

# AUTOMATED PET FEEDER

PUTRI NURAIN BINTI HANG TUAH

This report is submitted in partial fulfillment of the requirements for the award of Bachelor of Electronic Engineering (Industrial Electronics) With Honours.

Faculty of Electronic and Computer Engineering  
Universiti Teknikal Malaysia Melaka

April 2009



**UNIVERSITI TEKNIKAL MALAYSIA MELAKA**  
FAKULTI KEJURUTERAAN ELEKTRONIK DAN KEJURUTERAAN KOMPUTER

**BORANG PENGESAHAN STATUS LAPORAN  
PROJEK SARJANA MUDA II**

**Tajuk Projek : AUTOMATED PET FEEDER**

**Sesi Pengajian : 2/2008/2009**

Saya **PUTRI NURAIN BT HANG TUAH**

mengaku membenarkan Laporan Projek Sarjana Muda ini disimpan di Perpustakaan dengan syarat-syarat kegunaan seperti berikut:

1. Laporan adalah hakmilik Universiti Teknikal Malaysia Melaka.
2. Perpustakaan dibenarkan membuat salinan untuk tujuan pengajian sahaja.
3. Perpustakaan dibenarkan membuat salinan laporan ini sebagai bahan pertukaran antara institusi pengajian tinggi.
4. Sila tandakan (  $\checkmark$  ) :

**SULIT\***

(Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia seperti yang termaktub di dalam AKTA RAHSIA RASMI 1972)

**TERHAD\***

(Mengandungi maklumat terhad yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan)

**TIDAK TERHAD**

Disahkan oleh:

\_\_\_\_\_  
(TANDATANGAN PENULIS)

\_\_\_\_\_  
(COP DAN TANDATANGAN PENYELIA)

Alamat Tetap: NO 6, JLN PERMATANG 23,  
TMN DESA JAYA, 81100,  
JOHOR BAHRU, JOHOR.

Tarikh: 30 / 04 / 2009

Tarikh: .....

“I hereby declared that this report entitle Automated Pet Feeder is a result of my own work except for the works that have been cited clearly in the references.”

Signature : .....

Student Name : PUTRI NURAIN BT HANG TUAH

Date : 30 APRIL 2009

“I hereby declared that I have read this report in my opinion this report is sufficient in terms of the scope and quality for the award the Bachelor of Electronic Engineering (Industrial Electronics) With Honours.”

Signature : .....

Supervisor's Name : EN AMAT AMIR BIN BASARI

Date : 30 APRIL 2009

Special dedicated to my beloved parents, family, lecturer and fellow friends, who had strongly, encourage and supported me in my entire journey of learning.

## ACKNOWLEDGEMENT

First of all, I would like to express my thankfulness and gratitude to Allah S.W.T who has given me all the strength that I needed to complete this final year project and also prepare this report.

With this opportunity, I would like to express my gratitude to the Faculty of Electronics and Computer Engineering (FKEKK), Universiti Teknikal Malaysia Melaka (UTeM) generally, and especially to my supervisor Mr Amat Amir. for this help, advices and guidance that he gave during this project.

I am also indebted to my parents, a million of thanks to them because of their support to me with their prayer and their love. Last but no least, I would like to thank all my friends 4 BENE S1 whom have been such wonderful friends to me and also to everyone else who was involved in the completion of this project. I would like to thank them for all the support and encouragement to me which have given me the courage and wisdom to fulfill my final year project. Thank you.

## **ABSTRACT**

A microcontroller is a high technology that can store and running the program. This project is about a food container that can feed pet(hamster) twice a day without human observation by using the microcontroller ATmega32 software which can control the size of the automatic feeding machine's door. The time for the door to open had been program earlier in the microcontroller. To make sure that the pet's food is not over limit, force sensor will be place at the bottom of the bowl. It will detect the weight of the food where the operation will be program earlier in the microcontroller. The 'Automated Pet Feeder' will be controlled by a wireless infra-red remote control.

