

PJP/2011/FTK(9A)/S00959

**DESIGN AND DEVELOPMENT OF GREEN ELECTRICITY GENERATION
SYSTEM USING OCEAN SURFACE WAVE FOR SMALL SCALE
APPLICATION**

MOHD FARRIZ BIN MD BASAR

**FAKULTI TEKNOLOGI KEJURUTERAAN
UNIVERSITI TEKNIKAL MALAYSIA MELAKA**

2011

ABSTRACT

Non-renewable energy such as petroleum, coal, gas and nuclear cannot be restored once it has been used. Many countries in the world are heavily dependent on the non-renewable energy and polluting sources to generate electricity. This would cause the greenhouse gas emissions and would have adverse effects on the country due to climate changes. Generally, approximately 75% of earth is covered by the ocean and for that reason, many investors starting to develop a technology for harnessing the ocean wave. Wave energy is a form of renewable energy available on the earth where converting the ocean wave energy into electricity. In this project, it will study and develop the "Portable Power Supply from Wave Energy". Therefore, it will employ a basic concept of Faraday's Law. Wave energy is use as a prime mover for this project where it helps the solenoid to move right and left of permanent magnet to generate electricity. The magnetic field of magnets is cut by the solenoid and current is induced in the coil. The amount of induces current is depends on the number of wire turns, the number and the strength of magnet and the relative movement of magnet. Thus, this project is attempted to use a permanent magnet (Neodymium Iron Boron) and solenoid with 4000 turns of wire turns. The movement of wave will cause solenoid move to the right and move to the left of permanent magnet and cuts the magnetic fields and simultaneously produce alternating current (AC) voltage and then convert to direct current (DC) by using voltage multiplier. It is therefore, this project is very useful to supply electricity for small load such as LED lighting for outdoor activities likes camping and picnic.

TABLE OF CONTENTS

CHAPTER	TITLE	PAGE
	ABSTRACT	ii
	TABLE OF CONTENTS	iii
	LIST OF TABLES	v
	LIST OF FIGURES	vi
	LIST OF APPENDICS	vii
 1	 INTRODUCTION	 1
	1.1 Project Background	1
	1.2 Problem Statement	2
	1.3 Objective	3
	1.4 Scope of Project	3
 2	 LITERATURE REVIEW	 4
	2.1 Ocean Wave Energy	4
	2.1.1 Ocean Wave Characteristic	5
	2.1.2 Ocean Wave Energy Technologies	7
	2.1.2.1 Terminator	9
	2.1.2.2 Attenuators	10
	2.1.2.3 Points Absorbed	11
	2.2 Magnet	12
	2.2.1 Characteristic of Permanent Magnet	14
	2.2.2 Selection of Permanent Magnet	15
	2.2.3 The Care of Permanent Magnet	16
 3	 METHODOLOGY	 21
	3.1 Research Methodology and Experimental Work	21
	3.2 Full Scale Model	24

3.3	Project Planning	25
4	RESULTS	27
4.1	Preliminary Testing by Using 19 SWG Enamelled Copper Wire	27
4.2	Preliminary Testing by Using 25 SWG Enamelled Copper Wire	32
4.3	Voltage Multiplier	36
4.4	Simulation	37
4.5	Full Scale Model Testing	38
4.6	Field Testing at Pantai Puteri, Melaka	40
5	ANALYSIS AND DISCUSSION	43
5.1	Analysis	43
5.2	Discussion	56
5.3	Suggestion	56
6	CONCLUSION	57
	REFERENCES	58
	APPENDIX A	59
	APPENDIX B	60

LIST OF TABLES

TABLE	TITLE	PAGE
2.1	Special Characteristics of Permanent Magnet	14
2.2	Comparison between Four Types of Permanent Magnet Material	16
3.1	Project Planning	26
4.1	Induced Voltage and Current during 100 Turns of 19 SWG Wire	29
4.2	Induced Voltage and Current during 200 Turns of 19 SWG Wire	29
4.3	Induced Voltage and Current during 300 Turns of 19 SWG Wire	29
4.4	Induced Voltage and Current during 400 Turns of 19 SWG Wire	30
4.5	Induced Voltage and Current during 500 Turns of 19 SWG Wire	30
4.6	Induced Voltage and Current during 600 Turns of 19 SWG Wire	30
4.7	Induced Voltage and Current during 700 Turns of 19 SWG Wire	31
4.8	Induced Voltage and Current during 800 Turns of 19 SWG Wire	31
4.9	Induced Voltage and Current during 900 Turns of 19 SWG Wire	31
4.10	Induced Voltage and Current during 1000 Turns of 19 SWG Wire	32
4.11	Induced Voltage and Current during 100 Turns of 25 SWG Wire	32
4.12	Induced Voltage and Current during 200 Turns of 25 SWG Wire	33
4.13	Induced Voltage and Current during 300 Turns of 25 SWG Wire	33
4.14	Induced Voltage and Current during 400 Turns of 25 SWG Wire	33
4.15	Induced Voltage and Current during 500 Turns of 25 SWG Wire	34
4.16	Induced Voltage and Current during 600 Turns of 25 SWG Wire	34
4.17	Induced Voltage and Current during 700 Turns of 25 SWG Wire	34
4.18	Induced Voltage and Current during 800 Turns of 25 SWG Wire	35
4.19	Induced Voltage and Current during 900 Turns of 25 SWG Wire	35
4.20	Induced Voltage and Current during 1000 Turns of 25 SWG Wire	35

