SUPERVISOR DECLARATION

"I hereby declare that I have read this thesis and in my opinion this thesis is sufficient in terms of scope and quality for the award of the degree of Bachelor of Mechanical Engineering (Plant & Maintenance)"

Signature	:
Name	: DR NOR SALIM BIN MUHAMMAD
Date	:



EFFECT OF SIZE PZT ELEMENTS ON THE EXCITATION OF PHASED ARRAY TRANSDUCER IN BEAM STEERING AND BEAM FOCUSING TECHNIQUE

MUHAMMAD SHAZWAN BIN ABDUL RAZAK

A thesis submitted in partial fulfilment of the requirement for the award of the degree of Bachelor of Mechanical Engineering (Plant & Maintenance)

> Faculty of Mechanical Engineering Universiti Teknikal Malaysia Melaka

> > **JUNE 2015**

C Universiti Teknikal Malaysia Melaka

DECLARATION

"I hereby declare that the work in this thesis is my own except for summaries and quotation which have been duly acknowledged"

Signature	:
Name	: MUHAMMAD SHAZWAN BIN ABDUL RAZAK
Date	:

Dedicated to my parents, Abdul Razak bin Hussain and Zaiton binti Ramli My supporting siblings, Muhammad Shamier bin Abdul Razak Muhammad Shauqi Izham bin Abdul Razak and Nur Hidayah binti Abdul Razak and My entire friends in UTeM

for their encouragement.

ACKNOWLEDGEMENT

I would like to express my gratitude and respect to my supervisor,

Dr. Nor Salim bin Muhammad

for the guidance and assistance throughout this project.

My deepest gratitude is to my parents and my siblings for always staying on my side. Their constant support, encouragement, love and patience

gave me security and sustained me through my journey.

I also would like to acknowledge anyone who has supported me in anyway

during my four years degree studies at

Universiti Teknikal Malaysia Melaka, UTeM.

ABSTRACT

Ultrasonic testing has widely used in industry for defect evaluation. However this technique has several limitations such as fixed beam separator and mechanical scanning. These limitations can be solved by using phased array technique which used multiple element of arrangement with time delay that can be steering of focusing. A study is being carried out to study the effect of size PZT element on the excitation of phased array transducer. Several design parameters of phased array model need to be considered such as number of elements, distance between elements, frequency, and aperture size affect the excited beam of transducer. The guided wave with different modes which is symmetrical and anti-symmetrical is used as a principle to propagate wave in large structured using a single fixed point. Simulation of aluminium plate without defect for beam steering and beam focusing with time delay is being modelled using ABAQUS software. The visualization of wave propagation on defect is observed and compared with the different model.

ABSTRAK

Ujian ultrasonik telah digunakan secara meluas di dalam industri untuk penilaian kecacatan. Walaubagaimanapun, teknik ini mempunyai beberapa kekurangan seperti pengimbasan mekanikal dan pancaran spektra yang tidak boleh dikawal. Kekurangan ini boleh diselesaikan dengan menggunakan teknik "phased array" yang menggunakan gandaan susunan elemen dengan masa tertangguh yang membolehkan gelombang dikawal aataupun ditumpu. Kajian dilaksanakan untuk mengkaji kesan saiz elemen "PZT" dalam pengujaan "phased array" transducer. Beberapa design kriteria perlu diberi perhatian seperti jumlah elemen, jarak antara elemen, frekuensi dan saiz "aperture". Gelombang selari dengan mod berbeza iaitu symetri dan anti – symetri telah digunakan sebagai prinsip untuk menyebarkan gelombang di struktur yang besar menggunakan satu titik tetap. Simulasi kepingan aluminium tanpa kecacatan dengan masa tertangguh dimodelkan menggunakan perisian ABAQUS. Viusalisasi gelombang penyebaran terhadap kecacatan diperhati dan dibezaakn dengan model yang lain.

TABLE OF CONTENTS

CHAPTER	CONTENT	PAGES
	DECLARATION	ii
	DEDICATION	iii
	ACKNOWLEDGEMENT	iv
	ABSTRACT	v
	ABSTRAK	vi
	TABLE OF CONTENT	vii
	LIST OF TABLE	x
	LIST OF FIGURE	xi
	LIST OF SYMBOL	xvi
	LIST OF APPENDIX	xvii
CHAPTER I	INTRODUCTION	1
	1.0 Overview	1
	1.1 Background	1
	1.1.1 Ultrasonic Testing on Plate	6
	1.1.2 Ultrasonic Testing on Pipe	7
	1.2 Problem Statement in Ultrasonic Testing	
	Method	9
	1.2.1 Linear Beam Separation	9
	1.2.2 Mechanical Scanning	10
	1.2.3 Difficult Access On Testing Material	11
	1.3 Advantages in Using Ultrasonic Phased Array	11
	1.4 Objectives	12
	1.5 Scope of Study	12

