## AUTOMATIC SATELLITE SIGNAL TRACKING SYSTEM

## MOHAMMAD AIZAD BIN MOHAMMAD IDRIS

This report is submitted in partial fulfillment of the requirements for the award of Bachelor of Electronic Engineering (Telecommunication Electronics) with Honours

Faculty of Electronic and Computer Engineering

Universiti Teknikal Malaysia Melaka

13 NOVEMBER 2008

C Universiti Teknikal Malaysia Melaka

HALAYSIA	FAKULTI	UNIVERSTI TEKNIKAL MALAYSIA MELAKA KEJURUTERAAN ELEKTRONIK DAN KEJURUTERAAN KOMPUTER BORANG PENGESAHAN STATUS LAPORAN	
		PROJEK SARJANA MUDA II	
Tajuk Pro Sesi Peng	-	ATIC SATELLITE SIGNAL TRACKING SYSTEM 09	
Carro MOU			
Saya <u>MOH</u>	AMMAD AIZAD BIN	MOHAMMAD IDRIS	
syarat keguna	aan seperti berikut:	ojek Sarjana Muda ini disimpan di Perpustakaan dengan syarat-	
•		rsiti Teknikal Malaysia Melaka.	
·	2. Perpustakaan dibenarkan membuat salinan untuk tujuan pengajian sahaja.		
1	3. Perpustakaan dibenarkan membuat salinan laporan ini sebagai bahan pertukaran antara institusi		
pengajia			
4. Sila tand	lakan ( 🗸 ) :		
	SULIT*	(Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia seperti yang termaktub di dalam AKTA RAHSIA RASMI 1972)	
	TERHAD*	(Mengandungi maklumat terhad yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan)	
$\checkmark$	TIDAK TERHAD		
		Disahkan oleh:	
	(TANDATANGAN PENULI	S) (COP DAN TANDATANGAN PENYELIA)	

C Universiti Teknikal Malaysia Melał
--------------------------------------

"I hereby declare that this report is the result of my own work except for quotes as cited in the references"

Signature	:
Author	: MOHAMMAD AIZAD BIN MOHAMMAD IDRIS
Date	:

"I hereby declare that I have read this report and in my opinion this report is sufficient in terms of the scope and quality for the award of Bachelor of Electronic Engineering (Telecommunication Electronics) with Honours"

Signature	:
Supervisor's Name	: ABDUL RANI BIN OTHMAN
Date	:

C Universiti Teknikal Malaysia Melaka

To My Beloved Father and Mother

### ACKNOWLEDGEMENT

First and foremost, I would like to give thanks to ALLAH SWT for helping me through all the obstacles that I encountered during the work of this project.

I would like to express my appreciation to my supervisor, Abdul Rani Bin Othman for his support and guidance throughout this whole project.

I would like to thank my beloved family and my relatives for their encouragement and never ending support. Their support and lovely companionship is another important source of strength for me. My deepest appreciation goes to all my friends for the fruitful suggestion, proof reading and wishes.

Lastly, I would like to acknowledge every individual who involves in this project in order to accomplish the task given.

## ABSTRACT

This project will construct an Automatic Satellite Signal Tracking System. The model of satellite tracking used a comparator circuit to control the system. A simulated tracking satellite system using UHF bands have successfully developed.

## ABSTRAK

Projek yang akan dijalankan adalah untuk membina sebuah Sistem Pengecam Satelit Signal Automatik. Model ini akan dikawal oleh satu litar yang dikenali sebagai Litar Pembandingan. Satu simulasi telah berjaya dijalankan apabila diuji dengan jalur gelombang UHF pada sistem tersebut.

# TABLE OF CONTENT

CHAPTER	TIT	LE	PAGE
`	PRO	JECT TITLE	i
	ABS	TRAK	ii
	ABS	TRACT	iii
	TAB	BLE OF CONTENT	iv
	LIST	Г OF TABLES	v
	LIST	Γ OF FIGURES	vi
I	INT	RODUCTION	1
	1.1	Project Introduction	1
	1.2	Project Objective	3
	1.3	The Scope of Work	3
	1.5	Methodology	4
П	LIT	ERATURE REVIEW	5
	2.1	Satellite Dishes	5
		2.1.1 Parabolic	7
		2.1.2 Off Dish	7

