HAND SIGN LANGUAGE TRANSLATOR USING MOTION SENSOR

MUHAMMAD QAMAR AZFAR BIN MD TAUFIQ

UNIVERSITI TEKNIKAL MALAYSIA MELAKA

C Universiti Teknikal Malaysia Melaka

HAND SIGN LANGUAGE TRANSLATOR USING MOTION SENSOR

MUHAMMAD QAMAR AZFAR BIN MD TAUFIQ

This report is submitted in partial fulfilment of the requirements for the degree of Bachelor of Electronic Engineering with Honours

> Faculty of Electronic and Computer Engineering Universiti Teknikal Malaysia Melaka

> > **JUNE 2018**

C Universiti Teknikal Malaysia Melaka



UNIVERSITI TEKNIKAL MALAYSIA MELAKA FAKULTI KEJUTERAAN ELEKTRONIK DAN KEJURUTERAAN KOMPUTER

BORANG PENGESAHAN STATUS LAPORAN PROJEK SARJANA MUDA II

Tajuk Projek

HAND SIGN LANGUAGE TRANSLATOR USING MOTION SENSOR 2017/2018

Sesi Pengajian

:

Saya <u>MUHAMMAD</u> <u>QAMAR</u> <u>AZFAR</u> <u>BIN</u> <u>MD</u> <u>TAUFIQ</u> mengaku membenarkan laporan Projek Sarjana Muda ini disimpan di Perpustakaan dengan syarat-syarat kegunaan seperti berikut:

- 1. Laporan adalah hakmilik Universiti Teknikal Malaysia Melaka.
- 2. Perpustakaan dibenarkan membuat salinan untuk tujuan pengajian sahaja.
- 3. Perpustakaan dibenarkan membuat salinan laporan ini sebagai bahan pertukaran antara institusi pengajian tinggi.
- 4. Sila tandakan (✓):

SULIT*

TERHAD*

TIDAK TERHAD

(Mengandungi maklumat yang berdarjah keselamatan atau kepentingan Malaysia seperti yang termaktub di dalam AKTA RAHSIA RASMI 1972)

(Mengandungi maklumat terhad yang telah ditentukan oleh organisasi/badan di mana penyelidikan dijalankan.

Disahkan oleh:

*CATATAN: Jika laporan ini SULIT atau TERHAD, sila lampirkan surat daripada pihak berkuasa/organisasi berkenaan dengan menyatakan sekali tempoh laporan ini perlu dikelaskan sebagai SULIT atau TERHAD.

🔘 Universiti Teknikal Malaysia Melaka

DECLARATION

I declare that this report entitled "HAND SIGN LANGUAGE TRANSLATOR USING MOTION SENSOR" is the result of my own work except for quotes as cited in the references.

Signature :

Author : MUHAMMAD QAMAR AZFAR BIN MD TAUFIQ

Date : $28^{\text{TH}} \text{ MAY } 2018$

C Universiti Teknikal Malaysia Melaka

APPROVAL

I hereby declare that I have read this thesis and in my opinion this thesis is sufficient in terms of scope and quality for the award of Bachelor of Electronic Engineering with Honours.

Signature	:	
Supervisor Name	:	PM DR NURULFAJAR ABD MANAP
Date	:	



DEDICATION

I dedicated this thesis to my beloved parents, my project supervisor, UTeM lecturers and all my friends that help me throughout this degree life.

ABSTRACT

Hearing impairment and Speech impairment are form of disabilities that faced by a minor group of the society. By having those conditions will not only cause them a difficulty to communicate with the rest of people in the society, but also makes them hard to express their message. The main reason of this project is to break the barrier between deaf or mute community with the rest of the community by translating hand sign language into readable text. This project also can be access by everyone, it's like a platform that can allow anyone to access the algorithm anywhere. To make sure that this project achieves this target, an American Sign Language (ASL) Translator was created to translate ASL hand sign to readable English text. The LEAP Motion technology was implemented in this project to capture ASL fingerspelling hand sign gesture that been displayed by the user. The captured data is then being processed, recognized and classified into English letters. The translation letters will be displayed in the web so that user can know what have been translate. The average accuracy for all translation are more than 90% for pose and more than 65% for gesture. So, this technology can be used widely by all people so it can help translate the sign language into readable text.

ABSTRAK

Bisu dan pekak merupakan satu halangan yang dihadapi oleh sebahagian kecil masyarakat dunia. Dengan kecacatan ini, Orang Kelainan Upaya (OKU) ini bukan sahaja menghadapi kesukaran untuk berkomunikasi dengan masyarakat, tetapi ia juga menyebabkan mereka untuk menghadapi masalah untuk menyampaikan mesej mereka. Salah satu sebab utama projek ini adalah untuk memusnahkan halangan antara mereka untuk berkomunikasi dengan menterjemahkan Bahasa isyarat ke dalam texts yang boleh dibaca. Selain itu, projek ini juga boleh diakses oleh semua orang, dimana algoritmanya boleh didapati di mana sahaja yang mempunyai Internet. Untuk memastikan yang projek ini berhasil, Penterjemahan American Sign Language (ASL) akan dihasilkan bagi menterjemah ASL kepada teks Inggeris yang boleh dibaca. Teknologi LEAP Motion digunakan didalam projek ini untuk menangkap data yang sudah diberikan oleh pengguna. Data yang sudah didapati akan diiktiraf, diproses, dan diklasifikasikan kepada abjad Inggeris. Terjemahan abjad akan ditunjukkan di laman sesawang supaya pengguna tahu apa yang sudah diterjemahkan itu. Purata ketepatan untuk semua terjemahan mendapati lebih daripada 90% untuk Bahasa isyarat statik dan lebih daripada 65% bagi Bahasa isyarat bergerak. Jadi, teknologi ini boleh digunakan semua lapisan masyarakat kerana dapat membantu untuk menterjemahkan Bahasa isyarat kepada teks yang boleh dibaca.

ACKNOWLEDGEMENTS

Upon the successful completion of the project, I would like express my gratitude to those who helped me along the construction of the project. Special thanks addressed to my Final Year Project supervisor, PM Dr. Nurulfajar bin Abd Manap, for willing me to be part of this project. My supervisor had guided me step by step until I achieved my objective and project goals.

I would like to thank my family members, especially my parents for continuous support throughout my life. Their support, both in mentally and physically have helped me to keep survive in this degree life. Their encouragements had raise me up whenever I feel frustrated or devastated by the failure encountered.

I would like to express my thanks for all my friends, especially Ahamed Rizwan, Nurazman, Faiz, Aina and Naeem, who have guided and helped me during the development of the project. Their idea and opinion had more than often inspired and encouraged me to explore the unknown possibility, allowing me to improve my project.

Last but not least, credits and special thanks are given to all previous researchers for their magnificent work. Although I, myself might not know them in person, but their novel knowledge, creative idea and innovative solution had shed lights on my project, guiding me toward to completion of the project.

TABLE OF CONTENTS

Declaration	
Approval	
Dedication	
Abstract	i
Abstrak	ii
Acknowledgements	iii
Table of Contents	iv
List of Figures	ix
List of Tables	xii
List of Symbols and Abbreviations	xiii
List of Appendices	xiv
CHAPTER 1 INTRODUCTION	1
1.1 Background Study	1
1.2 Problem Statement	2
1.3 Objectives	3

1.4	Scope of Project	3
1.5	Project Significance	4
1.6	Report Structure	5
СНА	APTER 2 BACKGROUND STUDY	7
2.1	Introduction	7
2.2	Type of Sign Language	8
	2.2.1 American Sign Language	8
	2.2.2 Arabic Sign Language	9
	2.2.3 Thai Sign Language	10
2.3	Hand Feature Technology	10
	2.3.1 Hand Glove	10
	2.3.2 Single Camera	12
	2.3.3 LEAP Motion Controller	13
2.4	Pattern Recognition and Feature Extraction	14
	2.4.1 Hidden Markov Model	14
	2.4.2 Grassmann Covariance Matrices	15
	2.4.3 K-Nearest Neighbors Modelling	16
	2.4.4 Support Vector Machine	17
	2.4.5 Finite State Machine	18
2.5	Hand Gesture Tracking	19

v

2.6	Related Previous Research	19
	2.6.1 American Sign Language Recognition Using LEAP Motion	20
	2.6.2 Hand Gesture Recognition with LEAP Motion and Kinect Devices	21
2.7	Summary	22
СНА	PTER 3 METHODOLOGY	23
3.1	Introduction	23
3.2	System Development	23
	3.2.1 Project Block Diagram	24
	3.2.2 Project Flow Chart	25
3.3	LEAP Motion Controller	27
	3.3.1 Operation Range	27
	3.3.2 Device Calibration	28
3.4	ASL Recognition Algorithm	29
	3.4.1 Coordinate System	30
	3.4.2 Motion Tracking Data	30
	3.4.3 Sensor Images	34
	3.4.4 Algorithm Development Process	34
	3.4.4.1 Software Preparation:	34
	3.4.4.2 Hand Features Extraction:	36
	3.4.4.3 Classification Model:	38

	3.4.4.4 Graphic User Interface Development:	40
3.5	American Sign Language Fingerspelling Letters Feature Points	41
3.6	Summary	52
СНА	APTER 4 RESULTS AND DISCUSSION	53
4.1	Preliminary Phase Results	53
4.2	American Sign Language Classification Results:	54
	4.2.1 Group 1: Closed-Hand Gesture Type Letters	54
	4.2.2 Group 2: Y-axis Alignment Type Letters	55
	4.2.3 Group 3: X-axis Alignment Type Letters	57
	4.2.4 Group 4: Gesture Type Movement	58
4.3	Classification Accuracy	60
	4.3.1 Alphabets	60
	4.3.2 Numbering	62
	4.3.3 Basic Gesture	63
4.4	Discussion	65
4.5	Summary	67
СНА	APTER 5 CONCLUSION AND FUTURE WORKS	68
5.1	Project Conclusion	68
5.2	Suggestion and Future Works	69
5.3	Summary	70

vii

REFERENCES	70
APPENDIX	75

LIST OF FIGURES

Figure 2.1 The hand sign gesture for Arabic Sign Language alphabets [3].	9
Figure 2.2 The hand sign language for Thai Sign Language alphabets [4].	10
Figure 2.3 The hand glove to translate sign language [5].	11
Figure 2.4 View from the desk-based tracking camera [2].	12
Figure 2.5 The hat-mounted camera, pointed downward toward the hands, and corresponding view [2].	the 13
Figure 2.6 LEAP Motion Controller internal structure [7].	14
Figure 2.7 The Overview of the hand gesture recognition process [8].	15
Figure 2.8 The method of SLR recognition by GCM representations on the Grassmanifold [9].	nan 16
Figure 2.9 Traffic Sign Classification with k-NN implementation [10].	17
Figure 2.10 Process Flow Chart of Dynamic Gesture Recognition [11].	18
Figure 2.11 The sign of letters that are not classified perfectly using k-NN and SV [7].	VM 21
Figure 2.12 The pipeline of the proposed approach [14].	22
Figure 3.1 Project Block Diagram.	25
Figure 3.2 Process Flow Chart for Phase I : Preliminary Phase.	25
Figure 3.3 Process Flow Chart for Phase II: Impementation and Testing Phase	26
Figure 3.4 Operating Range of the LMC.	27

Figure 3.5 Device Calibration Selection Screen.	28
Figure 3.6 Calibration of device in progress.	29
Figure 3.7 The calibration process was completed and successfully achieved a s of 84/100.	core 29
Figure 3.8 Coordinate System of LEAP Motion Controller.	30
Figure 3.9 The <i>Hand</i> palm_Normal and direction vectors define the orientation of hand.	f the 31
Figure 3.10 Finger tip_position and direction vectors provide the position of a fit tip and the general direction in which a finger is pointing.	nger 32
Figure 3.11 A Finger object provides a Bone object describing the position orientation of each anatomical finger bone.	and 33
Figure 3.12 A raw sensor image with superimposed calibration points.	34
Figure 3.13 Command line for checking the java version.	35
Figure 3.14 Eclipse Logo.	35
Figure 3.15 Feature Extraction of API Grab Strength.	37
Figure 3.16 Feature Extraction of API Pinch Strength.	37
Figure 3.17 Assigning LEAP API for each of the fingers.	37
Figure 3.18 Layered Classification Diagram.	38
Figure 3.19 GUI for the ASL translator.	40
Figure 4.1 The shape of hand that been detected by LMC.	55
Figure 4.2 Classification result for Letter 'B'	55
Figure 4.3 Classification result for Letter 'D'	56
Figure 4.4 Classification result for Letter 'F'	56
Figure 4.5 Classification result for Number '3'	56
Figure 4.6 Classification result for Letter 'C'	57

Х

Figure 4.7 Classification result for Letter 'G'	57
Figure 4.8 Classification result for Number '10'	58
Figure 4.9 Classification result for Gesture 'J'	58
Figure 4.10 Classification result for Gesture 'Z'	59
Figure 4.11 Classification result for Gesture 'Hi'	59
Figure 4.12 Classification result for Gesture 'Hmm'	59
Figure 4.13 Classification result for Gesture 'That's It'	60
Figure 4.14 The graph of Accuracy Percentage for Alphabets	62
Figure 4.15 The graph of Accuracy Percentage for Numbering	63
Figure 4.16 The graph of Accuracy Percentage for Basic Hand Gesture	64

C Universiti Teknikal Malaysia Melaka

LIST OF TABLES

Table 3.1 Tabulation of ASL Alphabets Hand Features	41
Table 3.2 Tabulation of ASL Number Hand Features	48
Table 3.3 Tabulation of ASL Basic Gesture Hand Features	51
Table 4.1 Tabulation of Classification Success Rate for Alphabets	60
Table 4.2 Tabulation of Classification Success Rate for Numbering	62
Table 4.3 Tabulation of Classification Success Rate for Basic Gesture	63

LIST OF SYMBOLS AND ABBREVIATIONS

For examples:

- LMC : LEAP Motion Controller
- ASL : American Sign Languages
- API : Application Programmer Interface
- GUI : Graphical User Interface
- SVM : Support Vector Machine
- HMM : Hidden Markov Models
- 3D : Three Dimension
- TOF : Time of Flight
- PMD : Photonic Mixer Device
- TCP : Tool Control Point
- IR : Infrared
- K-NN : K- Nearest Neighbour
- SDK : Software Developer Kit
- HTML5 : Hypertext Markup Language 5
- FSM : Finite-State Machine

LIST OF APPENDICES

Appendix A: ASL Fingerspelling Alphabet Chart	74
Appendix B: ASL Fingerspelling Number Chart	75
Appendix C: ASL Fingerspelling Basic Gesture Chart	76
Appendix D: Coding	77

CHAPTER 1

INTRODUCTION

1.1 Background Study

Speech Impairment is a form of disabilities faced by a minor group of the society. By having this disabilities, it will make them hard to communicate with the rest of society, nevertheless, it will make them more difficult to express their message. This project was proposed to break the barrier between the disability group and with all the society by translating the sign language (American Sign Language) into readable English text. This project suggests the use of LEAP Motion Controller (LMC) to identify the hand gestures and movement of a person that communicate his/her message using sign language.

1.2 Problem Statement

Speech Impairment people are group that often facing difficulties to communicate effectively with the favored people as most of them do not know how to interpret sign language. This will not only form a hurdle between them and the rest of the community in term of socialization but also influenced their working chances. Thus, a system that capable of translating sign, language into written text is crucial to smoothen the communication between those who are fortunate and those who are unlucky.

Even though the sign language recognition can also be done using the camera that using the image processing technology, using LEAP Motion Technology will have a better advantage because LMC does not depends on the outdoor light intensity. Normal camera will have such a difficulty in capturing images when the surrounding light intensity in under certain values. By using LMC, this kind of problem can be solve because LMC are using the infrared sensing.

From previous research, LMC are not easily to track gesture in their translation because gesture have a motion tracking in that. Some of ASL have a gesture in their sign language like letter 'J' and 'Z'. So, a system that are able to recognize not only a pose sign language, a gesture also can be translated by the technology. It will help the unfortunate people to use this technology easily in the future.

1.3 **Objectives**

The objectives were set as main goal for the project to be achieved:

- i. To analyze the hand gesture and the movement involved in sign language used by the disabled group.
- ii. To implement LEAP Motion technology in the hand gesture and movement recognition.
- To design an application that can translate the sign language into English text.

1.4 Scope of Project

The scope of the project was a few of limitation and boundary range for the research work and for the project itself. Firstly, American Sign Language (ASL) was chosen as the target sign language because dialects of ASL and ASL-based creoles are used in many countries around the world, including much of West Africa and parts of Southeast Asia. ASL is also widely learned as a second language, serving as a lingua franca.

Secondly, English are the target language to be translated into. It is because we all know that English is the one language that well-known throughout the world. So, it will be easier for them to understand it.

Thirdly, my target group for this project is the one that having speech and hearing impairment. This groups is the most commonly user for the sign language. So, by targeting this group is much simple compare to other disabilities. Last but not least, we are using basic alphabet, numbers and basic gesture in ASL to put into the library.

1.5 Project Significance

The fundamental concept of this project is to convert the commonly used hand language, which is the American sign language into readable English text. By using motion sensing technology such as LEAP Motion Controller, the pattern recognition of hand gesture becomes more achievable.

The speech impairment community is constant having problem when they try to communicate with the rest of the society, as normal people are not hand sign language literate. Thus, by converting the hand sign language, natural language of deaf people to readable English text, a world-wide spoken language, is capable to minimize the obstacle faced by the deaf people in communication. So, upon commercialization, this project have a good future to have a significant good impact on the society, especially for the hearing and speech impairment community.

One of the advantages of this project including the breaking of the invisible blockade of communication as it allows fortunate people to understand the hand sign language expressed by the deaf people. This minor group shall no longer have problem to express their message to the normal people. This can indirectly rise the employment chances as many of the deaf people cannot present themselves to the employer well because the employer cannot understand what they try to convince.

In addition, the successful implementation of the project will help the learning of the sign language. There are a significant portion of hearing impairment group is not born with hearing defectiveness. They also can get this problem from illness or accident. So, they also need to learn the hand sign language. Therefore, by using this project, the education of hand sign language will become much easier, and it will help to self-learning of the hand sign language.