

**DEVELOPMENT AND ANALYSIS OF AN EMBEDDED
SOFTWARE FOR CILI-PADI PICKING ROBOT FRAMEWORK
USING MATLAB**

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UNIVERSITI TEKNIKAL MALAYSIA MELAKA

**DEVELOPMENT AND ANALYSIS OF AN EMBEDDED
SOFTWARE FOR CILI-PADI PICKING ROBOT
FRAMEWORK USING MATLAB WHICH HAS BEEN
APPROVED BY FACULTY OF ELECTRONIC AND
COMPUTER ENGINEERING (FKEKK)**

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**This report is submitted in partial fulfilment of the requirements
for the degree of Bachelor of Electronic Engineering with Honours**

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**Faculty of Electronic and Computer Engineering
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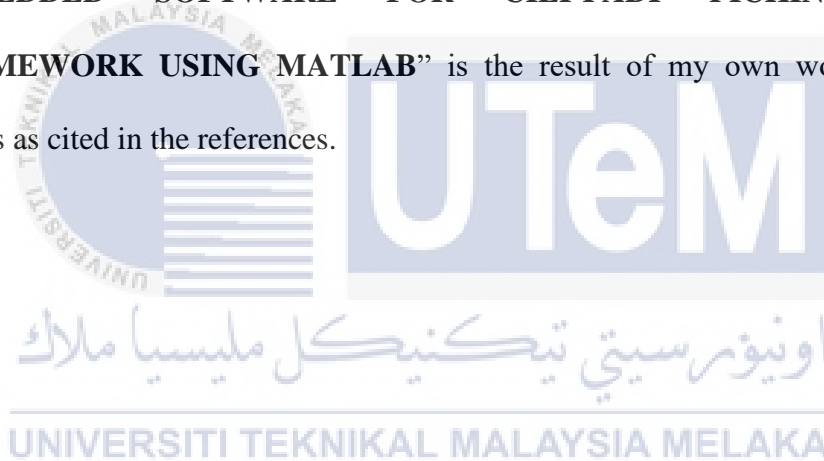
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I declare that this report entitled “**DEVELOPMENT AND ANALYSIS OF AN EMBEDDED SOFTWARE FOR CILI-PADI PICKING ROBOT FRAMEWORK USING MATLAB**” is the result of my own work except for quotes as cited in the references.



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I hereby declare that I have read this thesis and in my opinion this thesis is sufficient in terms of scope and quality for the award of Bachelor of Electronic Engineering with Honours.



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DEDICATION

I would want to thank everyone who helped make this project a reality, whether they were directly or indirectly involved. It's possible that I wouldn't have been able to finish all of this work without their help and encouragement. To express my gratitude for Dr. Zarina binti Mohd Noh's trust in me to complete my assigned thesis, I am happy to do so on this occasion. In addition, I would want to express my gratitude to Dr. Wira Hidayat bin Mohd Saad and all of the lecturers that helped me complete this PSM. I'd also like to thank everyone who helped make this assignment possible, especially my lecturer, Dr. Zarina binti Mohd Noh, for the guidance she provided over the course of this assignment and also other lecture who helped me with the PSM and this dissertation are also mentioned. I can't forget to thank my fellow soldiers, who have been a tremendous source of support and collaboration during the course of our mission. Finally, I'd want to thank all of my friends who helped me complete this project. Thanks a lot.

ABSTRACT

The primary focuses of this research are the development, implementation, and verification of embedded software for robotic systems. The Cili-Padi Picking Robot places a significant amount of attention on being able to function all actuators and sensors by making use of MATLAB and having the ability to communicate with a GUI. However, in order to reach its full potential, the robot needs to be equipped with AI in its visual system so that it can recognise mature chilies. However, the focus of this project is on embedded systems for sensors and actuators in robots. This is accomplished by connecting MATLAB and Arduino so that they are capable of communicating with each other thanks to the utilisation of serial communication, which enables both programmes to send and receive data. Prior to that, it needs to be done for the purpose of robot analysis, which includes determining what actuators and sensors are utilised as well as what data will be used regardless of whether or not the parameters are modified. Additionally, this results in the formation of many subdivisions for the system that is integrated into the robot. Systems comparable to these include a manual navigation system, a Robot Arm system, a visual robot system to detect Chile, as well as other systems of a similar nature.

ABSTRAK

Fokus utama penyelidikan ini ialah pembangunan, pelaksanaan dan pengesahan perisian terbenam untuk sistem robotik. Robot Pemetik Cili Padi memberi perhatian yang besar kepada keupayaan untuk berfungsi semua penggerak dan penderia dengan menggunakan MATLAB dan mempunyai keupayaan untuk berkomunikasi dengan GUI. Bagaimanapun, untuk mencapai potensi sepenuhnya, robot itu perlu dilengkapi dengan AI dalam sistem visualnya supaya ia dapat mengenali cili matang. Walau bagaimanapun, tumpuan projek ini adalah pada sistem terbenam untuk penderia dan penggerak dalam robot. Ini dicapai dengan menyambungkan MATLAB dan Arduino supaya mereka mampu berkomunikasi antara satu sama lain berkat penggunaan komunikasi bersiri, yang membolehkan kedua-dua program menghantar dan menerima data. Sebelum itu, ia perlu dilakukan untuk tujuan analisis robot, termasuk menentukan apakah penggerak dan penderia yang digunakan serta apakah data yang akan digunakan tanpa mengira sama ada parameter diubah suai atau tidak. Selain itu, ini mengakibatkan pembentukan banyak subbahagian untuk sistem yang disepadukan ke dalam robot. Sistem yang setanding dengan ini termasuk sistem navigasi manual, sistem Lengan Robot, sistem robot visual untuk mengesan Chile, serta sistem lain yang serupa.

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TABLE OF CONTENTS

Declaration	
Approval	i
Dedication	i
Abstract	i
Abstrak	ii
Acknowledgements	iii
Table of Contents	iv
List of Figures	viii
List of Tables	x
List of Symbols and Abbreviations	xi
List of Appendices	xii
CHAPTER 1 INTRODUCTION	1
1.1 Project Background	2
1.2 Problem Statement	2

1.3	Objectives	3
1.4	Scope of Project	4
1.5	Report Outline	4
CHAPTER 2 BACKGROUND STUDY		6
2.1	Robotic Framework and Its Application	7
2.2	Basic Embedded Software for Robot	11
2.2.1	Embedded System Hardware & Software	12
2.2.2	Real-Time Embedded Systems	12
2.2.3	Model Based Design in MATLAB	13
2.3	Basic Structure of Robot	18
2.4	Functionality of Robot	19
2.4.1	Mechanical Structure Function	21
2.4.2	Sensory Structure Function	21
2.4.3	Control Structure (Robot Control Organs)	21
2.4.4	Governance Structure (Memorization and Calculation Organs) Function	22
2.5	Software Architecture and Programming of a Robot	24
CHAPTER 3 METHODOLOGY		26
3.1	Analyzing of Robot Framework for Cili-Padi Picking Robot	28
3.2	Development an Embedded Software for Requirement Cili-Padi Picking Robot	30

3.2.1	Navigation System Requirement	30
3.2.2	Delta Robot Arm Requirement	31
3.2.3	Robot Gripper Requirement	32
3.2.4	Robot Vision Requirement	32
3.3	Real-time robot operating system using FreeRTOS	33
3.4	Arduino coding for each part sensor for Cili-Padi Picking Robot	37
3.4.1	Part of Navigation system Arduino coding	37
3.4.2	Part of Delta Robot Arm and gripper system Arduino coding	39
3.5	Development Functionality Robot using MATLAB software	40
3.5.1	Serial Communication MATLAB (Simulink) connect in Arduino	41
3.5.2	Simulink to App Design for GUI	45
3.6	Demonstration Hardware and Software for Functoriality	47
CHAPTER 4 RESULTS AND DISCUSSION		48
4.1	Analysis of Cili-Padi Picking Robot Framework	49
4.2	Develop Embedded Software Interfaced with Graphical User Interface (GUI).	50
4.2.1	Arduino and MATLAB communicate for Cili-Padi Picking Robot	51
4.2.2	App Design and Simulink communicate for GUI Cili-Padi Picking Robot	54
4.3	Functionality of the Embedded Software in Real Time	59
CHAPTER 5 CONCLUSION AND FUTURE WORKS		61

5.1	Conclusion	61
5.2	Future Works	62
	REFERENCES	63
	APPENDICES	68



LIST OF FIGURES

Figure 2.1 Fundamental Robotic Operations and Actions	20
Figure 3.1 Flowchart of Project	27
Figure 3.2 Architecture of Cill-Padi Picking Robot	28
Figure 3.3 Cili-Padi Picking Robot Architecture and Components	30
Figure 3.4 Navigation System Requirement	31
Figure 3.5 Delta Robot Arm Requirement	31
Figure 3.6 Robot Gripper Requirement	32
Figure 3.7 Robot Vision Requirement	33
Figure 3.8 Library FreeRTOS	35
Figure 3.9 FreeRTOS Task	35
Figure 3.10 void Task Coding and Loop	36
Figure 3.11 Codes Require Delay	36
Figure 3.12 API Delays	37
Figure 3.13 Circuit Flex Sensor and Motor	38
Figure 3.14 Coding Flex Sensor to Apply at Motor	38
Figure 3.15 Output from Coding Flex	39

Figure 3.16 Output IMU Sensor	39
Figure 3.17 Block in Simulink for Single Data For Send Data And Receive Data ...	42
Figure 3.18 Coding Single Data.....	42
Figure 3.19 Coding for Multiple Data	43
Figure 3.20 Simulink Multiple Data	44
Figure 3.21 App Design Coding	46
Figure 3.22 GUI with Simulink	46
Figure 3.23 Circuit Prototype Cili Padi Picking Robot	47
Figure 4.1 Arduino Communicate with MATLAB	51
Figure 4.2 Send data from MATLAB to Arduino	52
Figure 4.3 Block Send And Receive Data In.....	52
Figure 4.4 Receive Data from Arduino.....	53
Figure 4.5 App Design Read Output Simulink.....	58
Figure 4.6 App Design Changed Value in Simulink Input.....	58
Figure 4.7 Reading Accelerometer in Simulink	59
Figure 4.8 Reading Gyro in Simulink.....	59
Figure 4.9 Graph Flex Sensor and IMU Sensor.....	60
Figure 4.10 Hardware for Testing.....	60

LIST OF TABLES

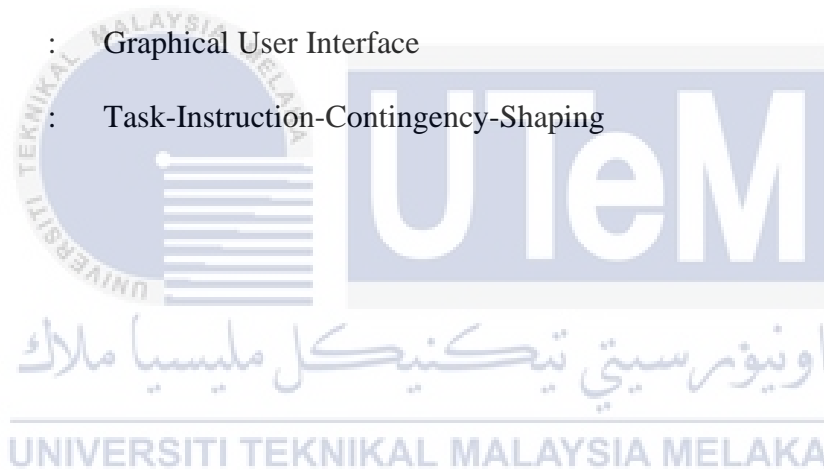
Table 2.1 Research Robotic Framework.....	10
Table 2.2 Model Based Design in MATLAB	16
Table 2.3 Functionality of Robot	22
Table 3.1 Description Each Function in Coding FreeRTOS	35
Table 4.1 Sensor and Actuator Setup Check List	49
Table 4.2 Overall Design in GUI.....	55

LIST OF SYMBOLS AND ABBREVIATIONS

ROS : Robot Operating System

GUI : Graphical User Interface

TICS : Task-Instruction-Contingency-Shaping



LIST OF APPENDICES

Appendix A Coding in Arduino.....	68
Appendix B Coding of App Design(MATLAB)	75
Appendix C Gantt Chart of Project Planning.....	86



CHAPTER 1

INTRODUCTION



This chapter describes the idea general idea for this project which includes the background of the project, problem statement, objectives, scope of the project, and the report outline.

1.1 Project Background

"Industry 4.0" refers to the transition to cyber-physical systems, which marks the fourth major industrial revolution [1]. In the fourth industrial revolution, the application of robot had been widely accepted to ease the work in the industry such as for agriculture propose. Because of this, the goal of this project is to find solutions to the challenges faced in the agriculture by constructing a robot structure with the capability of assisting farmer in tasks that can reducing their workload and reducing the amount of time they spend on such tasks. Therefore, this project is about how to build a robot framework through embedded software. By using the appropriate software to integrate the software for agriculture purpose, specifically for Cili Padi Picking Robot.

Selection of the right framework and middleware for software and hardware integration is a difficult process that can have far-reaching consequences for any robotics framework. In most cases, computational and memory resources are limited in the robotics software. The goal of this project is to create a framework through which embedded software like MATLAB can communicate to hardware like Arduino and demonstrate its application for robot's framework that can be used in agriculture. This project is also to run simulations with software and hardware also involve software simulation and hardware demonstration in real-world environment.

1.2 Problem Statement

Malaysia should encourage rice and chilli farming due to its struggling economy [2]. An increasing population and worldwide market demand agricultural products. Malaysia needs a more advanced and reliable food production system to address food sustainability and minimize dependence on imported basic food supply.

Upgrade seeds, pesticides, insecticides, fertilizers, and farming procedures. After locating the chili, the robot arm can pick up the plants one by one. The robot's durability and endurance will outperform a human's speed. Preventing chilies from bruising and lowering crop quality depends on the robot arm and fruit picking process.

Robots are made up of numerous functional components and require a variety of specific talents. These algorithms may be tested in either a simulated or real-world environment. An experimental setup with real parts can be used to test a design, but this approach is both costly and limiting in terms of exploratory study. In addition it is performed time-consuming to design a robot since each component has a distinct function, such as developing architecture robots, creating visual images, and creating arm robots. Hence, a simulation framework can cut down on the time, effort, and money needed to demonstrate working prototype of robot software [3].

In this project, the simulate framework will be integrated hardware involved in an embedded software to keep track of robot's system. The robotic system demonstrated of this prototype with utilized the Cili Padi Picking Robot, as an example one of the systems that can be used in agriculture.

1.3 Objectives

The objectives of this project are to:

1. Analyze and broken down a Cili-Padi Picking robot framework large systems into smaller and more manageable pieces.

2. Develop an embedded software part of the Cili-Padi Picking robot function using MATLAB software (Simulink and App Designer) that can be interfaced with Graphical User Interface (GUI).
3. Demonstrate the functionality of the embedded software in real time.

1.4 Scope of Project

The scope of this project to analyses a robotic framework of a Analysis part of Robot Cili-Padi Picking Robot and develop its framework through the use of MATLAB Simulink software communicate the Arduino using serial communication and freeRTOS. The hardware prototype of the robot demonstration within the Arduino board as its base platform.

1.5 Report Outline

The information presented in this report on the project is broken up into five chapters which are the introduction, the background study, the methodology followed by the results and the discussion, and the conclusion. In chapter 1, the description of the ideal and concept for robot agriculture and explanation step by step to analysis and develop the robot framework. This is followed the project background, problem statement, objective and scope of project.

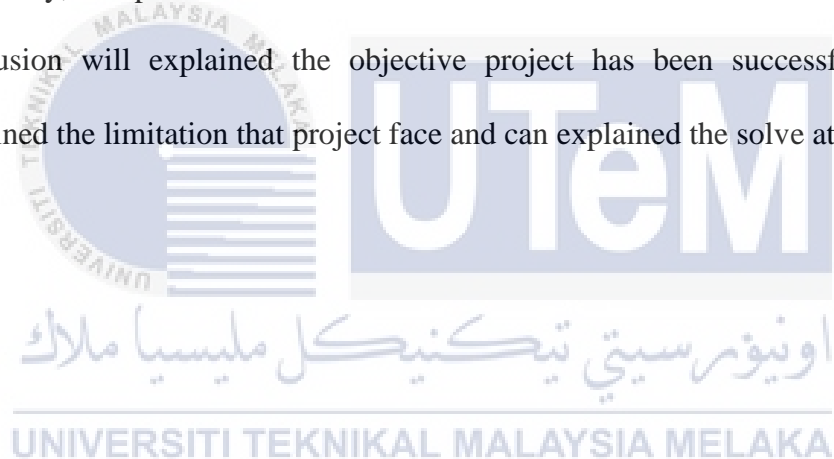
In Chapter 2 focused on the literature review or background study on robotic framework and embedded software using MATLAB software. In explanation for this comparison of previous research papers concerning the framework and application.

In chapter 3 is a focus in methodology content to achieve the objective project. This is followed by objective 1, the explanation on how analysis of Cili-Padi picking robot framework. In objective 2 show the step to develop embedded software and

hardware interface using MATLAB. And objective 3 is the final step how embedded software can run in real time in hardware.

Chapter 4, as where the result show achieves of the objective project. Result in objective 1 with analysis of Cili-Padi picking robot framework and can defined which actuators and sensor has been used and parameter has been used. Next, the objective 2, result show the develop embedded software interfaced with hardware and software communicate to produce GUI. Lastly objective 3 show the result functionality of embedded software in real time.

Finally, chapter 5. conclusion and future works towards the project. At conclusion will explained the objective project has been successful. This also explained the limitation that project face and can explained the solve at future work.



CHAPTER 2

BACKGROUND STUDY



This chapter focuses on research on the development and analysis of embedded software for a robot. First, research about robotic frameworks and their applications. Second, the basic embedded software for robots and robot functionality. Finally, a robot's software architecture and programming.