ix

	2.1.3	Cass	7
	2.1.4	Principle of Operation	8
2.2	Low N	loise Block Converter	10
2.3	Compa	arator	12
	2.3.1	Types of Comparator	12
		2.3.1.1 Inverting and Noninverting	
		Comparator	12
		2.3.1.2 Comparator with Hysteresis	13
		2.3.1.3 Voltage comparator (using Op-amp)	15
		2.3.1.4 Microvolt comparator	17
2.4	Compa	arison between Comparator	18
2.5	Motor	ized Satellite Dish	20
	2.5.1	Rotation of Stepper Motor	21
2.6	Freque	ency to Voltage Converter	23
	2.6.1	Types of Converter	23
		2.6.1.1 LM2917 - Frequency to Voltage	
		Converter	23
		2.6.1.2 VFC320 - Frequency to Voltage	
		Converter	26
		2.6.1.3 LM331A/LM331 Precision	
		Frequency to Voltage Converters	28
	2.6.2	Conclusion	30

III	PRO	JECT METHODOLOGY	32
	3.1	Introduction	32
	3.2	Flow Chart	33
	3.3	Signal Tracking System Model	34
	3.4	Measured Amplified Signal	34
	3.5	Power Supply System and Circuit	36
	3.6	Comparator F/V Circuit	36
IV	<b>RESULT AND DISCUSSION</b>		38
	4.1	Comparator Circuit	38
		4.1.1 Work out with Function Generator	39
		4.1.2 Troubleshooting	40
	4.2	Block Diagram of System	43
	4.3	Automatic Satellite Signal Tracking System	43
V	CON	CLUSION AND SUGGESTION	45

5.1	Conclusion	46
5.2	Suggestion	46

VI REFERENCES 47

# LIST OF FIGURES

# NO TITLE

## PAGE

1.0	Block Diagram of Home Terminal Reception	2
2.1	Types of dishes (a) Parabolic, (b) Off-center, (c) Cassegrain	6
2.2	(1) C-band dishes, (2) Ku-band dishes	9
2.3	Low Noise Block Converter	10
2.4	LNB Illustration Diagram	11
2.5	Non-inverting Comparator	13
2.6	Inverting Comparator	13
2.7	Inverting comparator with Hysteresis	14
2.8	Non-inverting comparator with hysteresis	14
2.9	Schematic Diagram of voltage comparator	16
2.10	Illustrated of circuit	16
2.11	Schematic diagram of microvolt comparator	18
2.12	Rotations of motor	22
2.13	Typical Application	24

2.14	Connection Diagram of Converter (8-pin)	24
2.15	Connection Diagram of Converter (14-pin)	25
2.16	Functional Block Diagram	27
2.17	Connection Diagram for F/V Conversion	27
2.18	Functional Block Diagram	29
2.19	Frequency-to-Voltage Converter	29
3.1	Model of Tracking System	34
3.2	Amplifier Circuit Diagram	35
3.3	Regulated DC Diagram	36
3.4	F/V circuit	37
4.1	Comparator Circuit	38
4.2	Tested with Function Generator	39
4.3	Troubleshooting with Yagi Antenna	40
4.4	Block Diagram of System	43
4.5	Tracking System Model	43
4.6	Overall System Design	44

# LIST OF TABLES

NO	TITLE	PAGE
2.1	Typical overdrive delay	17
2.2	Comparison of LM360 and uA760C	19
2.3	Comparison of LM261 and NE529	19
2.4	Comparison of F/V Converters	30

# LIST OF GRAPH

NO	TITLE	PAGE
4.1	Power (uW) vs Frequency (MHz) for 0.5m	42
4.2	Power (uW) vs Frequency (MHz) for 1m	42

C Universiti Teknikal Malaysia Melaka

### **CHAPTER 1**

## INTRODUCTION

### **1.1 INTRODUCTION**

The use of satellite in communication systems is very much a fact of everyday life, as is evidenced by the many homes which are equipped with antennas or dishes used for reception of satellite television. Satellite form an essential part of telecommunication systems worldwide, carrying large amounts of data and telephone traffic of data in addition to television signals.[1]

A satellite communications system uses satellites to relay radio transmissions between earth terminals. The two types of communications satellites are ACTIVE and PASSIVE. A passive satellite only reflects received radio signals back to earth. An active satellite acts as a REPEATER; it amplifies signals received and then retransmits them back to earth. This increases signal strength at the receiving terminal to a higher level than would be available from a passive satellite.[2]