CHAPTER II	LITERATURE REVIEW	13
	2.0 Overview	13
	2.1 Introduction of Phased Array Transducer	13
	2.1.1 Beam Focusing and Beam Steering of	
	Phased Array	16
	2.1.2 Effect on Number and Size of Transducer	17
	2.2 Guided Wave	18
	2.2.1 Modes of Lamb Wave	19
	2.2.2 Dispersion Curve of Group Velocities and	
	Phase Velocities	19
CHAPTER III	METHODOLOGY	22
	3.0 Overview	22
	3.1 Flowchart	23
	3.2 Dispersion Curve of Group Velocity for	
	Aluminium	24
	3.3 Algorithm of Time Delay	27
	3.3.1 Time Delay of Beam Focusing	27
	3.3.2 Time Delay of Beam Steering	29
	3.4 Finite Element Modelling On Defects	30
	3.5 Excitation of Guided Wave on FEM	35
CHAPTER IV	RESULT AND ANALYSIS	36
	4.0 Overview	36
	4.1 Effect of Size PZT Elements on the Excitation	
	Guided Wave Beam Focusing Phased Array of	
	A0 mode at 1600 mm	37
	4.1.1 The Excitation Guided Waves Phased Array	
	of Rectangular Shape of Elements	37
	4.1.2 The Excitation Guided Waves Phased Array	
	of Square Shape of Elements	41
	4.1.3 The Excitation Guided Waves Phased Array	

	of Distance Between Elements	45
	4.2 Effect of Size PZT Elements on the Excitation	
	Guided Wave Beam Steering Phased Array of	
	A0 mode at 1600 mm	49
	4.2.1 The Excitation Guided Waves Phased Array	
	of Rectangular Shape of Elements	49
	4.2.2 The Excitation Guided Waves Phased Array	
	of Square Shape of Elements	53
	4.2.3 The Excitation Guided Waves Phased Array	
	of Distance Between Elements	56
CHAPTER V	CONCLUSION AND RECOMMENDATION	61
	5.0 Conclusion	61
	5.1 Recommendation	62
	REFERENCES	
		63
	APPENDIX	66

ix

LIST OF TABLE

1.1	The dimension parameters of the pipe and other	
	experimental conditions for guided wave inspection	8
2.1	Comparisons of small pipe weld inspections time and	
	conditions for manual UT, RT and phased arrays	15
2.2	Properties of the aluminium	20
3.1	Proposed size of PZT elements used in simulation	34
3.2	Zinc material properties	34

NO.

TITLE

PAGES

LIST OF FIGURES

TITLE

PAGES

1.1	Ultrasonic waves from transducer (a) without flaw and	
	(b) with flaw	2
1.2.	Longitudinal wave	
	(Source: Diligent, (2003))	3
1.3	Transversal wave	
	(Source: Diligent, (2003))	3
1.4	Guided wave inspections for corrosion defect on plate	4
1.5	Data presentation in ultrasonic testing (a) A-scan (b) B-	
	scan and (c) C-scan	5
1.6	Ultrasonic testing on plate using (a) contact transducer	
	(b) immersion transducer	7
1.7	Schematic diagram of guided ultrasonic wave	
	inspections on pipe	8
1.8	Beam separation (a) normal beam (b) phased array	
	beam	10
1.9	Mechanical scanning of conventional ultrasonic	
	transducer	10
2.1	Linear array geometry and typical field of view	
	(Source: Lawrence, (1998))	14
2.2	Beam focusing with time delays	16

(Source: NDT, (2007))

2.3	Beam steering with time delays	
	(Source: NDT, (2007))	17
2.4	Grating lobe, main lobe and side lobe	18
2.5	Mode of guide propagation in (a) S-mode and (b) A-	
	mode	19
2.6	Group velocity dispersion curve	20
2.7	Phase velocity dispersion curve	21
3.1	Flowchart of simulation	23
3.2	Group velocity dispersion curve	25
3.3	Phase velocity dispersion curve	25
3.4	Applied force using Tone Burst signal frequency	
	100kHz (4 cycles).	26
3.5	Centre of frequency at 100 kHz	26
3.6	Direction of the beam focusing phased array transducer	28
3.7	S0 mode array signal of beam focusing at 600 mm	28
3.8	Direction of the beam steering phased array transducer	29
3.9	Array signal of beam steering at angle -30 degrees	30
3.10	Plate with blind defect for (a) beam focusing and (b)	
	beam steering	31
3.11	Mesh control used in modelling	32
3.12	Assembly of PZT element and aluminium plate in	
	ABAQUS	33
3.13	Schematic diagram of element used in simulation	33
3.14	Direction force applied of S0 mode	35
3.15	Direction force applied of A0 mode	35
4.1	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 6mm	38
4.2	Time waveform at receiver point with element height	
	of 6 mm	38

