

Date: 17th April 2009

APPROVAL

This report is submitted to the Faculty of Manufacturing Engineering of UTeM as a partial fulfillment of the requirements for the degree of Bachelor of Manufacturing Engineering (Robotic and Automation) with Honours. The member of supervisor committee is as follow:

(Signature of Supervisor)

.....

(Official Stamp of Supervisor)

ABSTRAK

Kajian ini dilakukan untuk mencari dan mengenalpasti permasalahan yang di hadapi di dalam industri. Pendekatan ini dilakukan bagi menambahbaik sistem yang ada sekarang dengan menggunakan sistem yang ringkas dan berkesan. 'Automated Factory Safety Control' di lengkapi dengan PLC (Pengawal logik aturcara) yang memainkan peranan sebagai perantara antara penderia dengan paparan LED. Sistem ini beroperasi mengawal operasi mesin, mengawal suhu di dalam kilang, mengenalpasti kerosakkan dalam sistem kawalan elektrik dan lain lain lagi. Paparan LED digunakan bagi mengenal pasti kerosakkan yang di alami. Sistem ini dapat membantu mengurangkan masa langkah mesin, mengurangkan kos baik pulih mesin dan membantu memudahkan kerja kerja baik pulih sesuatu masalah yang di hadapi.

ABSTRACT

This paperwork describe about a problem faces in industrial by improving an existed system with effective and simple . PLC (programmable logic controller) has been used acts as a interface between sensor and LED display for this automated factory control. Operation of this system are control machine, control temperature, and detect fault in electrical control system. This system can be help to reduce a downtime and cost machine maintenance,and a gives a good product.

DEDICATION

For my supervisor, lecturers, family and friends

ACKNOWLEDGEMENT

I wish to thank my supervisor, En. Shariman Bin Abdullah for his valuable advice, constructive criticisms, stimulating discussions and valuable suggestions during the preparation of this project report. I would like to express my thanks to all colleagues who are always ready to give their helping hands. Last but not least, no words can be used to express my deepest gratitude to my parent and family for their encouragement and love, which are forever indebted.

Thank you very much.

TABLE OF CONTENTS

Abstract	i
Abstrak	ii
Dedication	iii
Acknowledgement	iv
Table of Content	v
List of Figures	vii
List of Table	xii
1. INTRODUCTION	
1.1 Project Background	1
1.2 Objective	2
1.3 Scope Of Work	2
1.4 Problem Statement	3
2. LITERATURES REVIEW	
2.1 Introduction	4
2.2 Smart Factory	6
2.2.1 Argus Titan System	6
2.2.2 Smart (Intelligent) System	9
2.3 Monitoring System	11
2.3.1 The performance of the monitoring system	12
2.3.2 Push Button Panel PP7 and PP17	14
2.3.3 Text Display	15
2.3.4 Graphic Display OP1 70B and OP2 70	16
2.3.5 Touch Panel TP1 70 and TP2 70	16
2.3.6 Multi Panel MP1 70B and MP3 70B	17

2.4 Fault Detection	18
2.4.1 Fire Detection System	18
2.4.1.1 Smoke Detection	18
2.4.1.2 Heat Detectors	20
2.4.1.3 Flame Detectors	21
2.4.2 Temperature Sensor	21
2.4.2.1 Type Of Temperature Sensor	22
2.4.2.2 Classes Of Temperature Sensor	23
2.4.2.3 Analog Plus Temperature Sensor	24
2.4.2.4 Temperature Control System Using LM 35	25
2.5 Controller System	27
2.5.1 PLC (Programmable Logic Controller)	27
2.5.1.1 Ladder Logic	32
2.5.1.2 Programming	33
2.5.1.3 PLC Connection	36
2.5.1.4 Ladder Logic Inputs	37
2.5.1.5 Ladder Logic Outputs	38
2.5.2 PIC (Programmable Integrated Circuit)	39
2.5.2.1 PIC Instruction Structure	40
2.6 Summary	42
3. METHODOLOGY	
3.1 Introduction	43
3.2 Problem Statement Identified	44
3.3 Project Planning	44
3.3.1 Gantt Chart	45
3.4 Research About Project	46
3.5 Design Factory Model	46
3.6 PLC Ladder Diagram	47
3.7 LED Display Panel	48

