

raf

TJ223.P76 .K36 2009.



0000067315

Development of visualization system for material handling
system using wonderware intouch software / Kamal
Syahidi Kamaruddin.

**DEVELOPMENT OF VISUALIZATION SYSTEM FOR
MATERIAL HANDLING SYSTEM USING
WONDERWARE INTOUCH SOFTWARE**

KAMAL SYAHIDI BIN KAMARUDDIN

UNIVERSITI TEKNIKAL MALAYSIA MELAKA



UNIVERSITI TEKNIKAL MALAYSIA MELAKA

**DEVELOPMENT OF VISUALIZATION SYSTEM FOR
MATERIAL HANDLING SYSTEM USING WONDERWARE
INTOUCH SOFTWARE**

This report submitted in accordance with requirement of the Universiti Teknikal Malaysia Melaka (UTeM) for the Bachelor Degree of Manufacturing Engineering (Robotic and Automation) with Honours.

by

KAMAL SYAHIDI BIN KAMARUDDIN

FACULTY OF MANUFACTURING ENGINEERING

2009



UNIVERSITI TEKNIKAL MALAYSIA MELAKA

BORANG PENGESAHAN STATUS LAPORAN PROJEK SARJANA MUDA

TAJUK: Development of Visualization System for Material Handling System Using Wonderware InTouch Software

SESI PENGAJIAN: 2008/09 Semester 2

Saya **KAMAL SYAHIDI BIN KAMARUDDIN**

mengaku membenarkan Laporan PSM ini disimpan di Perpustakaan Universiti Teknikal Malaysia Melaka (UTeM) dengan syarat-syarat kegunaan seperti berikut:

1. Laporan PSM adalah hak milik Universiti Teknikal Malaysia Melaka dan penulis.
2. Perpustakaan Universiti Teknikal Malaysia Melaka dibenarkan membuat salinan untuk tujuan pengajian sahaja dengan izin penulis.
3. Perpustakaan dibenarkan membuat salinan laporan PSM ini sebagai bahan pertukaran antara institusi pengajian tinggi.
4. **Sila tandakan (√)

SULIT

(Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia yang termaktub di dalam AKTA RAHSIA RASMI 1972)

TERHAD

(Mengandungi maklumat TERHAD yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan)

TIDAK TERHAD

Disahkan oleh:

Alamat Tetap:

Cop Rasmi:

Lot 171 Kg Kutan Hilir,

16250 Wakaf Bharu,

Kelantan

SHARIMAN BIN ABDULLAH
Pensyarah
Fakulti Kejuruteraan Pembuatan
Universiti Teknikal Malaysia Melaka


Tarikh: 21/05/09

Tarikh: 21/05/09

** Jika Laporan PSM ini SULIT atau TERHAD, sila lampirkan surat daripada pihak berkuasa/organisasi berkenaan dengan menyatakan sekali sebab dan tempoh laporan PSM ini perlu dikelaskan sebagai SULIT atau TERHAD.

DECLARATION

I, hereby, declared this report entitled “The Development of Visualization System for Material Handling System using Wonderware InTouch Software” is the result of my own research except as cited references.

Signature : 
Author's Name : KAMAL SYAHIDI BIN KAMARUDDIN
Date : 21/05/09

APPROVAL

This report is submitted to the Faculty of Manufacturing Engineering of UTeM as partial fulfillments for the degree of Bachelor of Manufacturing Engineering (Robotic and Automation) with Honours. The member of supervisory committee is as follow:



SHARIMAN BIN ABDULLAH
Pensyarah
Fakulti Kejuruteraan Pembuatan
Universiti Teknikal Malaysia Melaka

ABSTRACT

There are several techniques of visualization to control the automation system. One of the most common techniques is the Human Machine Interface (HMI). The task of an HMI is to make the function of a technology self-evident. In this case, the Programmable Logic Controller (PLC) is programmed by using the Step 7-Micro/Win software. In order to develop the visualization system, Wonderware InTouch software is been used. The report covers from the literature stage and the designing until the finishing stage. The literature stage is about how to collect the information and generate the ideas, while the designing covers with the programming and drawings of the system, then the interaction between them will be tested and analyzed until the desired result is obtained. The result obtained in this project shows the effectiveness of the virtual controller in InTouch design that replace the real control panel on the conveyor, in which affect the simulation of material handling system that mainly programmed by the PLC programming software as well as the programming in the InTouch software itself.