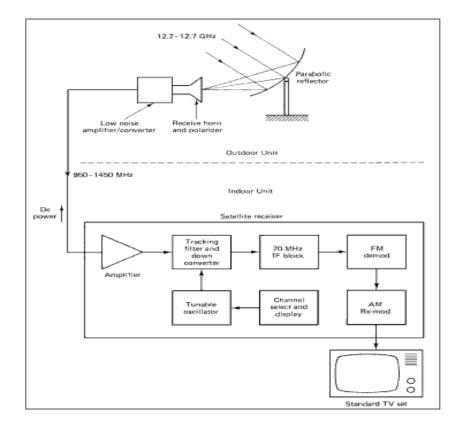


Figure 1.0 Block Diagram of Home Terminal Reception

Figure 1.0 shows the communication between outdoor unit and indoor unit. Outdoor unit consist the antenna types, horn receiver and low noise amplifier/converter. The signal on the antenna will be transmit to indoor unit consist satellite receiver and output device (television).

Satellite communications offer a number of features not readily available with other means of communications. The areas of the earth are very large to the satellite, because of that, the satellite can form the star point of a communications net linking together many users simultaneously, user who may be widely separated geographically. The same feature enables satellite to provide communications links to remote communities in sparsely populated area which are difficult to access by other means [1]. Thus, this project will gather all the data needed to predict the telecommunication system model.

## **1.2 PROJECT OBJECTIVE**

The objective of my project is to develop a model of Automatic Satellite Signal Tracking System.

### **1.3 SCOPE OF WORK**

After identified the scope of work needed, there are several main areas that have to be done:

1. Literature Review

These consist of existing research done about satellite system prediction and design model.

2. Suitable data for design

The system design will consider the suitable parameter in order to determine the model

3. Prototype model

Since all the parameters and component of circuits were gathered, next is to predict the model.

4. Performance testing

After constructed the circuit for the system, the circuit are need to test the effectiveness and maintain the results

5. Model of system

Finally, the model of Satellite Tracking System will be developed.

3

### **1.4 PROJECT METHODOLOGY**

This project started by studying the basic fundamental of satellite communications. All of this information was obtained from journal, paper, book and sites.

There are many types of tracking system designed in the market today, but several of them are operated in manual way. By improving the existed design, the system will able to operate automatically. The signal tracked on the antenna/dishes usually comes from many different angles before it can store into receiver panel. The problem is, the rotation of antenna/dishes only can rotate in 2 ways either horizontal or vertically. After some considerations, the system will operate the antenna/dishes on horizontal ways which give more area of searching to antenna/dishes.

Besides attenuation effects, the strength of signal coming into antenna/dish also need to be considered. The signal captured on the antenna must be strong enough to trigger the comparator circuit. Means, the antenna wouldn't stop rotating if signals are not strong /sufficient.

It's very important for antenna to rotate smooth and slow enough to capture the signal. These motors must capable to rotate 360 degree forward and backward since several wires will attach to motor's body. If not, wires might be twisted around and spoils the VHF and UHF plates.

The comparator circuit is a very important part where it can control the motor's rotation to stop or keep rotate. The details about choosing the IC will be discuss in the results later.

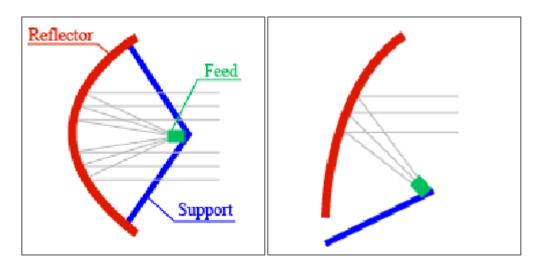
## **CHAPTER 2**

## LITERATURE REVIEW

## 2.1 SATELLITE DISHES

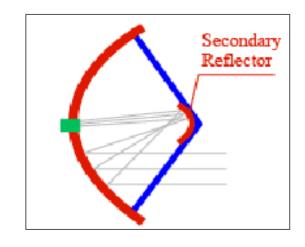
A satellite dish is a type of parabolic antenna that receives or transmits electromagnetic signals to and from another location typically a satellite. A satellite dish is a type of microwave antenna. Satellite dishes come in varying sizes and designs, and are commonly used to receive satellite television. Many of the offset type of satellite dishes are sections of a larger parabolic dish. **Figures 2.1(a)**, (b) and (c) show the types of satellite dishes such parabolic, Off-center and Cass.