4.3	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 12 mm	39
4.4	Time waveform at receiver point with element height of	
	12 mm	39
4.5	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 24 mm	40
4.6	Time waveform at receiver point with element height of	
	24 mm	40
4.7	Time waveform for different rectangular size elements	
	at receiver point in beam focusing	41
4.8	Wave interaction behaviour in z-direction for A0 mode	
	with square element of 3 mm	42
4.9	Time waveform at receiver point with square elements	
	size of 3 mm	42
4.10	Wave interaction behaviour in z-direction for A0 mode	
	with square element of 6 mm	43
4.11	Time waveform at receiver point with square elements	
	size of 6 mm	43
4.12	Time waveform for different square size of elements at	
	receiver point in beam focusing	44
4.13	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at 1/4 λ	45
4.14	Time waveform at receiver point with distance between	
	elements at $1/4 \lambda$	46
4.15	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at $3/4 \lambda$	46
4.16	Time waveform at receiver point with distance between	
	elements at $3/4 \lambda$	47
4.17	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at $5/4 \lambda$	47
4.18	Time waveform at receiver point with distance between	
	elements at $5/4 \lambda$	48
4.19	Time waveform for different distance between elements	

	at receiver point in beam focusing	48
4.20	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 6mm	49
4.21	Time waveform at receiver point with element height of	
	6 mm	50
4.22	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 12 mm	50
4.23	Time waveform at receiver point with element height of	
	12 mm	51
4.24	Wave interaction behaviour in z-direction for A0 mode	
	with element height at 24 mm	51
4.25	Time waveform at receiver point with element height of	
	24 mm	52
4.26	Time waveform for different rectangular size elements	
	at receiver point in beam steering	53
4.27	Wave interaction behaviour in z-direction for A0 mode	
	with square element of 3 mm	54
4.28	Time waveform at receiver point with square elements	
	size of 3 mm	54
4.29	Wave interaction behaviour in z-direction for A0 mode	
	with square element of 6 mm	55
4.30	Time waveform at receiver point with square elements	
	size of 6 mm	55
4.31	Time waveform for square size of elements at receiver	
	point in beam steering	56
4.32	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at 1/4 λ	57
4.33	Time waveform at receiver point with distance between	
	elements at $1/4 \lambda$	57
4.34	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at $3/4 \lambda$	58
4.35	Time waveform at receiver point with distance between	
	elements at $3/4 \lambda$	58

4.36	Wave interaction behaviour in z-direction for A0 mode	
	with distance of element at $5/4 \lambda$	59
4.37	Time waveform at receiver point with distance between	
	elements at $5/4 \lambda$	59
4.38	Time waveform for different distance between elements	
	at receiver point in beam steering	60

XV

LIST OF SYMBOL

d	=	Element width, m
С	=	Material wave speed, m/s
ω	=	Angular velocity, rad/s
k	=	Wave number
C_l	=	Bulk longitudinal velocities, m/s
C_T	=	Shear velocities, m/s

xvi

LIST OF APPENDIX

NO.	TITLE	PAGES	
А	MATLAB Coding for Beam Focusing	66	
В	MATLAB Coding for Beam Steering	69	

CHAPTER I

INTRODUCTION

1.0 OVERVIEW

This chapter covers the introduction of this project that involved the project background, problem statement, objectives of the project and scope of study.

1.1 BACKGROUND

Ultrasonic testing is a versatile technique in Non-Destructive Testing (NDT) which is been used to most materials, metallic or non-metallic including various industries such as oil and gas, aerospace, forest industry and building construction. By using this ultrasonic testing, surface and internal discontinuities such as slags, inclusions, laps, seams, voids, cracks and lack of bond can be detected accurately from one side. Ultrasonic testing utilizes a high frequency acoustic wave which is varied according to the application ranging from 1 to 10 Mega Hertz (MHz) generated by piezoelectric transducer. (Baldev Raj, T. Jayakumar, and M. Thavasimuthu, 2008)

PZT elements is defined as lead zirconate titanate (Pb[Zr(x)Ti(1-x)]O3) that have been widely used in piezoelectric transducer. According to (Ting hai Cheng, Xiang-dong Guo and Gang Bao, 2011), PZT elements is used to produce bending cylindrical transducer that transforms input electrical energy to output mechanical energy in ultrasonic transducer, their excitation position and excitation modes. Length and thickness of PZT elements need to consider in order enhancing the output characterization type transducer.