LIST OF FIGURES

FIGURE	TITLE	PAGE
2.1	Shape of Ocean Wave	4
2.2	Characteristic of Idealized Wave	6
2.3	Schematic Representation of Various Types Wave Energy Converter	7
2.4	Generator Assembly Sketch	8
2.5	Oscillating Water Column	9
2.6	Pelamis Wave Energy Converter	10
2.7	Aqua Buoy Point Absorber Wave Energy	11
2.8	Direction of Induced Current	13
2.9	Neodymium Iron Boron (NdFeB) Magnet	17
2.10	Samarium Cobalt (SmCo) Magnet	18
2.11	Alnico Magnet	19
2.12	Ceramic or Ferrite Magnet	20
3.1	Project Methodology	22
3.2	Full Scale Mode	24
4.1	Enamelled Copper Wire (19 SWG)	27
4.2	Neodymium Iron Boron Magnet	27
4.3	Preliminary Model Setup	28
4.4	Half Wave Rectifier	36
4.5	Full Wave Rectifier	36
4.6	Voltage Multiplier Circuit	37
4.7	Simulation Result	38
4.8	Actual Model Setup	39
4.9	Preliminary Testing	39
4.10	Full Scale Model Setup	41
4.11	Real testing on Ocean Wave	42
4.12	Real testing on Ocean Wave	42
5.1	Induced Voltage Obtained During 100 Turns of Wire without Load	44
5.2	Induced Current Obtained During 100 Turns of Wire without Load	45
5.3	Induced Voltage Obtained During 200 Turns of Wire without Load	45
5.4	Induced Current Obtained During 200 Turns of Wire without Load	46

5.5	Induced Voltage Obtained During 300 Turns of Wire without Load	46
5.6	Induced Current Obtained During 300 Turns of Wire without Load	47
5.7	Induced Voltage Obtained During 400 Turns of Wire without Load	47
5.8	Induced Current Obtained During 400 Turns of Wire without Load	48
5.9	Induced Voltage Obtained During 500 Turns of Wire without Load	48
5.10	Induced Current Obtained During 500 Turns of Wire without Load	49
5.11	Induced Voltage Obtained During 600 Turns of Wire without Load	49
5.12	Induced Current Obtained During 600 Turns of Wire without Load	50
5.13	Induced Voltage Obtained During 700 Turns of Wire without Load	50
5.14	Induced Current Obtained During 700 Turns of Wire without Load	51
5.15	Induced Voltage Obtained During 800 Turns of Wire without Load	51
5.16	Induced Current Obtained During 800 Turns of Wire without Load	52
5.17	Induced Voltage Obtained During 900 Turns of Wire without Load	52
5.18	Induced Current Obtained During 900 Turns of Wire without Load	53
5.19	Induced Voltage Obtained During 1000 Turns of Wire without Load	53
5.20	Induced Current Obtained During 1000 Turns of Wire without Load	54
5.21	Induced Voltage in Difference Number of Wire Turns without Load	55
5.22	Induced Current in Difference Number of Wire Turns without Load	55

LIST OF APPENDICES

APPENDIX	TITLE	PAGE
A	Copper Enamelled Wire	59
B	Magnetic Characteristic and Physical Properties of NdFeB	60

CHAPTER 1

INTRODUCTION

1.1 Project Background

This project is all about the “Portable Power Supply from Wave Energy”. The term of “portable” meaning that the product of this project is easily to moveable anywhere because of the size is small. This portable power supply is able to produce electricity where it can be use for military purposes or for the outdoor activities such as picnic and camping.

There are two types of energy source in the world which non-renewable energy and renewable energy. Once a non-renewable energy source is used, it cannot be replace but renewable energy source is one that can be replacing and it is good for our environments. The term of “renewable” referred to its energy because it does not finish even though it is use regularly. This energy has a few advantages than non-renewable energy such as the energy is free because its form natural resources, it’s clean to the environment and cheaper. There are many types of renewable energy available on earth but the ocean wave is one which growing up recently according to the research and development to harnessing their energy.

This project intended to generate electricity by using wave energy with the aid of solenoid and permanent magnet. The literature review is cover about the permanent magnet, copper wire, ocean wave and previous study on ocean wave.