## ABSTRAK

Pengawal mikro merupakan cip yang berteknologi tinggi yang mampu menyimpan dan melaksanakan sesuatu aturcara program. Projek ini adalah tentang mengawal makanan binatang peliharaan(hamster) dua kali sehari secara automatic menggunakan pengawal mikro ATmega32. Ia digunakan untuk mengawal bukaan pada alat pemakanan secara automatik. Tempoh masa untuk bukaan telah ditetapkan. Untuk memastikan tiada makanan yang melimpah keluar dari mangkuk makanan, alat pengesan tekanan diletakkan dibawah mangkuk makanan. Ia akan mengesan berat makan yang dituangkn ke dalam mangkuk makanan seperti yang telah di programkan di dalam microcontroller. 'Automated Pet Feeder' akan dikawal oleh alat kawalan jauh infra-merah tanpa wayar.



## TABLE OF CONTENTS

CHAPTER	CONTENT	PAGE
	TITLE	i
	DECLARATION	ii
	DEDICATION	iii
	ACKNOWLEDGEMENTS	iv
	ABSTRACT	vi
	ABSTRAK	vii
	TABLE OF CONTENT	viii
	LIST OF FIGURE	xi
<b>I</b>	<b>INTRODUCTION</b>	
	1.1 Introduction	1
	1.2 Project Objective	2
	1.3 Problem Statement	2
	1.4 Scope Of Work	2
	1.5 Thesis outline	3
<b>II</b>	<b>LITERATURE REVIEW</b>	
	2.1 Introduction	4
	2.2 Microcontroller	4
	2.2.1 ATmega32	5

2.3	Infra-red remote control	6
2.4	IR encoder/decoder	6
2.4.1	MCP2120 IR encoder/decoder	6
2.5	Transceivers	8
2.5.1	TFDU6103	8
2.6	Transistor	10
2.6.1	BUZ73 power transistor	10
2.7	Opto-isolator	11
2.7.1	Darlington pair	11
2.7.2	4N35 opto-isolator	11
2.8	Keypad	12
2.9	LCD	13
2.9.1	LCD defect	13
2.10	Etching	14
2.10.1	Material for etching process	14
2.11	DC motor	15
2.12	Analog to Digital converter(A/D) module	16

### **III**

### **METHODOLOGY**

3.1	Methodoly of the project	17
3.2	Hardware development	18
3.3	Software development	19
3.3.1	Code vision AVR flowchart	19
3.3.2	ISIS 7 Professional and ARES Professional Flowchart	20
3.4	Code Vision AVR	21
3.5	ISIS Professional	25
3.6	ARES Professional	26
3.7	Etching process(manually)	28
3.8	Design of the project	30

	3.9 Stages of the project	31
<b>IV</b>	<b>RESULT AND DISCUSSION</b>	
	4.1 Methodology Of The Project	33
	4.2 Transmitter circuit	34
	4.3 Receiver circuit	36
	4.4 Power Circuit	38
	4.5 Project analysis	39
	4.6 Discussion	40
<b>V</b>	<b>CONCLUSION AND RECOOMENDATION</b>	
	5.1 Conclusion	41
	5.2 Recommendation	42
	<b>REFFERENCES</b>	43

## LIST OF FIGURE

NO	TITLE	PAGE
Figure 2.1	ATMega32	5
Figure 2.2	ATMega32 symbol	5
Figure 2.3	MCP2120	7
Figure 2.4	MCP2120 symbol	7
Figure 2.5	MCP2120 blockdiagram	8
Figure 2.6	Transceivers	9
Figure 2.7	TFDU6103 block diagram	9
Figure 2.8	TFDU6103 pin diagram	9
Figure 2.9	BUZ73 symbol	10
Figure 2.10	BUZ73	10
Figure 2.11	Opto-isolator	11
Figure 2.12	Numeric keypad	12
Figure 2.13	LCD defects	13
Figure 2.14	Etching acid	14
Figure 2.15	Etching board	14
Figure 2.16	Sand Paper	15
Figure 2.17	DC motor	15
Figure 3.1	Hardware development flowchart	18
Figure 3.2	Software development flowchart	19
Figure 3.3	Open new layout	27
Figure 3.4	Example of layout	27
Figure 3.5	Flow chart of the project	30
Figure 4.1	Transmitter circuit	34