(c)

Figure 2.1 Types of dishes (a) Parabolic, (b) Off-center, (c) Cass

The parabolic dish (a) shape reflects the signals directly to the feed placed at the focus point of the dish. Off-center dish (b) operates same as parabolic, but the support of the feed is placed quite lower than the center where the Off-center's focus point is placed. The Cass dish (c) has 2 reflectors where signal will reflect twice as to the feed. The Cass's feed is placed at first the reflector.[1]

#### 2.1.1 Parabolic

There are a number of dish antenna types. The first and simplest is the Prime Feed Focus dish, which is a parabolic dish with the LNC mounted centrally at the focus. Because the LNC is mounted centrally, it means that a lot of the incoming signals are blocked by the LNC. Its efficiency of 50% is low compared with the other types. The Prime Feed Focus dishes are mainly used for antennae with diameters over 1.4 meters. The parabolic antenna is less sensitive to small directional deviations and there is a better chance of receiving signals outside the normal footprint. On the other hand, rain and snow can easily collect in the dish and could interfere with the signal.[3]

### 2.1.2 Off Dish

The Offset Dish Antenna has its LNC not mounted centrally, but to the side of the dish. Because the LNC no longer obstructs the signal path, the dish has a better performance than the Prime Feed Focus dish. This allows the dish diameter to be smaller. Another advantage of this type of dish is that it can be positioned almost vertically, whereas the Prime Feed Focus dish needs to be positioned more obliquely. The problem that it could collect rain and snow and give disturbance to the signals is therefore less likely to happen.[3]

#### 2.1.3 Cass

The Cass (Dual Offset Dish) Antenna is an improvement on the Offset Dish antenna and has an even better performance. Its efficiency is about 80%. The main feature of this antenna is that it has two dishes: a larger receiving dish and a smaller dish facing the opposite direction which collects the signals from the larger dish and directs it to the LNC.[3]

#### 2.1.4 Principle of operation

The parabolic or any shape of a dish reflects the signal to the dish's focal point. Mounted on brackets at the dish's focal point is a device called a feedhorn. This feedhorn is essentially the front-end of a waveguide that gathers the signals at or near the focal point and 'conducts' those to a low-noise block downconverter or LNB (**Figure 2.03**). The LNB converts the signals from electromagnetic or radio waves to electrical signals and shifts the signals from the downlinked C-band and/or Ku-band to the L-band range. Direct broadcast satellite dishes use an LNBF, which integrates the feedhorn with the LNB. (A new form of unidirectional satellite antenna, which does not use a directed parabolic dish and can be used on a mobile platform such as a vehicle).[4]

The theoretical gain (directive gain) of a dish increases as the frequency increases. The actual gain depends on many factors including surface finish, accuracy of shape, feedhorn matching. At lower frequencies, C-band for example, dish designers have a wider choice of materials. The large size of dish required for lower frequencies led to the dishes being constructed from metal mesh on a metal framework. At higher frequencies, mesh type designs are rarer though some designs have used a solid dish with perforations. A common misconception is that the LNBF, the device at the front of the dish, receives the signal directly from the atmosphere. For instance, one news countdown shows a "red data stream" being received by the LNBF directly instead of being beamed to the dish, which because of its parabolic shape will collect the signal into a smaller area and deliver it to the LNBF.[4]

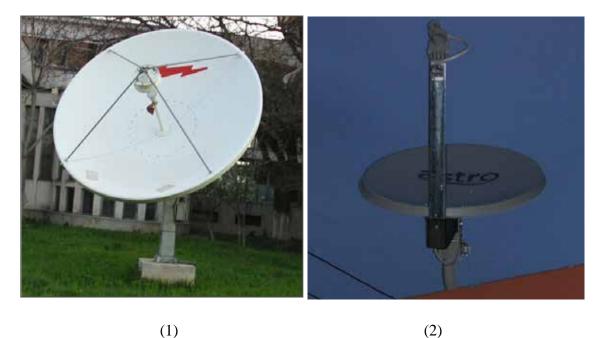




Figure 2.2 (1) C-band dishes, (2) Ku-band dishes

Modern dishes intended for home television use are generally 43 cm (18 in) to 80 cm (31 in) in diameter, and are fixed in one position, for Ku-band reception from one orbital position. Prior to the existence of direct broadcast satellite services, home users would generally have a motorized C-band satellite dish of up to 3 meters in diameter for reception of channels from different satellites. Overly small dishes can still cause problems, however, including rain fade and interference from adjacent satellites.[5]