The preliminary model setup has been constructed to understand and verify the system principle which permanent magnet and solenoid can generate electricity. The basic idea to generate electricity is form Faraday’s Law where the magnetic fields of permanent magnet is cut by solenoid. A few shape of permanent magnet and various number of wire

turns are used in this testing. Some analysis and discussion need to be done after preliminary testing completed.

The full-scale model has been developing as a real model of a wave energy device. This model was tested in a real situation. So that, harvesting the ocean wave energy and convert it to the electricity power.

1.2 Problem Statement

This project is constructing based on a few problem statement. Firstly, is about the non-renewable energy. Nowadays, power plants use sources such as diesel, coal and gas. Once these are burned to generate electricity, their energy is lost forever. It is thought that the current resources for oil and gas under the North Sea will last about another 20 years and the world resources will last for about 70 years. Even though the world has relatively larger reserve for coal but it is expected that the coal can be lasting only for the next century [9]. For that reason, developing an alternative energy is must for future demand.

Besides that, the oil price has increased up to \$100.00 per barrel and all countries anxious with this situation [10]. Therefore, to solve this oil prices crisis, the ocean wave is used as the alternative energy to generate electricity.

Next, the problem associated with fossil fuels uses are that the extraction of fossil fuel causes local environment problem including damage to land surface, noise, dust, acid rain and pollution [11]. In order to reduce this effect, the wave energy is harnessing to obtain a green energy for electricity.

An additional, the past research and product has a bulky size and apply on the open sea only. It is fixed design and unremoveable product. Therefore, to make the product more comfortable and convenient, this project has an advantages because of it size is small and allocate at the seaside.

The old design of the product is much expensive compare with the proposed one because it use a lot of materials and the materials is in biggest size which required high

cost to build it. Compare with the new one, it is cheaper because the material used is not much and more simply than the old one.

1.3 Objective

The objectives of this project are:

1. To generate induced current with the aid of magnet and solenoid
2. To analyze the effect of magnet, solenoid and relative movement of magnet to the electrical characteristics
3. To develop a hardware for harnessing the wave energy.

1.4 Scope of Project

In order to achieve the project objectives, the following scopes will be covered:

1. Studies the literature reviews about the magnet, copper wire, ocean wave and previous study on ocean wave.
2. Identifies the circuits and components and procurement of components and materials.
3. Conduct a preliminary testing by using various shapes of permanent magnet and number of wire turns to understand and verify the system principle.
4. Construct the full scale model by using wave energy to generate electricity.

Studying the literature reviews about the magnet, copper wire, ocean wave and previous study on ocean wave is a very fundamental in order to develop a full scale system for harnessing the wave energy. Next, circuits and components that are used need to be identified and then procurement of components and material should be done. In addition, the preliminary testing is constructed by using various shapes of permanent magnet and numbers of wire turns to understand and verify the system principle. Finally, the full scale model has been constructed and tested by using wave energy to generate electricity.

CHAPTER 2

LITERATURE REVIEW

2.1 Ocean Wave Energy

Ocean has a sinusoidal waveform where the highest peak is called crest and lowest part is called troughs. The difference in height between peaks and troughs is known as height, H and the distance between successive peak (or troughs) of wave is known as a wavelength, λ [1]. The wave period T is the time interval between passage of successive crests at a stationary points. The shape of ocean wave is shown in Figure 2.1 below:



Figure 2.1: Shape of Ocean Wave

Waves are generated when wind passing over the sea. There is an energy transfer from the wind to the most of wave when the waves propagate slower than the wind speed. Waves growth happened when there are difference in both air pressure between the upwind and the lee side of a wave crest.

Wave height is depends on a few factor such as wind speed, time duration the wind has been blowing and water depth. Wave size is determined by wind speed and fetch and by the depth and topography of the seafloor. A given wind speed has a matching practical limit over which time or distance will not produce larger waves. This limit is called a “fully developed sea” [7].

There are three type of wind wave which is capillary waves or ripples, sea and swells. Ripples appear on smooth water when the wind blowing but it will die quickly if there is no wind. The irregular motions under sustained winds as called sea and they much longer than the ripples even after the wind is died. Swells are created when seas propagate away from their area of origin.

2.1.1 Ocean Wave Characteristic

The wave power is determined by wave speed, wavelength and water density. Usually, when the wave is larger we can say that the wave is more powerful than the smaller one.