Pulse-echo inspection technique is most widely used for ultrasonic inspection of components. In pulse-echo inspection technique, ultrasonic sound energy is transmitted between the face of the transducer and the surface of the test component. When ultrasonic energy penetrates into a material and strike a discontinuity or flaw, part of energy will be reflected back to the probe and the remaining part propagates in the material in forward direction as shown in **Figure 1.1 (a)** and **(b)**. To facilitate the transmission of ultrasonic energy between the transducer and the test component, a couplant that made from water based material is used between the transducer and the surface of the plate. (Baldev Raj, T. Jayakumar, and M. Thavasimuthu, 2008).



Figure 1.1: Ultrasonic waves from transducer (a) without flaw and (b) with flaw.

Ultrasonic sound wave that transmitted from a transducer can travel in longitudinal wave and transversal or shear wave. In longitudinal waves, the direction of oscillation is parallel to the direction of propagation meanwhile transversal wave is perpendicular the direction of oscillation as shown in **Figure 1.2** and **Figure 1.3**. (Josef Krautkramer & Herbert Krautkramer, 1990)

<i>λ</i>								
Direction of acongantion								

Figure 1.2: Longitudinal wave (Source: Diligent, (2003))



Figure1.3: Transversal wave

(Source: Diligent, (2003))

Guided wave technique is the latest technique for non-destructive testing and material evaluation for any defects in plate and pipe. This technique has advantages since the guided waves can propagate in perpendicular direction with lower frequency ranging 10 to100 kHz which covers for a long range inspection. The guided waves for damage monitoring in plates used pulse-echo method to evaluate the corrosion defect. This experiment used pulser or receiver system which generates an ultrasonic spikes pulse driven through the corrosion plate in the form of longitudinal waves as shown in **Figure 1.4**. Ultrasonic signals were taken in pulse

echo mode for the corroded plate at each level of corrosion and the readings were compared with the healthy readings. (Ramandeep Singh, Shruti Sharma & Sandeep Sharma, 2014)



Figure 1.4: Guided wave inspections for corrosion defect on plate

In ultrasonic testing, the results can be displayed in several conditions which called A-scan, B-scan and C-scan presentation.

Figure 1.5 (a) shown A-scan that display amount of received ultrasonic energy as a time waveform. The relative amount of received energy is plotted in along the vertical axis against the time elapsed in horizontal axis. Relative discontinuity size can be estimated in A-scan by comparing the signal amplitude obtained with unknown reflector to known reflector.

Figure 1.5 (b) shown B-scan that display the cross sectional view or depth of the test material. In this B-scan presentation, the depth of reflector and its linear dimension in the scan direction can be visualized

Figure 1.5 (c) shown C-scan presentation that visualise the image in two dimensions that from reflected ultrasound signal that provides a top view of the location and size of the test material using an automated data acquisition system.



Figure 1.5: Data presentation in ultrasonic testing (a) A-scan (b) B-scan (c) C-scan

C Universiti Teknikal Malaysia Melaka

Ultrasonic testing had been used since 1940's applied by Firestone and Simon that developed pulsed ultrasonic testing using a pulse-echo technique. This testing is continually improved after World War II when a group of researchers from Japan develop medical diagnostic using ultrasound (History of Ultrasonic, 2014). At the same time, Nobel Laureate Luis Alvarez used phase array transmission in a rapidly-steer in "ground controlled approach", a system to help the landing aeroplanes in Britain (Swapana Koganti & Kaapaarapu Satish Babu, 2012). A phased array consist several sets of elements that pulsed to produce sound beam by means controlled interference pattern in a desired direction. The ultrasonic phased array is widely used in medical applications that used multi-elements piezoelectric device which individually excited by electric pulse at programmed time delay (Joon Hyun Lee & Sang Woo Choi, 2000).

1.1.1 ULTRASONIC TESTING ON PLATE

Manufacturing stages of plate type nuclear fuel elements produced structural discontinuity such as cracks and bonding due to mechanical and thermal processing conditions. This discontinuity reduces the performance of the nuclear fuel during its operational life. Mucio Jose and teammates has conducted the non-destructive test using ultrasonic testing to detect bonding failures at core interface during hot rolling process. They has been used two different types of ultrasonic transducer which is contact transducer as shown in **Figure 1.6(a)** range in 10 MHz and 15 MHz and immersion transducer as shown in **Figure 1.6(b)** range from 4 MHz and 10 MHz.

The response and results by each transducer based from artificial discontinuities on the plate such as flat bottom holes with different diameter and slits with different length and width of the plate is observed. They conclude that contact transducer with high frequency and low focus transducer is more sensitive and obtain good visualization compared with immersion transducer (Mucio jose Drumond de Brito, Wilmar Barbosa Ferraz, Donizete Anderson de Alencar and Silverio Ferreira, 2009).