Figure 4.2	Transmitter layout	35
Figure 4.3	Receiver circuit	36
Figure 4.4	Receiver PCB layout	37
Figure 4.5	Power circuit in ISIS 7	38
Figure 4.6	Power circuit	38
Figure 4.7	Power circuit PCB layout	39

## CHAPTER 1

### INTRODUCTION

#### 1.1 Introduction

Automated pet feeder is one of the new technologies for feed pet. It will help pet owner to take care of their pet while they are not at home. Even the owners are not at home, they still can feed their pet. Automated pet feeder is built to help pet owner taking care of their pet. Automated pet feeder is one of the pet feeders that will be controlled by a wireless infra-red remote control. The automated pet feeder will be automatically dispenses predetermined amounts of food at the exact times user choose with controlled by a wireless infra red remote control.

As pet lovers, user should understand those pets also need a proper diet management. Sometimes, the responsibilities of life inhibit pet owners from properly caring for their pets. Whether user away from home unexpectedly or simply would like one less chore to worry about, user can feel secure that the beloved pet will be cared for and fed on time, every time.

## **1.2 Project Objective**

The objective of this project is to create an automatic feeding machine. Nowadays, everyone can have a pet at home without giving their full commitment to have a healthy pet. With this automatic feeding machine, it will help pet owner to manage their pet dietary well. When user at home, it can be controlled by wireless infrared remote control. If user is not at home, user can set the timer to feed their pet. To make sure that the food does not exceed, force sensor will active and detect the exact amount should be in the bowl.

## **1.3 Problem Statement**

As we look nowadays, pet owners sometimes does not have much time to look at their pet. Because of this disability, an automated pet feeder had been build. For information, automated pet feeder offers some tangible advantage to the pet owners. Potential advantages included are this purpose could help pet owners to give good diet management for their pet and to help pet get a healthy life.

## **1.4 Scope of Work**

The scope of works in this project is to develop pet feeder by using wireless infra red remote control. Pet owners will just use the wireless infra red remote control to depressed predetermined amount of food at one time. In order to implement this design, both software and hardware will be use. Microcontroller that will be used is ATmega32.

## 1.5 Thesis Outline

This thesis represent by five chapters. The following is the outline for this project in order to understand the whole report.

Chapter 1 of the thesis will explain briefly about the project background, objective of the project which needs to be achieved, problem statement of the project, scope of works regarding the project and methodology of the project.

Chapter 2 describes about literature review involved gather information of the project in order to complete the whole project. This study is focused especially on microcontroller that been used and others component that important for this project.

Chapter 3 explains about the project methodology where how the project is implemented. The approach for meeting the goals and objectives and project life cycle phase is described in this chapter, along with the tasks needed to complete it.

Chapter 4 describes the project finding which includes the simulation design. This chapter also discusses and analyze about the project and operation of the software such as the programmed for the microcontroller.

Chapter 5 will be the conclusion and suggestion to the project in future undertakings.



## **CHAPTER 2**

### **LITERATURE REVIEW**

#### **2.1 Introduction**

Automated pet feeder is one of the new technologies that can help pet owner to manage their pet dietary well. So, in terms of made an automatic pet feeder, some research about the component that be used will be made. It will give more information about the component.

#### **2.2 Microcontroller**

A microcontroller (also MCU or  $\mu\text{C}$ ) is a functional computer system-on-a-chip. It contains a processor core, memory, and programmable input/output peripherals. Microcontrollers include an integrated CPU, memory (a small amount of RAM, program memory, or both) and peripherals capable of input and output.