As mention in previous section, we can suppose that the peaks and troughs of ocean wave move across the surface with the velocity, v and time in seconds is taken for successive peaks (or troughs) is known as the period, T . When the waves travel at velocity v , it will travel a distance that it's equal to its wavelength λ in a time equal to the wave period T . So, the velocity v is equal to the wavelength λ divided by the period of T . The mathematically equation can be express in Equation 2.1 below:

$$v = \frac{\lambda}{T} \quad (2.1)$$

In deep water waves, if the water is greater than the half of its wavelength, the velocity of ocean wave can be express in Equation 2.2:

$$v = \frac{gT}{2\pi} \quad (2.2)$$

The properties of the waves is increases by water depth when the water become shallower and when it reach shallow water, their properties are completely is taken by the water depth but for the intermediate depths the properties of the waves is influenced by both water depth d and water period T . When the waves approach the shore, the seabed starts to have an effect on their speed and this can be show if the water depth d is less than a quarter of the wavelength. The current velocity in this stage is shown in Equation 2.3 below:

$$v = \sqrt{gd} \quad (2.3)$$

The characteristic of an idealized wave is shown in Figure 2.2 below:

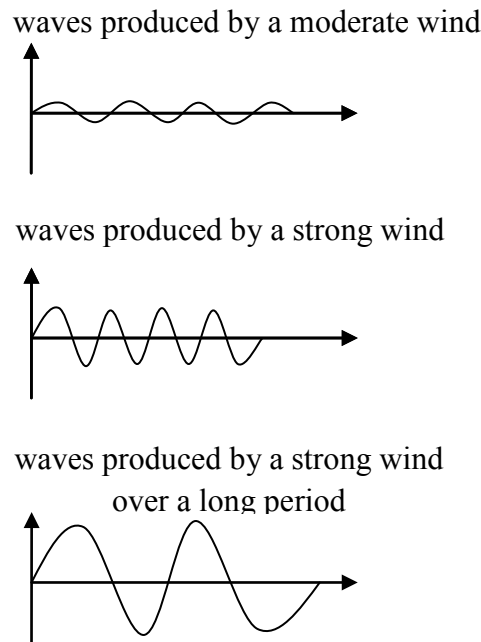


Figure 2.2: Characteristic of Idealized Wave

Wave energy is depends on wind speed, time duration of the wind blowing, the distance of open water that the wind has blown over and water depth. Wave power could be determined by wave height, wavelength and water density [2]. This mathematically could be described as in Equation 2.4 [3].

$$P = \frac{\rho g^2 T H^2}{32\pi} \text{ watt per meter} \quad (2.4)$$

where;

- ρ : the density of seawater (kg/m^3)
- g : acceleration due to gravity (m/s^2)
- H : wave height (m)
- T : period of wave (s)

The amount of energy available in a given wave can be expressed in terms of energy density or energy flux \bar{E} [2]. The SI unit is used and the energy density units is Joules per meter squared. The Equation 2.5 below has shown the equation of energy density or energy flux:

$$\bar{E} = \frac{\rho g H^2}{8} \quad (2.5)$$

where; ρ : density of seawater (kg/m^3)
 g : acceleration due to gravity (m/s^2)
 H : wave height (m)

2.1.2 Ocean Wave Energy Technologies

In order to capture energy from sea waves, variety of technologies has been used to harnessing the wave energy to convert into useful electrical energy. However, each is in too early a stage of development to predict which technology or mix of technologies would be most prevalent in future commercialization [3].

Wave energy converter is devices that can be convert the wave energy to electrical energy which it is central, stable structure and have some active part which moves relative to it under the force of the waves. There are many different configuration of wave energy converter and a number of ways of classifying them have been proposed. One schematic representation of the various types wave energy converter is shown in Figure 2.3 below [1].