ABSTRAK

Terdapat pelbagai teknik untuk menggambarkan serta mengawal sesuatu sistem automasi. Salah satu teknik yang paling biasa digunakan ialah manusia-mesin-pemuka (HMI). Tujuan penggunaan HMI adalah untuk menjadikan sesuatu sistem itu itu menerima maklumat serta bertindak dengan sendiri. Di dalam kes ini, pengawal logik boleh ubah (PLC) diprogramkan menggunakan perisian Step 7-Micro/Win, manakala untuk menggambarkan sistem tersebut, perisian seperti Wonderware InTouch digunakan. Laporan untuk projek ini merangkumi dari peringkat sastera hinggalah ke peringkat rekaan dan penamat. Peringkat sastera adalah bertujuan untuk mengumpul maklumat serta menjana idea. Peringkat rekaan pula adalah bertujuan untuk meraka bentuk HMI yang digunakan untuk sistem serta membuat atur cara untuk PLC. Selain itu, pada peringkat ini juga interaksi dan komunikasi antara kedua-duanya akan diuji dan dianalisis sehingga mendapat keputusan yang terbaik. Keputusan projek ini menunjukkan bagaimana efektifnya penggunaan pengawal maya yang menggantikan fungsi pengawal sebenar yang terdapat pada panel sistem pengedali. Pengawal maya ini dibina menggunakan rekaan InTouch yang mana memberi kesan ke atas simulasi sistem pengendalian bahan yang diprogramkan melalui perisian program PLC dan juga melalui program di dalam perisian InTouch itu sendiri.

DEDICATION

To my family, my friends, and lectures as well as my
beloved ones

ACKNOWLEDGEMENT

I would like to thank for my supervisors, Mr Shariman, Mr. Azrul Azwan, Pn. Nur Aidawaty, and Pn Silah Hayati as well to my ex-co-supervisor, Mr. Mohd Najib Ali for all the guidance in order to help me to finish up this report. I also want to say thanks to all technicians that give me the support and allow me to spend the time in the laboratory and use the tools in it.

TABLE OF CONTENT

Abstract	i
Abstrak	ii
Dedication	iii
Acknowledgement	iv
Table of Content	v
List of Tables	viii
List of Figures	ix
List Abbreviations	xi
1. INTRODUCTION	1
1.1. Problem Statement	2
1.2. Aim of The Project	3
1.3. Project Objectives	3
1.3.1. Project Scopes	3
1.4. Project Planning	4
2. LITERATURE REVIEW	6
2.1. FMS	6
2.1.1. Conveyor System	9
2.2. Type of Controller	11
2.2.1. PLC	11
2.2.1.1. PLC Hardware	12
2.3. Overview of HMI Components	15
2.3.1. Interface Components	16
2.3.1.1. Physical component	16
2.3.1.2. Virtual Component	17
2.3.1.3. Visual Component	17
2.3.2. SCADA	18
2.3.2.1. Architecture of SCADA	19
2.3.2.2. Application Development	21

2.4.	DDE	22
3.	METHODOLOGY	25
3.1	Project Flow	25
3.1.1.	Literature Stage	27
3.1.1.1.	Selection and Understanding Topic	27
3.1.1.2.	Data Collection	27
3.1.1.3.	Study the Configurations Involved	27
3.1.2.	Construction and Improvement Stage	28
3.1.2.1.	HMI Design	28
3.1.2.2.	Creating the Program	29
3.1.2.3.	Communicate the Programming with the HMI Design	30
3.1.2.4.	Testing And Analyzing	30
3.1.2.5.	Implementation and Observation	30
3.1.3.	Finishing Stage	30
3.1.3.1.	Discussion and Conclusion	31
3.1.3.2.	Presentation and Report Writing	31
3.2.	Project Tools and Equipments	31
3.2.1.	Personal Computer (PC)	31
3.2.2.	Flexible Conveyor System with Siemens S7-200 PLC	32
3.2.3.	Wonderware InTouch Software (Trial Version 9.5)	33
3.2.4.	Siemens STEP 7-MicroWIN Software	34
3.2.5.	SolidWorks CAD Software (Trial Version)	34
3.2.6.	CoDeSys Programming System Software (Free Version)	35
3.2.7.	Communication Cable	35
4.	DEVELOPMENT AND IMPLEMENTATION FOR THE SYSTEM	36
4.1.	Development	36
4.2.	Implementation	37
4.2.1.	Tag Names/ Variables	37
4.2.2.	Programming	39
4.2.3.	Designing And Programming of the Drawing	41
4.3.	Testing	43

5. RESULT AND DISCUSSION	45
5.1. Result	45
5.2. Discussion	46
5.2.1. Programming Analysis	46
5.2.1.1. Establishment of Communication	47
5.2.1.2. Ladder Diagram in Siemens Step7-MicroWIN and CoDeSys	47
5.2.1.3. InTouch Design and Programming	52
6. CONCLUSION AND RECOMMENDATION	66
6.1. Conclusion	66
6.2. Recommendation	67
REFERENCES	68

APPENDICES

- A. Global Variables list in CoDeSys
- B. The list of I/O variables in CoDeSys
- C. The external variables to create ladder diagram in CoDeSys
- D. The list of tag names used in InTouch software
- E. The programming in Application Script in InTouch

LIST OF TABLES

1.1	Gantt chart for the project	5
2.1	Sample of Input-Output in PLC	14
2.2	Classification of PLCs by Number of Input/Output Terminals	14
3.1	The list of tag names that corresponding on each element	38

LIST OF FIGURES

2.1	Flexibility in traditional FMS	8
2.2	Comparison of throughput time for a traditional and FMS	8
2.3	Variety types of conveyors	10
2.4	PLC system components overview	12
2.5	Typical configurations for PLC	15
2.6	Simple relationship between PLC and HMI and equipment	16
2.7	Sample of visual of HMI	18
2.8	Typical hardware architecture	19
2.9	Generic software architecture	20
3.1	Flow chart of the project	26
3.2	Sample of drawn Flexible Conveyor System	29
3.3	Sample of programming in LAD mode	29
3.4	Personal computer	32
3.5	Flexible Conveyor System in FKP CIM Laboratory in UTeM	32
3.6	The processes flow in Flexible Conveyor System	33
3.7	Preface of Wonder InTouch Software	33
3.8	Preface of Siemens STEP 7-Micro/WIN 32 Version 3.2 Software	34
3.9	The SolidWorks Software Logo	34
3.10	CoDeSys programming system software	35
4.1	The ladder diagram in MicroWin	41
4.2	The assembly of parts to make a conveyor in Solidwork software	42
4.3	The 'cylinder' part that is created in SolidWorks software.	42
4.4	The assembly of whole parts from SolidWorks in InTouch software.	43
5.1	Thegraphical view of the result of the visual system for the material handling system	45
5.2	Access name in InTouch.	47
5.3	The conveyor lines with the items involved	53

5.4	Configurations of pallet for the left side of the conveyor	55
5.5	Configurations of pallet for the middle side of the conveyor	56
5.6	Configurations of pallet for the right side of the conveyor	57
5.7	The programming in Application Script in InTouch	59
5.8	Panel board of the conveyor	61
5.9	The related switches and buttons on the conveyor panel board	62
5.10	The configurations for the actuating of cylinder 1	64
5.11	The configurations for the actuating of cylinder 2	64

LIST OF ABBREVIATIONS

CAD	-	Computer Aided Design
CIM	-	Computer Integrated Manufacturing
CP	-	Communications Processor
CPU	-	Central Processing Unit
DDE	-	Dynamic Data Exchange
FBD	-	Functional Block Diagram
FMS	-	Flexible Manufacturing System
FKP	-	Fakulti Kejuruteraan Pembuatan
GUI	-	Graphical User Interface
HMI	-	Human Machine Interface
I/O	-	Input / Output
LAD	-	Ladder Diagram
LAN	-	Local Access Network
MPI	-	Multipoint Interface
PC	-	Personal Computer
PL1	-	Pilot Light 1
PLC	-	Programmable Logic Controller
PSM	-	Projek Sarjana Muda
RTDB	-	Real Time Data Base
SCADA	-	Supervisory Control and Data Acquisition
SE	-	Sensor
UTeM	-	Universiti Teknikal Malaysia Melaka

CHAPTER 1

INTRODUCTION

Talking about the interface, it exists in many forms and there is a commonality among them. A simplest word to say about the interface is that what connects two dissimilar materials, devices, systems, or processes so that they can work together but in the fact they would not interact with each other under the ordinary circumstances. Thus, the interface makes the interaction is possible.

The specific meaning of the interface always changes with time. In hardware, an interface is a connector used to link devices. In software, it allows communication between two software systems or between people and systems. An interface is a shared boundary, in which a physical point of demarcation between two devices where the electrical signals, connectors, timing and handshaking are defined. The other meaning for interface is the procedures, codes and protocols that enable two entities to interact for a meaningful exchange of information.

There are two general categories of interface that must be concerned with. The first one is HMI. HMI allow people to talk to machines. The interface translates information from the machine into something we can understand, and translates information from us into language that machine can understand. The second one is machine-machine interfaces (MMI) in which allow the machines to talk to one another by converting the signals that one understands into signals that the other understands.

The task of an HMI is to make the function of a technology self-evident. HMI effectiveness is measured by a number of components, such as learn ability and productivity. These components are sometimes brought together under the title of

"usability," also known as quality of use. Through the graphic based HMI, it is easy for the operator to monitor the process, set the working condition of the treatment, search the historical data, and reminder and alarm the operator when necessary. The HMI also enable the user to visualize and control industrial processes while providing engineers with an easy-to-use development environment and extensive functionality to rapidly create test and deploy powerful automation applications that connect and deliver real-time information. Generally, the hardware that controls the system is programmable logic control (PLC).

Esposito (2003) states that, PLC is a user –friendly electronic computer designed to perform logic functions such as AND, OR, and NOT for controlling the operation of industrials equipment and processes.

In addition, there are several advantages of PLC compared to the relay control system. They are more reliable and faster in operation and come out in smaller size and can be readily to be expanded. They also require less electrical power and are less expensive for the same number of control functions. Furthermore, they does not taking any modifications of hard-wiring to perform specific functions.

SCADA is stands for Supervisory Control and Data Acquisition that focuses on the supervisory level. It normally use in the PLC to supervise its condition or prediction of the processes involved.

1.1 Problem Statement

The current flexible conveyor system in Faculty of Manufacturing Engineering (FKP) Computer Integrated Manufacturing (CIM) Laboratory in Universiti Teknikal Malaysia Melaka (UTeM) that uses the PLC has no visualization system. The system operation can only be seen from the simulation of ladder diagram. There is a need for user to visualize the operation of the system. In order to make this flexible conveyor system to be a reliable control system, a HMI must display the necessary information and sufficiently for competent decision making. In the other word, HMI will

visualize the operations of the hardware system that controlled by PLC. Moreover, the control panel of the conveyor system also can be replaced by this HMI.