### 2.2.1 ATmega32

The Atmel ATmega series of microcontrollers are very popular due to the large number of peripherals inbuilt in them. It have features such as internal PWM channels, 10-bit A/D converters, UART/USART and much more, which are useful for a lot of applications. It is also help reducing external hardware these are built-in.



Figure 2.1: ATmega32

(XCK/T0) PB0	1	40	PA0 (ADC0)
(T1) PB1	2	39	PA1 (ADC1)
(INT2/AIN0) PB2	3	38	PA2 (ADC2)
(OC2/AIN1) PB3	4	37	PA3 (ADC3)
(SS) PB4	5	36	PA4 (ADC4)
(MOSI) PB5	6	35	PA5 (ADC5)
(MISO) PB6	7	34	PA6 (ADC6)
(SCK) PB7	8	33	PA7 (ADC7)
RESET	9	32	AREF
VCC	10	31	GND
GND	11	30	AVCC
XTAL2	12	29	PC7 (TOSC2)
XTAL1	13	28	PC6 (TOSC1)
(RXD) PD0	14	27	PC5 (TDI)
(TXD) PD1	15	26	PC4 (TDO)
(INT0) PD2	16	25	PC3 (TMS)
(INT1) PD3	17	24	PC2 (TCK)
(OC1B) PD4	18	23	PC1 (SDA)
(OC1A) PD5	19	22	PC0 (SCL)
(ICP) PD6	20	21	PC7 (OC2)

Figure 2.2: ATmega32 symbol[4]

### **2.3 Infra-Red remote control**

A remote control is an electronic device used for the remote operation of a machine. Commonly, remote controls are used to issue commands from a distance to consumer electronics. Remote controls for these devices are usually small wireless handheld objects with an array of buttons for adjusting various settings such as track number and volume. In fact, for the majority of modern devices with this kind of control, the remote contains all the function controls while the controlled device itself only has a handful of essential primary controls. Most of these remotes communicate to their respective devices via infrared (IR) signals and a few via radio signals.

### **2.4 IR encoder/decoder**

IR encoder is remote control device paired with IR decoder utilizing infrared signal transmission. It encodes the data either from the button or from the microcontroller, with the address code into a serial coded waveform sending through IR modulation. IR decoder receives the IR signal using the IR receiver module, and decodes it back to data and address.

#### **2.4.1 MCP2120 IR encoder/decoder**

MCP2120 is a low-cost, high-performance, fully-static infrared encoder/decoder. This device sits between a UART and an infrared (IR) optical transceiver. The data received from a standard UART is encoded (modulated) and output as electrical pulses to the IR Transceiver. The IR Transceiver also receives data which it outputs as electrical pulses that the MCP2120 decodes (demodulates) then transmits the data via the MCP2120 UART. This modulation and demodulation method is performed in accordance with the IrDA standard.

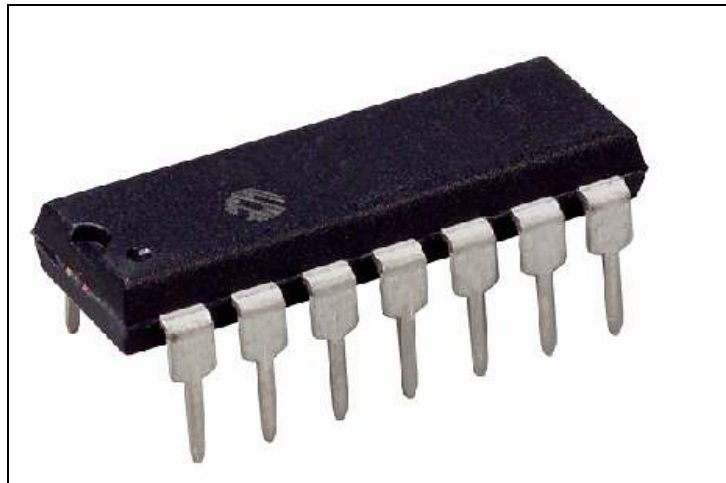


Figure 2.3: MCP2120

It also builds up with CMOS technology with special specification. The specification is listed below.