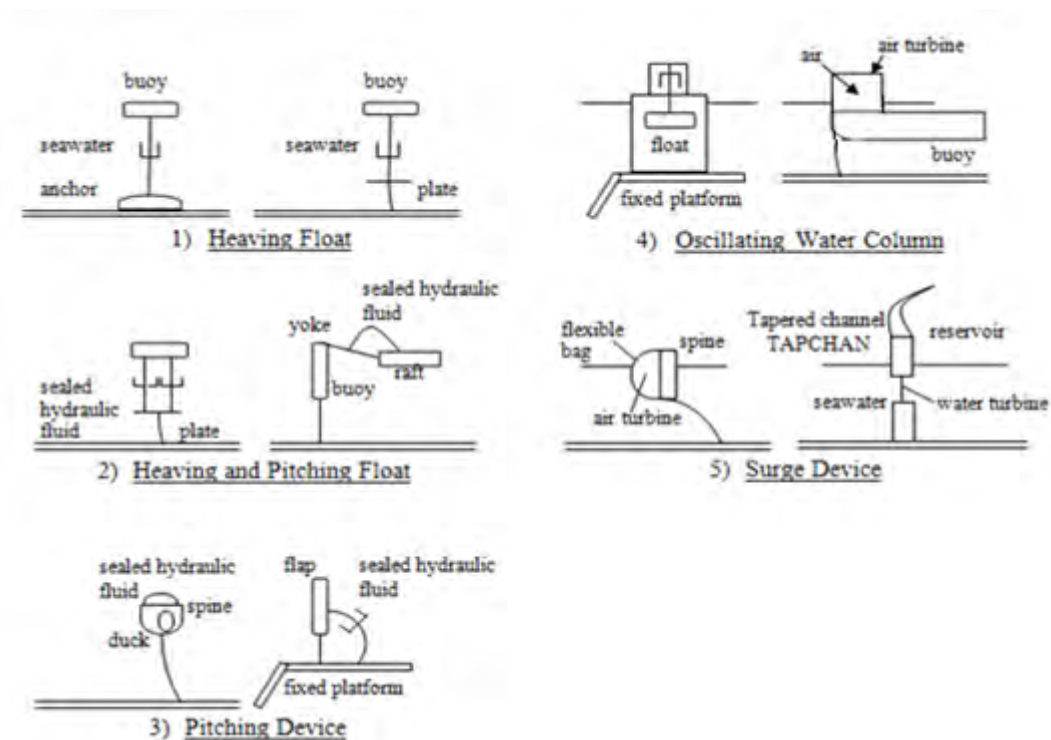


Figure 2.3: Schematic Representation of Various Types Wave Energy Converter

Wave energy converters can be classified in terms of their location [1]:

- a) Fixed to the seabed, generally in shallow water.
- b) Floating offshore in deep water or
- c) Tethered in intermediate depths

According to the paper “Numerical Modeling of the Electric Linear Generator Based on the Sea Wave Energy”, permanent magnet linear generator can be used as to producing electrical energy based on clean resources, such as sea waves energy. These generators have special features in comparison with other types of electric generators. They take the advantage of renewable energy resources such as it’s do not pollute the environment, have to be water-proofed, and can be built in a range of various powers without having geometrical dimensions limitations [4].

The operating principle of this project is simple where there is an armature with permanent magnet at the central of their designed. The armature will anchored to the sea floor, and the floater moves the permanent magnet relative to the fixed armature coils to induce voltage. In Figure 2.4 below, it show the sketch of the entire system. Part number 1 show the translating armature, part number 2 is a fixed armature with coils, part number 3 is a shaft, part number 4 is a fixing pillar, part number 5 is a buoys/floater, part number 6 is a rope and part number 7 is a spring.

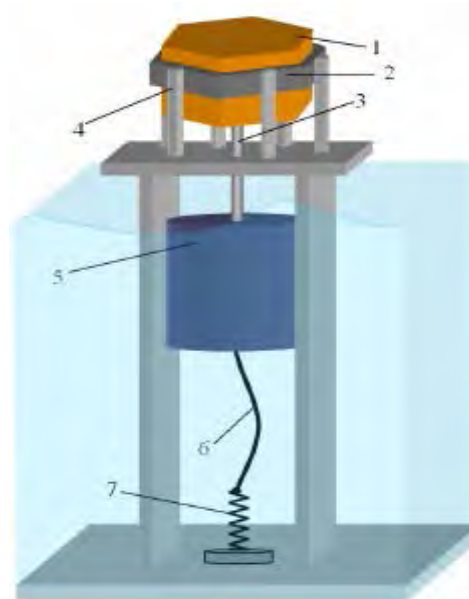


Figure 2.4: Generator Assembly Sketch

Otherwise, the wave energy converter can be divided into three categories based on their geometry and orientation such as terminator, attenuators and point absorbers.

2.1.2.1 Terminator

Terminator devices extend perpendicular to the direction of wave travel and capture or reflect the power of the wave. These devices are typically installed onshore or nearshore. However, floating versions have been designed for offshore applications. The oscillating water column (OWC) is an example form of terminator in which water enters through a subsurface opening into a chamber with air trapped above it. The wave action causes the captured water column to move up and down like a piston to force the air through an opening connected to a turbine. A full-scale, 500-kW, prototype OWC designed and built by Energetech in year 2006 shown in Figure 2.5 and it is undergoing testing offshore at Port Kembla in Australia, and a further project is under development for Rhode Island [3].