1.2 Aim of The Project

This project is aimed to design and develop a HMI system (or visualization system). In this case, a visualization system will be developed to simulate PLC (Siemens) program. The simulation shall be created based on the real condition of PLC (Siemens) that located on the conveyor in FKP CIM Laboratory.

1.3 Project Objectives

There are two objectives involved in this project. These objectives will determine the basic requirement of the target in which the project may result.

- (a) A visualization system for PLC Siemens in FKP CIM laboratory must be developed to show the effectiveness of the replacing the control panel of the conveyor system with the virtual control panel in HMI.
- (b) PLC software and HMI software must be communicated to each other to show the relationship between both of them

1.4 Project Scopes

In order to develop a visualization system, a computer is used to create the design in HMI software such as Wonderware InTouch, as well as to create the programme that will control the design by using PLC programming software such as Step 7-Micro/Win. The computer also will simulate the visualization system after both tasks above is done.

The path communication between Siemens STEP 7-MicroWIN software and Wonderware InTouch software will be generated before the simulation of the system is started. This means, both software must interact to each other and can be functional properly. In the case of the unexpected condition, such as the communication between both of them is failed, the CoDeSys software will replace the MicroWin, but using the same programming in MicroWin.

1.5 Project Planning

The planning for this project is based on the Gantt chart that was design in order to organize the time that must be taken to complete the project Table 1.1, shows all the steps taken in the chart. By using this chart, the researcher can estimate on what time he must be taken to complete such of task.

CHAPTER 2

LITERATURE REVIEW

This chapter will cover all the information related to this project, such as Flexible Manufacturing System (FMS), PLC, HMI, and Dynamic Data Exchange (DDE)

Using this information, the element in the project will be presented to give more understanding about the title, objective, problem statement and the scope of project. The source that may be taken is either from book, journal, patent, conference paper, research paper and website.

2.1 FMS

A manufacturing system is a collection of integrated equipment and human resources, whose function is to perform one or more processing and/or assembly operations on a starting raw material, part, or set of parts.

A FMS is a group of numerically-controlled machine tools, interconnected by a central control system. The various machining cells are interconnected, via loading and unloading stations, by an automated transport system. Operational flexibility is enhanced by the ability to execute all manufacturing tasks on numerous product designs in small quantities and with faster delivery. It has been described as an automated job shop and as a miniature automated factory. Simply stated, it is an automated production system that produces one or more families of parts in a flexible manner. Today, this prospect of automation and flexibility presents the possibility of producing nonstandard parts to create a competitive advantage. (Advameg Inc, 2007)

The general objectives of an FMS are to approach the efficiencies and economies of scale normally associated with mass production, and to maintain the flexibility required for small- and medium-lot-size production of a variety of parts.

A generic FMS is said to consist of the following components.

- (a) A set of work stations containing machine tools that do not require significant set-up time or change-over between successive jobs. Typically, these machines perform milling, boring, drilling, tapping, reaming, turning, and grooving operations.
- (b) A material-handling system that is automated and flexible in that it permits jobs to move between any pair of machines so that any job routing can be followed.
- (c) A network of supervisory computers and microprocessors that perform some or all of the following tasks:
 - (i) Directs the routing of jobs through the system;
 - (ii) Tracks the status of all jobs in progress so it is known where each job is to go next;
 - (iii) Passes the instructions for the processing of each operation to each station and ensures that the right tools are available for the job;
 - (iv) Provides essential monitoring of the correct performance of operations and signals problems requiring attention.
- (d) Storage, locally at the work stations, and/or centrally at the system level.
- (e) The jobs to be processed by the system. In operating an FMS, the worker enters the job to be run at the supervisory computer, which then downloads the part programs to the cell control or NC controller.

(Advameg Inc, 2007)

The potential benefits from the implementation and utilization of a flexible manufacturing system have been detailed by numerous researchers on the subject. A review of the literature reveals many tangible and intangible benefits that FMS users will experience (Advameg Inc, 2007). These benefits include:

- (a) Less waste
- (b) Fewer workstations