SPECIFICATION
Low-power, high-speed CMOS technology
Fully static design
Low voltage operation
Commercial and Industrial temperature ranges
Low power consumption - < 1 mA @ 3.3V, 8 MHz (typical), 3 mA typical @ 5.0V when disabled.

Table 2.1: MCP2120 specification[5]

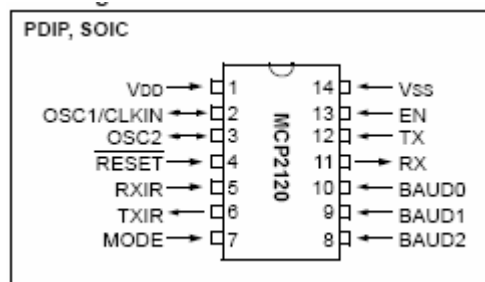


Figure 2.4: MCP2120 symbol[5]

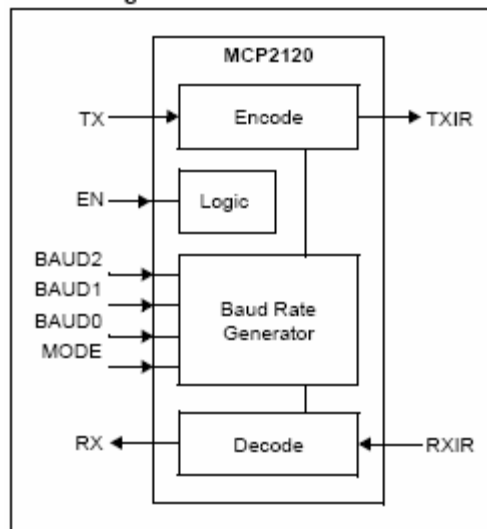


Figure 2.5: MCP2120 block diagram[5]

## 2.5 Transceivers

A transceiver is a device that has both a transmitter and receiver which are combined and share common circuitry or a single housing. If no circuitry is common between transmit and receive functions, the device is a transmitter-receiver. The term originated in the early 1920s. Technically, transceivers must combine a significant amount of the transmitter and receiver handling circuitry.

### 2.5.1 TFDU6103

The TFDU6103 is a low-power infrared transceiver module compliant to the latest IrDA physical layer standard for fast infrared data communication, supporting IrDA speeds up to 4.0 Mbit/s (FIR), and carrier based remote control modes up to 2 MHz. Integrated within the transceiver module are a PIN photodiode, an infrared emitter (IRED), and a low power CMOS control IC to provide a total front solution in a single package.



Figure 2.6: Transceivers[6]

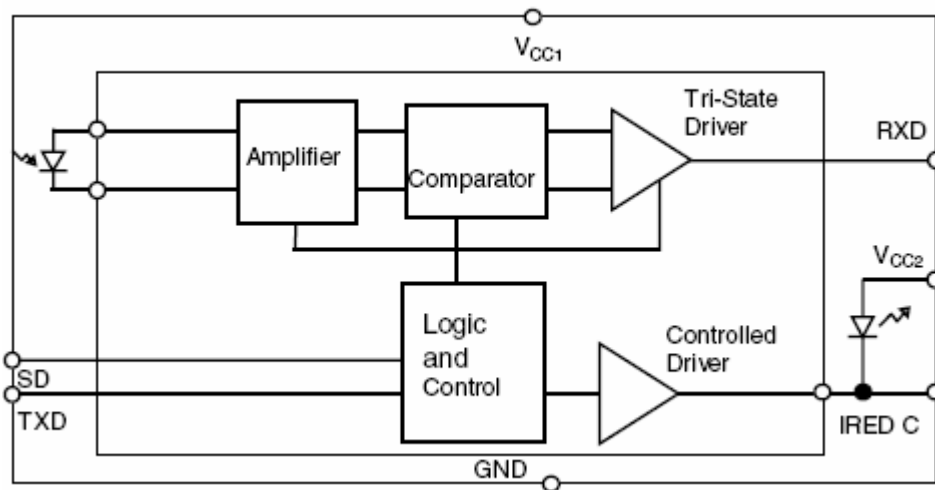


Figure 2.7: TFDU6103 block diagram[6]

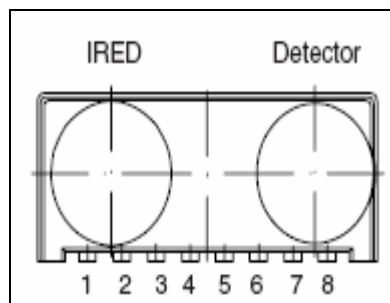


Figure 2.8: TFDU6103 pin diagram[6]

## 2.6 Transistor

A transistor is a semiconductor device commonly used to amplify or switch electronic signals. A transistor is made of a solid piece of a semiconductor material, with at least three terminals for connection to an external circuit. A voltage or current applied to one pair of the transistor's terminals changes the current flowing through another pair of terminals. Because the controlled (output) power can be much larger than the controlling (input) power, the transistor provides amplification of a signal. The transistor is the fundamental building block of modern electronic devices, and is used in radio, telephone, computer and other electronic systems. Some transistors are packaged individually but most are found in integrated circuits.

### 2.6.1 BUZ73 Power Transistor

Buz73 is one of the transistor families. It is n-type channel JFET transistor. JFET means junction field effect transistor and use electron for conduction since it is n-type channel.

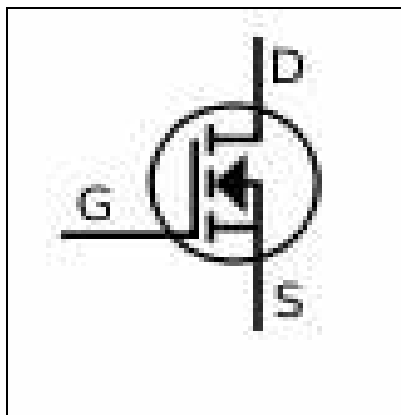


Figure 2.9: BUZ73 symbol



Figure 2.10: BUZ73

## 2.7 Opto-isolator

An opto-isolator (or optical isolator, optocoupler, photo coupler, or photoMOS) is a device that uses a short optical transmission path to transfer a signal between a transmitter and a receiver, while keeping them electrically isolated. The opto-isolator is a package that contains both an infrared LED and a photo detector such as silicon diode, transistor Darlington pair, or SCR. The wave-length response of each device is tailored to be as identical as possible to permit the highest measure of coupling possible.

### 2.7.1 Darlington pair

Darlington pair is a compound structure consisting of two bipolar transistors (either integrated or separated devices) connected in such a way that the current amplified by the first transistor is amplified further by the second one. This configuration gives a much higher current gain (written  $\beta$ ,  $h_{fe}$ , or  $h_{FE}$ ) than each transistor taken separately and, in the case of integrated devices, can take less space than two individual transistors because they can use a *shared* collector. Integrated Darlington pairs come packaged in transistor-like integrated circuit packages.

### 2.7.2 4N35 Opto-isolator

For this project, opto-isolator type 4N35 is choosing. 4N35 had been choosing because it is in a simple package and it is easy to construct with the circuit.

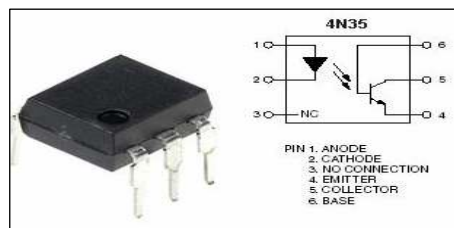


Figure 2.11: Opto-isolator