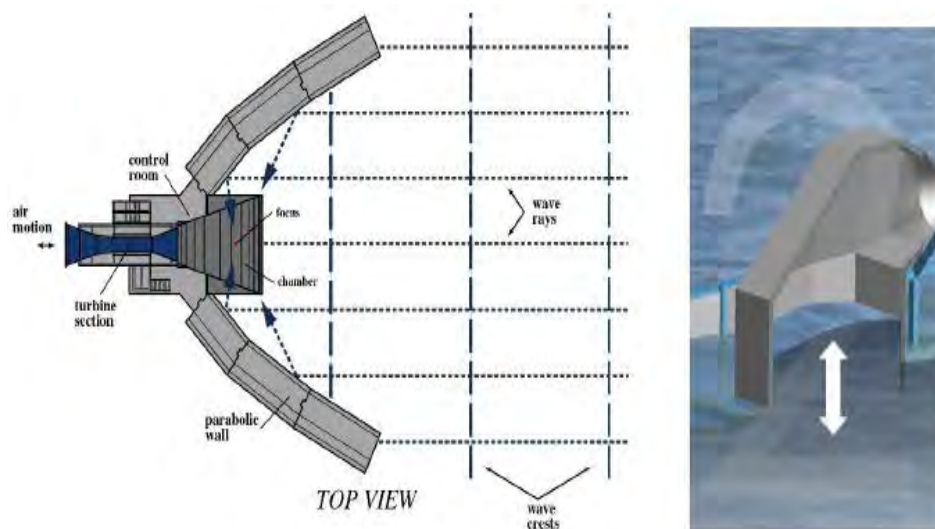


Figure 2.5: Oscillating Water Column [3]

In an Electric Power Research Institute (EPRI), a design, performance, and cost assessment was conducted for an Energetech commercial-scale OWC with a 1,000-kW rated capacity, sited 22 km from the California shore. With the wave conditions at this site (20 kW/m average annual), the estimated annual energy produced was 1,973 MWh/yr. For a scaled-up commercial system with multiple units producing 300,000 MWh/yr, the estimated cost of electricity would be on the order of \$0.10/kWh [3].

2.1.2.2 Attenuators

Attenuators are long multisegment floating structures oriented parallel to the direction of the wave travel. The differing heights of waves along the length of the device causes flexing where the segments connect, and this flexing is connected to hydraulic pumps or other converters [3]. The example of attenuators is Pelamis by Ocean Power Delivery, Ltd.

The Pelamis is a semi-submerged machine, articulated structure composed of cylindrical sections linked by hinged joints. The wave-induced motion of these joints is resisted by hydraulic rams, which pump high-pressure oil through hydraulic motors via smoothing accumulators. The Pelamis contains three Power Conversion Modules, each rated at 250kW (sea tested for 1000 hours in 2004).

The first stage, scheduled to be completed in 2006, consists of three Pelamis machines with a combined rating of 2.25 MW to be sited about 5 km off the coast of northern Portugal. An expansion to more than 20-MW capacity is being considered.

A Pelamis powered 22.5-MW wave energy facility is also planned for Scotland, with the first phase targeted for 2006 [3]. Figure 2.6 below show the Pelamis Wave Energy Converter.

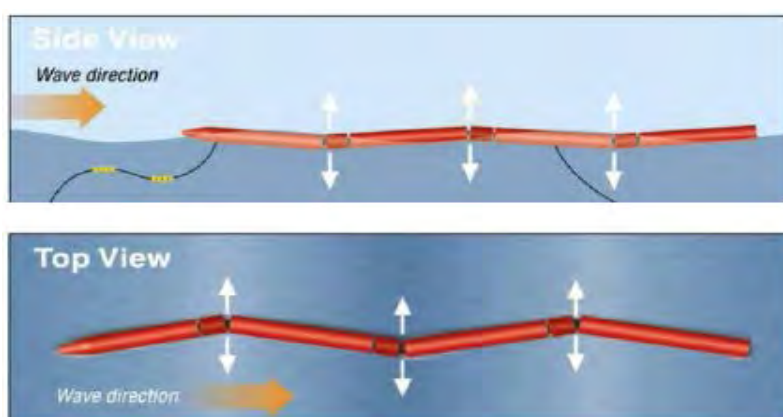


Figure 2.6: Pelamis Wave Energy Converter [3]

2.1.2.3 Points Absorbed

Point absorbers have a small horizontal dimension compared with the vertical dimension and utilize the rise and fall of the wave height at a single point for wave energy converter. One of example of this points absorbed is Aqua Buoy.

The Aqua Buoy being developed by the AquaEnergy Group, Ltd. In year 2005 this point absorber is the third generation of two Swedish designs that utilize the wave energy to pressurize a fluid that is then used to drive a turbine generator. The vertical movement of the buoy drives a broad, neutrally buoyant disk acting as a water piston contained in a long tube beneath the buoy. The water piston motion in turn elongates and relaxes a hose containing seawater, and the change in hose volume acts as a pump to pressurize the seawater. The Aqua Buoy design has been tested using a full-scale prototype, and a 1-MW pilot offshore demonstration power plant is being developed offshore at Makah Bay, Washington. The Makah Bay demonstration will include four units rated at 250 kW placed 5.9 km offshore in water approximately 46 m deep [3]. The Aqua Buoy Point Absorber Wave Energy Converter is show in Figure 2.7 below.