3.8 Analyzing	49
3.8.1 Flow Chart	50
3.9 Improvement	51
4. DESIGN AND DEVELOPMENT	
4.0 Introduction	52
4.1 Model Design	52
4.2 Electrical and Electronic Construction	55
4.2.1 LED Wiring	56
4.2.2 Relay Wiring	57
4.2.3 DC Motor Speed Controller	59
4.2.4 Photoelectric Sensor	61
4.2.5 Servo Controller	63
4.2.6 Temperature Controller	65
4.2.7 Smoke Detection	68
4.3 Summary	71
5. RESULT AND DISCUSSION	
5.0 Introduction	72
5.1 Result	72
5.1.1 Electrical Diagram	73
5.1.2 Programming PLC	74
5.1.3 Programming PIC	83
5.2 Discussion	87
5.3 Summary	87
6. CONCLUSION AND FURTHER WORK	
6.0 Introduction	88
6.1 Summary of Project	88
6.2 Conclusion	89
6.3 Future Work	89

REFERENCES

90

APPENDIX

- A- Ladder Diagram of PLC
- B- Programming PIC
- C- Figure of automated factory control system using PLC.

LIST OF FIGURES

2.1	Simple Automated Cell	5
2.2	Relationship Block Diagram For Argus System	7
2.3	Hard wiring require a large number of control wires to interconnect a system	9
2.4	A smart device uses a communication protocol that allows individual device to communicate with each other	10
2.5	Monitor may be added to protect a system from many different type problem	13
2.6	Series Device	14
2.7	Push Button Panel	15
2.8	Front View Of The TD 17 Text Display	15
2.9	Front View Of The OP170B and OP270 Graphics Display	16
2.10	Front View Of The TP170 and TP270	17
2.11	Front View Of The MP270B and MP370 Multi Panel	17
2.12	Ionization Detector	19
2.13	Photoelectric Detector	20
2.14	Heat Detector	20
2.15	Sensor and IC Manufacturers	23
2.16	ICs that signal when a temperature has been exceeded Are well suited for over/under temperature alarms And simple on/off fan control	25

2.17	Block Diagram Of Temperature Sensor Using LM32	25
2.18	Power Transistor	26
2.19	Sensor LM 35	26
2.20	The block diagram of the typical component that make up a PLC	27
2.21	SLC processor module (CPU)	28
2.22	a) Status of real world , b) The memory control one output	29
2.23	Various racks sizes	30
2.24	Modules, racks, and a rack filled with modules	30
2.25	PLC direct I/O wiring	31
2.26	Simple Relay layouts and Schematic	32
2.27	A simple relay controller	33
2.28	An Example of a Mnemonic Program and Equivalent Ladder Logic	34
2.29	An Example of a Sequential Function Chart	35
2.30	An Example of a Structured Text Program	36
2.31	The Separation of Controller and Process	36
2.32	The Scan Cycle of a PLC	37
2.33	Ladder Logic Inputs	38
2.34	Ladder Logic Outputs	39
2.35	A typical Microcontroller system	40
2.36	PIC 16C84 and Oscillator Circuit	41
3.0	Project Schedule	45
3.1	Design Factory Model	46
3.2	PLC Controller	47
3.3	LED display panel	48
3.4	Flow Chart	50
4.1	Top view of indication system and factory model with dimension	53
4.2	Side view of design indication system and factory model.	53
4.3	Font view of design indication system	54
4.4	Three dimension (3D) for all model design	54

4.5	Design Factory Model	55
4.6	Circuit connection LED with Resistor.	56
4.7	Complete the LED connection.	57
4.8	Symbol for relay	57
4.9	Connection diagram relay	58
4.10	Connection Relay	58
4.11	DC motor speed controller.	59
4.12	motor speed controller.	60
4.13	LDR circuit.	61
4.14	Control circuit extension of solar and LDR	62
4.15	Complete system (solar and LDR)	62
4.16	LED indication of solar system	63
4.17	Servo Motor	63
4.18	Circuit controller	64
4.19	Placement of servo motor	64
4.20	LED indicator	65
4.21	Temperature controller	65
4.22	Placement of blower fan and sensor LM 35.	67
4.23	Blower Fan	67
4.24	LCD Display	68
4.25	Temperature control circuit	68
4.26	Schematic of Smoke detection.	69
4.27	Smoke detection	69
4.28	Smoke sensor	70
4.29	LED indication for smoke system	70
5.1	Circuit Connection	73
5.2	Setup	74
5.3	RS232 Cable and Serial Cable	75
5.4	Operating Mode to Run	75
5.5	Ladder Diagram for Temperature system	78

5.6	Ladder Diagram of Electrical System.	79
5.7	Ladder diagram of solar system.	80
5.8	Ladder diagram of machine status.	81
5.9	Ladder diagram for door lock system	82
5.10	Ladder diagram of master control.	83
5.11	Temperature control system using LM 35.	84
5.12	Design the temperature control circuit.	85
5.13	PIC Command.	86

LIST OF TABLE

4.1	List the DC motor speed controller component.	59
4.2	Component description	60
4.3	List of component	66
5.1	Assigned Input Address and Address Description.	76
5.2	Assigned Output Address and Address Description	77

CHAPTER 1

INTRODUCTION

1.1 Project Background

Safety systems provide the safety for humans, machines and environment. They are used to prevent accidents and damage resulting from a fault or malfunction. The safety controllers (Safety Integrated) detect faults autonomously and immediately change into or remain in a safe mode when a fault occurs. They are optimized for use in production engineering and provide air-tight safety for all its many facets.

All industry must include safety protection device to protect the machine, electrical equipment, operator and to produce the quality of product. All system are required to have a minimum amount of protection to protect personnel and property. Most system required more than the required minimum amount of protection in order to minimize equipment damage and reduce maintenance downtime.

In this project, PLCs have been used to reduce costs and increase productivity. They are now being incorporated for safety aspects. Safety PLCs are easier to repair and use while also reducing false alarms

By acting as a automated factory safety control system, when a problem and error occurs in the system of factory, number, light indicator or words are displayed on a digital readout attached to the equipment or LED display panel.

1.2 Objective

The main objective of this project is to develop a automated factory safety control system using PLC. This system can be detect fault of the all system and show in LED fault indicator. All of the system controlled by PLC (Programmable Logic Controller) and PIC (Programmable Integrated circuit). Additional objective of this projects are :

- (a) To develop a fully functional controller that can be used to detect the problem in the system.
- (b) To design and develop a program PLC and PIC controller.
- (c) To reduce course of maintenance in industry
- (d) To design a LED display panel

1.3 Scope Of Work

The scope should be identified and planned to achieve the objective of the project successfully on the time, first the scope for this project is to design and develop an electrical circuit to control input and output from PLC (Programmable Logic Controller). Second scope is to design a program in PLC system for control all or the system, the design program must be function, easy to understand and comfortable to maintenance. Another scope are :

- (a) To used and understand the PIC (Programmable integrated circuit)

1.4 Problem Statement

In most industrial, they still used manual system to control their system. The malfunction at DB (Distributor Board) occurred when there are no supply current, it is one of the example of manual system that used in industry. In order to detect the malfunction manually a multimeter or multimeter is used to ensure the component are damage. Some of the manual procedure that one still being practice in industry are such as trigger the blower fan, fault machine detection and others. When manual system fail to operate it will give side effect such as interfering with machine movement. It will also effect the maintenance occurred thus effecting the production course. In order to overcome this problem, a automated factory safety control system with LED display panel is used. It function as a monitoring device to the factory with only one workstation.

CHAPTER 2

LITERATURE REVIEW

2.1 Introduction

A literature review is a description of the literature relevant to a particular field or topic. This is often written as part of a postgraduate thesis proposal, or at the commencement of a thesis. In this project overview about the Smart Factory in industrial automation.

Industrial automation or numerical control is the use of control systems such as computers to control industrial machinery and processes, replacing human operators. In the scope of industrialization, it is a step beyond mechanization. Whereas mechanization provided human operators with machinery to assist them with the physical requirements of work, automation greatly reduces the need for human sensory and mental requirements as well. Currently, for manufacturing companies, the purpose of automation has shifted from increasing productivity and reducing costs, to broader issues, such as increasing quality and flexibility in the manufacturing process.

The old focus on using automation simply to increase productivity and reduce costs was seen to be short-sighted, because it is also necessary to provide a skilled workforce who can make repairs and manage the machinery.

An automated system is collection of device working together to accomplish tasks or produce a product or family of product.(John Stenerson (2003)). An automobile, for example, is an automated system. The automobile has a brain box to receive inputs from various sensor and to control various output that regulated the engine's operation and other function such as antilock braking.

A home burglar alarm system is another automated system. its control box receives input from sensor and switches located on doors and windows of the house. If the control box receives a signal that a door or window has been opened, it sound the alarm and calls the police department. (John Stenerson (2003)

Industrial automated system can be one machine or a group of machines called a cell, show in figure 2.1 below :

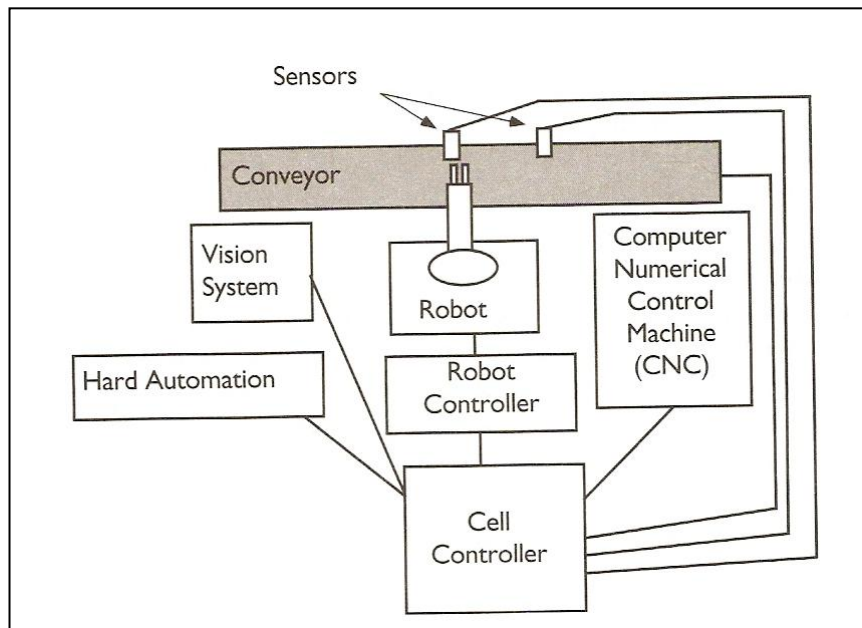


Figure 2.1 : This figure show a simple automated cell with several devices. (John Stenerson (2003)

The cell has a conveyor for bringing material into and out of the cell, a robot to move the material between devices in the cell, a CNC machine for the machining the parts, a hard automation device for a special task, a vision system for inspecting the parts, some sensor for sensing parts, and a cell controller for integrating and controlling all of the other device. Device includes those that actually produce the product and that provide support, control, and feedback to the system. The four basic type of device in a cell are production, support, control, and feedback. (John Stenerson (2003).

2.2 Smart Factory

Smart factory its means in industrial the factory used the high safety to protect all system. Where PLC will control the alarm system and analyse data from sensor. In smart factory PLC is used to detect temperature gradient, smoke alarm detection, machine operation and malfunction of electrical system. The PLC will control the alarm system and analyse data from sensor and show on the indicator controller monitor.

2.2.1 Argus Titan System

In industrial like ‘Argus Titan System’, are used automation safety system, The Argus Titan system is a user-programmable, real-time control system with dedicated distributable hardware. It has been specifically designed to accomplish three objectives within a single platform:

- (a) Automated equipment control
- (b) Monitoring and alarms
- (c) Data acquisition

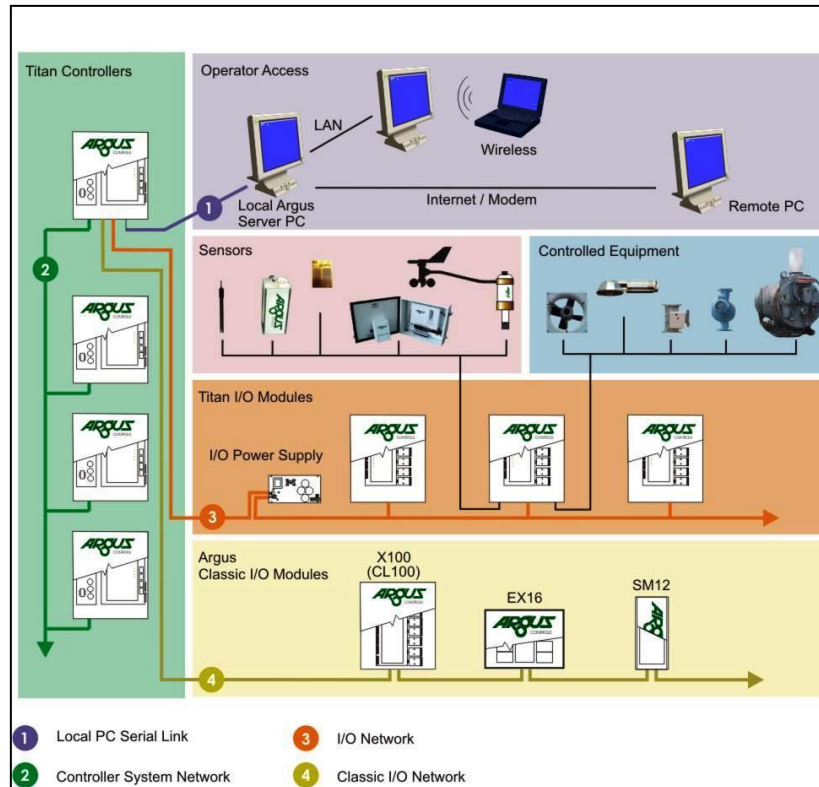


Figure 2.2: relationship block diagram for Argus system

For horticulture applications, the Argus system can also meet the needs of the crop by controlling CO₂ levels, irrigation, chemical treatments, and nutrient supplies. It continuously monitors all growing environments and equipment operations and reports on the consumption and supply of resources such as water, electricity, heat, and chemicals and equipment operation hours.

The Argus system not only addresses direct safety problems with proper equipment installation and wiring, but also includes additional settings to further protect and improve operation. These include

- (a) Minimum “on” and “off” times prevent short-cycling and premature wear of equipment.
- (b) Power-up delay times will delay and stage load operations upon return from power failures or drop outs. This feature is much appreciated by either your generator or the electrical company, as the case may be.

- (c) Event records and data recording provide summaries of equipment operating frequency and duration as well as a continuous operating audit. This information is very important when evaluating performance or maintenance and service requirements.
- (d) Multiple operating limits, and safety overrides can be configured to ensure the safest operation, and extend the operating life of equipment.
- (e) Modulating control - the Argus system contains programs to manage modulating equipment such as hot water heating systems and ventilation systems. These systems are capable of delivering a wide range of output levels. The computer can calculate and then directly deliver the correct output, after evaluating a range of operator set limits
- (f) Pulse-width modulation - most on/off equipment is either too effective when on or not effective enough when off. Unfortunately, most equipment responses required are somewhere between these two extremes. Staging of multi-unit systems like cooling fans can provide some intermediate steps, but these are not sufficient for full smooth control.
- (g) The Argus system can cycle a piece of equipment on and off in proportion to the required response and achieve a very full range of control. The inertia of the greenhouse environment can absorb these operating pulses quite effectively and smooth out the “bumps”. For example, the computer will turn a unit heater “off” after the calculated heat requirement has been delivered, regardless of the current air temperature. The longer term air temperature average will include the pulse of heat and future heat pulses will be adjusted to give greater or lesser response as required. This control strategy greatly reduces temperature overshoot, resulting in lower energy costs and a better growing environment without increasing the total number of equipment operations (cycling). It is particularly effective when managing fog and mist systems.

The distributed network of controllers is treated as a single system. The activities of individual controllers can be coordinated to accomplish cross-module control objectives such as irrigation and the efficient distribution of heat from a central supply.

Typical Hardware components include in this smart system is :

- (a) Argus Titan controllers
- (b) Titan I/O modules (and any 'Classic' equipment on older installations and retrofits)
- (c) Sensors
- (d) Output relays
- (e) Power supplies
- (f) Local PC for operator access

2.2.2 Smart (Intelligent) system

In the hard wiring circuit, inputs such as limit switch, emergency push button, sensor such as temperature switches are wired into the system using several different wires for each device. For example is show a car wash system in figure 2.3 below :

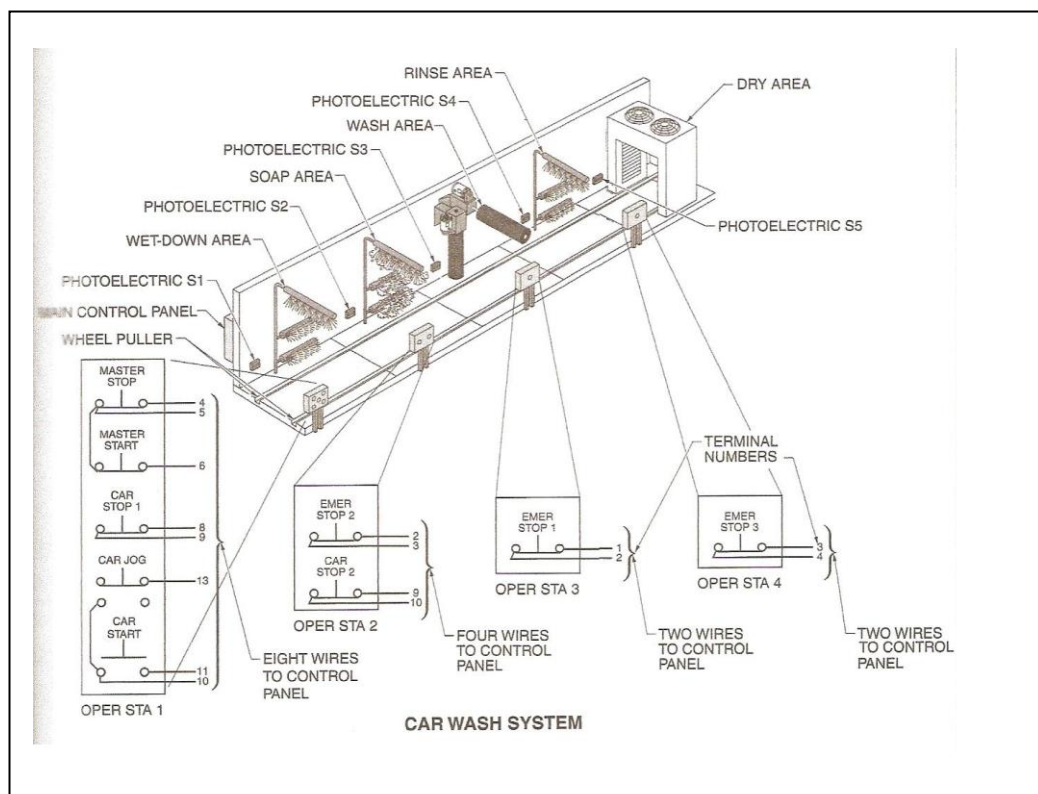


Figure 2.3 : Hard wiring require a large number of control wires to interconnect a system.

(Gary J. Rockis and Glen A. Mazur 2003)