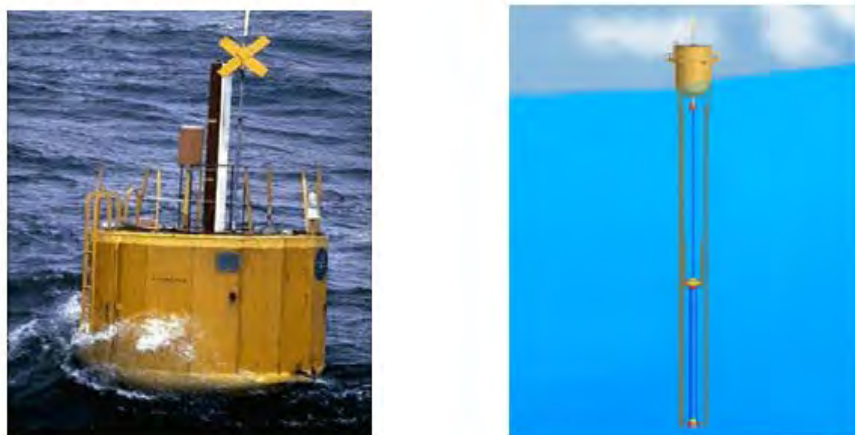


Figure 2.7: Aqua Buoy Point Absorber Wave Energy [3]

2.2 Magnet

Magnet is a material or object that produces a magnetic field. The magnet has at least two poles where it is North Pole and South Pole. Magnet that has same pole (N-N or S-S) will repelled to each other but when they has difference pole (N-S or S-N) they will attracted to each other.

The magnetic fields of magnet are invisible but we can see them in when scatter the iron filing around the magnet. The lines that created by iron filing are called magnetic field which they leave the North Pole and enter the South Pole of magnet. Inside the magnet, the field line travels from South Pole to North Pole. Magnetic field will strong when the field lines are close together and become weak if the field lines are far away from one another.

There are three type of magnetism such as ferromagnetism, diamagnetism and paramagnetism. Ferromagnetism is a material that when we placed it near a magnet, it will be attracted toward the region of greater magnetic field. Example for this material is iron, cobalt, nickel, gadolinium, dysprosium and alloys. Diamagnetism is a material that when we placed it near a magnet, it will be repelled from the region of grater magnetic field such as copper, gold, silver and lead. Paramagnetism is a material that when we placed it near a magnet, it will be attracted to the region of greater magnetic field. The difference paramagnetic and ferromagnetic material is that the attraction of paramagnetic material is weak than ferromagnetic material.

The magnet is employing concept of electromagnetic induction such as Faraday's Law, Lenz's Law and Fleming's Right-Hand Rule. The Faraday's Law is a basic law of electromagnetism where this law states "The induced electromotive force or EMF in any closed circuit is equal to the time rate of change of the magnetic flux through the circuit". Equation 2.6 below shows the equation of Faraday's Law [12]:

$$|\mathcal{E}| = \left| \frac{d\Phi_B}{dt} \right| \quad (2.6)$$

where: $|\mathcal{E}|$ = magnitude of the electromotive force (EMF) in volts

Φ_B = magnetic flux through the circuit (in webers)

The direction of the induced electromotive forces or EMF and current is given by Lenz's Law where the law states "An induced current is always in such direction as to oppose the motion or change causing it". In the other words this law state that the induced EMF and the change in flux have opposite signs of Faraday's Law. The Fleming's Right-Hand Rule shows the direction induced current flow when a conductor moves in magnetic fields. The right hand is held with the thumb, first finger and second finger mutually perpendicular to each other. The direction of induced current is shown in Figure 2.8 below [13]:

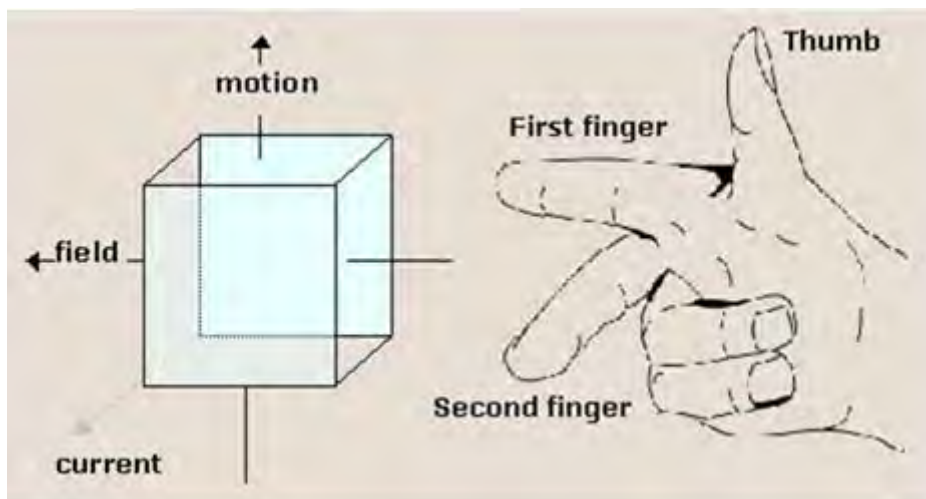


Figure 2.8: Direction of Induced Current

The tens facts of magnet are show in below [8]:

- 1) North Poles point north, South Pole point south
- 2) Like pole repel, unlike pole attract
- 3) Magnetic forces attract only magnetic materials
- 4) Magnetic forces acts at a distance
- 5) While magnetized, temporary magnet acts like permanent magnet
- 6) A coil of wire with an electric current flowing through it becomes a magnet
- 7) Putting iron inside a current carrying coil increases the strength of the electromagnet
- 8) A changing magnetic field induces an electric current in a conductor
- 9) A charged particle experiences no magnetic force when moving parallel to a magnetic field, but when it is moving perpendicular to the field it experiences a force perpendicular to both the field and the direction of motion.

- 10) A current carrying wire in a perpendicular magnetic field experiences a force in a direction perpendicular to both the wire and the field.

There are three main types of magnet such as permanent magnet, temporary magnet and electromagnet. Permanent magnets are use for this project and there are four classes of permanent magnets such as Neodymium Iron Boron (NdFeB), Samarium Cobalt (SmCo), Alnico and Ceramic or Ferrite.

2.2.1 Characteristic of Permanent Magnet

The permanent magnet has a characteristic just like another magnet. The special characteristic of four classes of permanent magnet is shown in Table 2.1 below [8]:

Table 2.1: Special Characteristics of Permanent Magnet

Material	Br	Hc	BHmax	Tcoef of Br	Tmax	Tcurie
NdFeB	12,800	12,300	40	-0.12	150	310
SmCo	10,500	9,200	26	-0.04	300	750
Alnico	12,500	640	5.5	-0.02	540	860
Ceramic	3,900	3,200	3.5	-0.20	300	460

- Br** - measure of its residual magnetic flux density in Gauss, which is the maximum flux the magnet, is able to produce.
- Hc** - measure of the coercive magnetic field strength in Oersted, or the point at which the magnet become demagnetized by an external field.
- BHmax** - term of overall energy density. The higher the number, the more powerful the magnet.
- Tcoef of Br** - temperature coefficient of Br in terms of % per degree Centigrade.
- Tmax** - maximum temperature the magnet should be operated at. After the temperature drop below this value, it will still behave as it did before it reached that temperature.

T_{curie} - Curie temperature at which the magnet will become demagnetized. After the temperature drop this value, it will not behave as it did before it reached that temperature.

2.2.2 Selection of Permanent Magnet

Before start the project, selection of magnet is most important that needs to be considered. This is including:

- i. Magnetic properties
- ii. Corrosion resistance
- iii. Material cost and
- iv. Maximum operating temperature

A good permanent magnet should produce a high magnetic field with a low mass and should be stable against the influences which would demagnetize it. The desirable properties of such magnet are typically stated in terms of remanence and coercive of the magnet material [6].

Alnico, Nd₂Fe₁₄B and SmCo magnet are classified as the rare earth permanent magnets and can produce largest magnetic flux with the smallest mass. Table 2.2 shows the comparison between four types of permanent magnet material [6].

Table 2.2: Comparison between Four Types of Permanent Magnet Material

	Lowest	Low	High	Highest
Cost	Ferrite	Alnico	Nd ₂ FeB ₁₄	SmCo
Energy	Ferrite	Alnico	SmCo	Nd ₂ FeB ₁₄
Operating Temperature	Nd ₂ FeB ₁₄	Ferrite	SmCo	Alnico
Corrosion Resistance	Nd ₂ FeB ₁₄	SmCo	Alnico	Ferrite
Resistance to Demagnetization	Alnico	Ferrite	Nd ₂ FeB ₁₄	SmCo
Mechanical Strength	Ferrite	SmCo	Nd ₂ FeB ₁₄	Alnico
Temperature Coefficient	Alnico	SmCo	Nd ₂ FeB ₁₄	Ferrite

A rare earth permanent magnet, Nd₂Fe₁₄B is chosen as a component for this project based on number of considerations especially in terms of producing high energy product. The physical, mechanical and magnetic properties of the magnet such as thermal conductivity, specific heat, electrical resistivity and magnetic flux density which are affected by temperature are investigated. Nd₂Fe₁₄B magnet is selected due to its high energy at its maximum operating temperature [6].

2.2.3 The Care of Permanent Magnet

When deal with magnet, there are four areas that must be concerned depending on their classes such as mechanical shock, heat, moisture and demagnetizing fields. The Neodymium Iron Boron (NdFeB) in Figure 2.9 is a strongest permanent magnet today and need a few experiences to play with it. They are usually use in headphones, disk drives, new toys and all over the place. The areas must be concerned is: